

Loosely Time-Triggered Architectures: Improvements and Comparisons

Guillaume Baudart
Albert Benveniste
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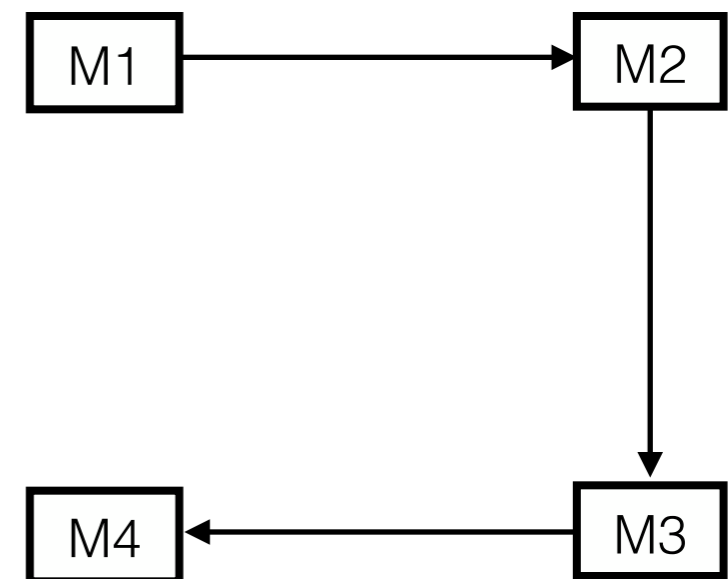
Synchronous Applications...

Composition of Communicating Mealy Machines

- Each machine is characterized by
 - an initial state S_{init}
 - a transition function

$$F : \mathcal{S} \times \mathcal{V}^I \rightarrow \mathcal{S} \times \mathcal{V}^O$$

- Machines communicate through unit delays.



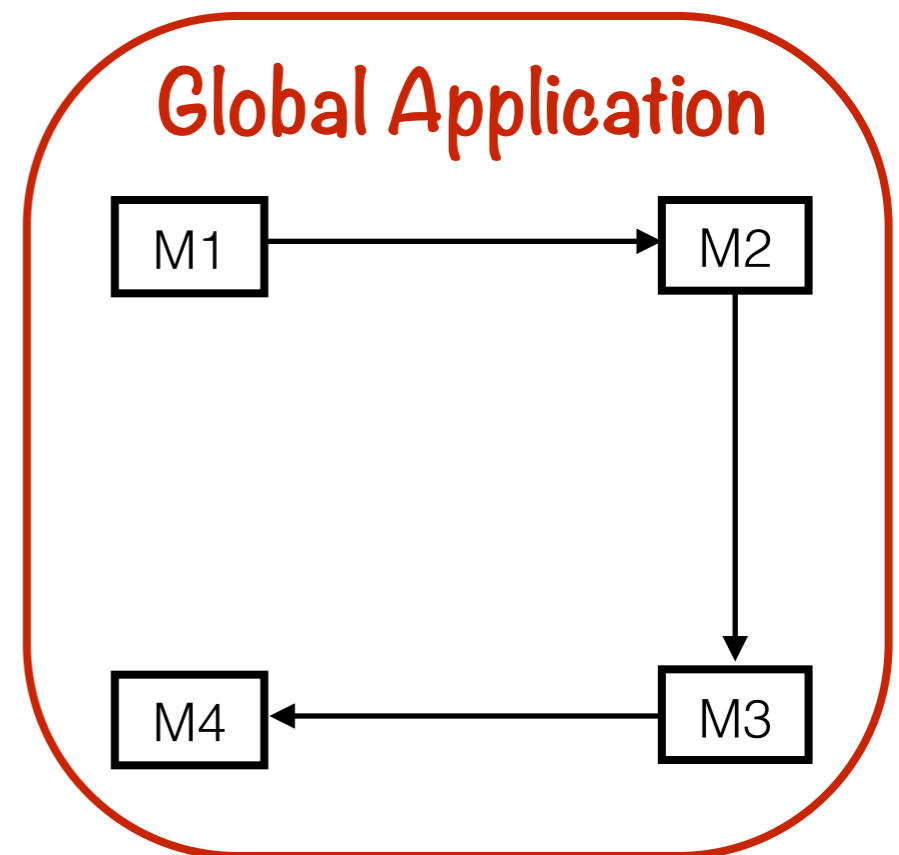
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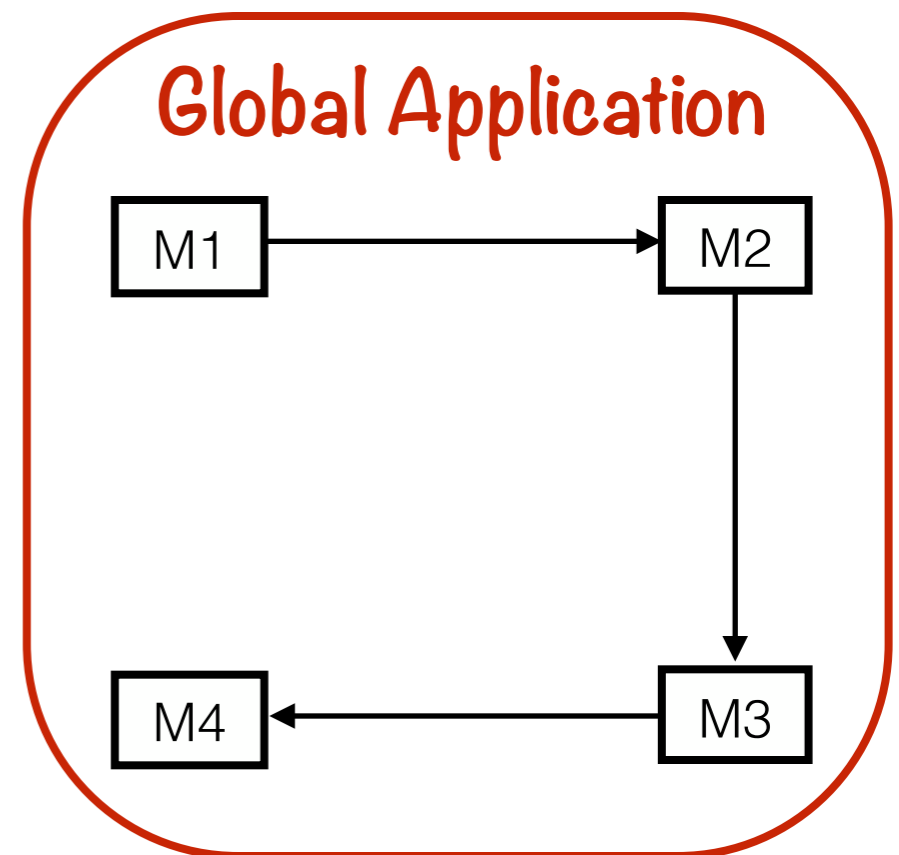
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Semantics: Sequence of values on each variable

...on Quasi-Periodic Architecture

- A set of “quasi-periodic” processes with local clocks and nominal period T^n (jitter ε)

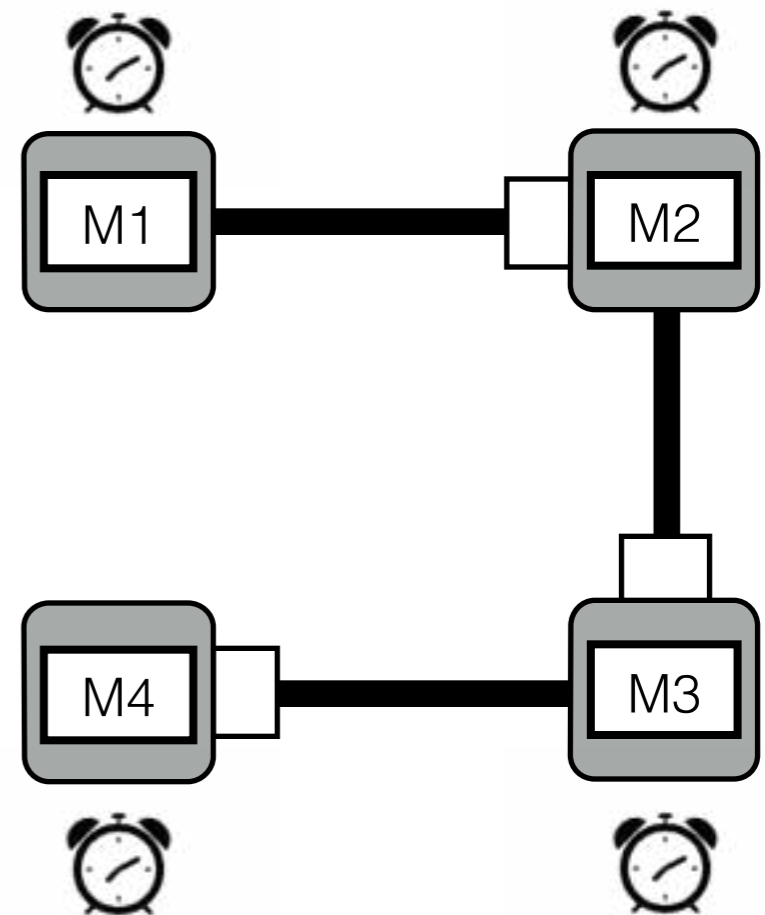
$$0 < T_{\min} \leq T^n \leq T_{\max} \quad \text{or}$$

$$T^n - \varepsilon \leq \kappa_i - \kappa_{i-1} \leq T^n + \varepsilon$$

$(\kappa_i)_{i \in \mathbb{N}}$ clock activations

- Buffered communication without message inversion or loss
- Bounded communication delay

$$\tau_{\min} \leq \tau \leq \tau_{\max}$$



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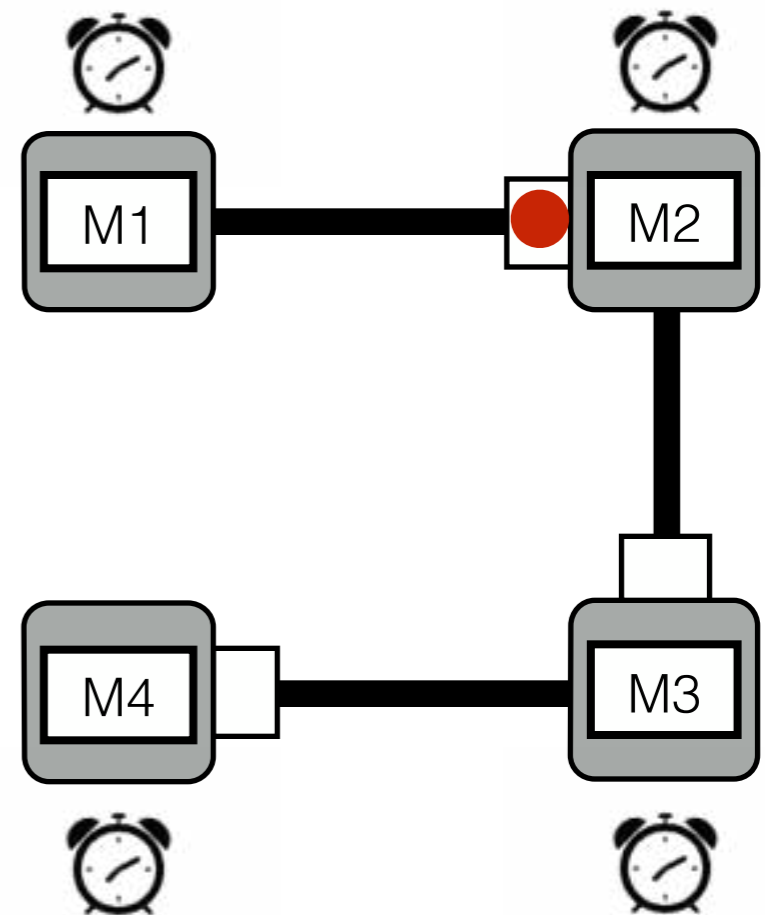
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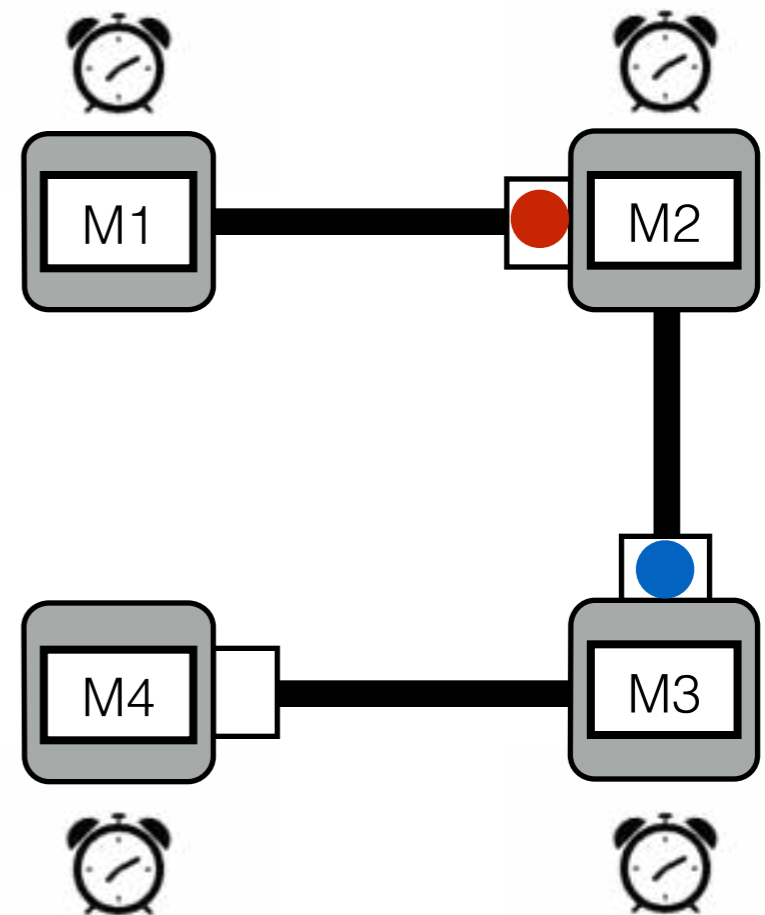
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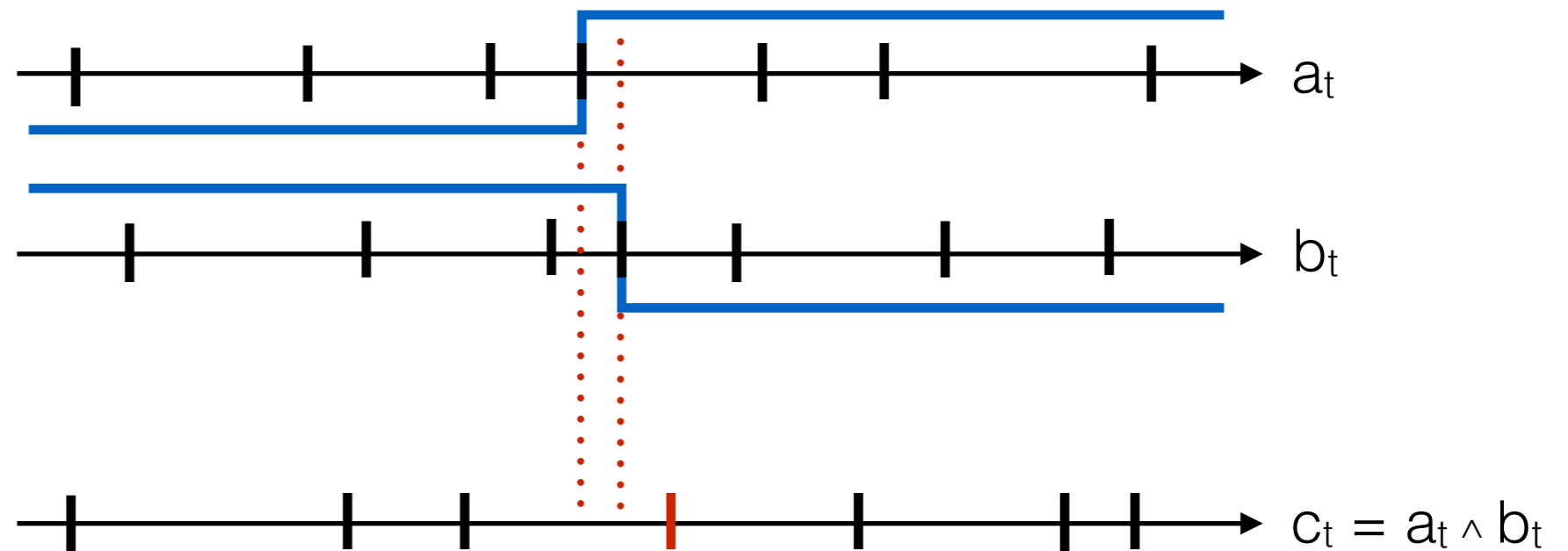
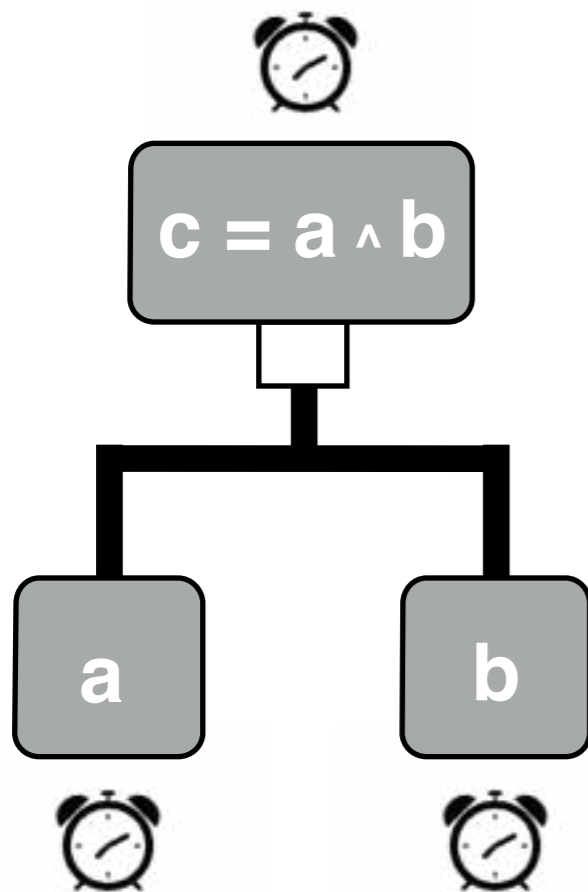
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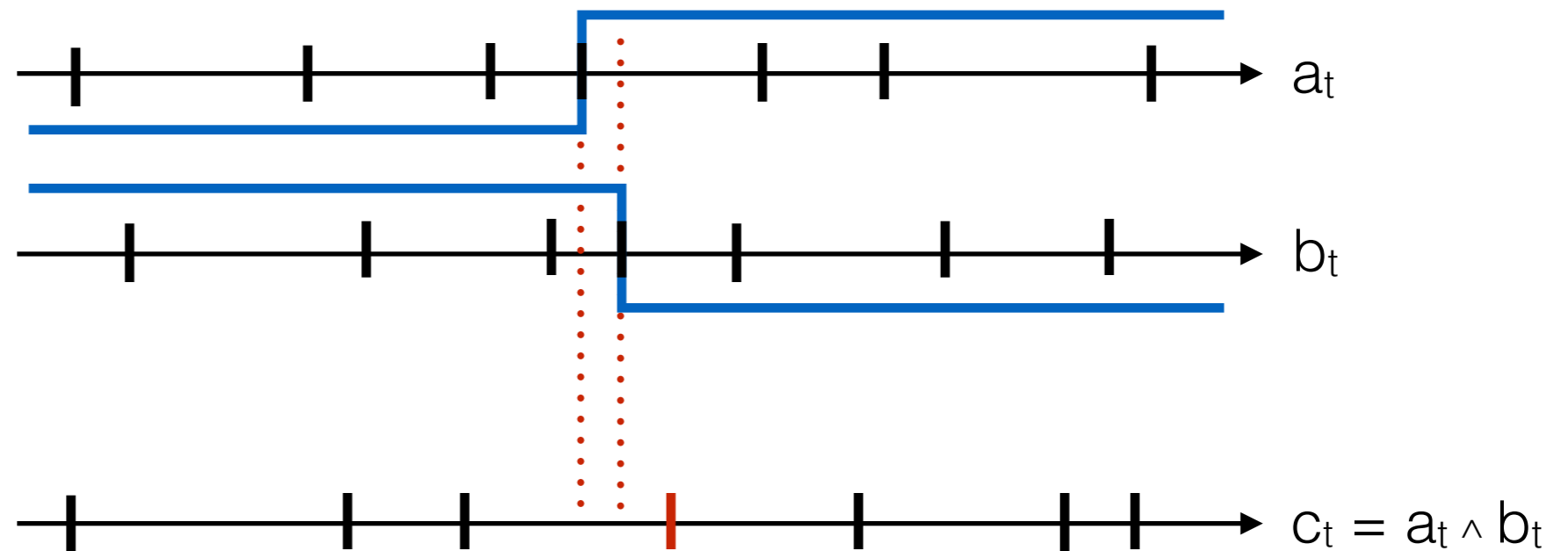
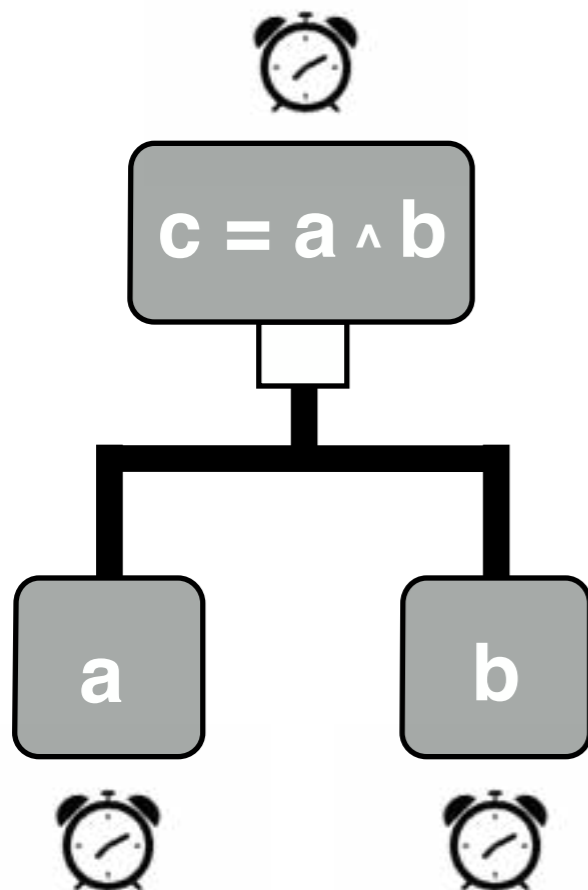
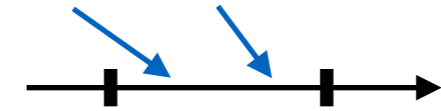
Sampling Artifacts

- **Overwriting:** Loss of values
- **Oversampling:** Duplication of values
- **Combination of signals**



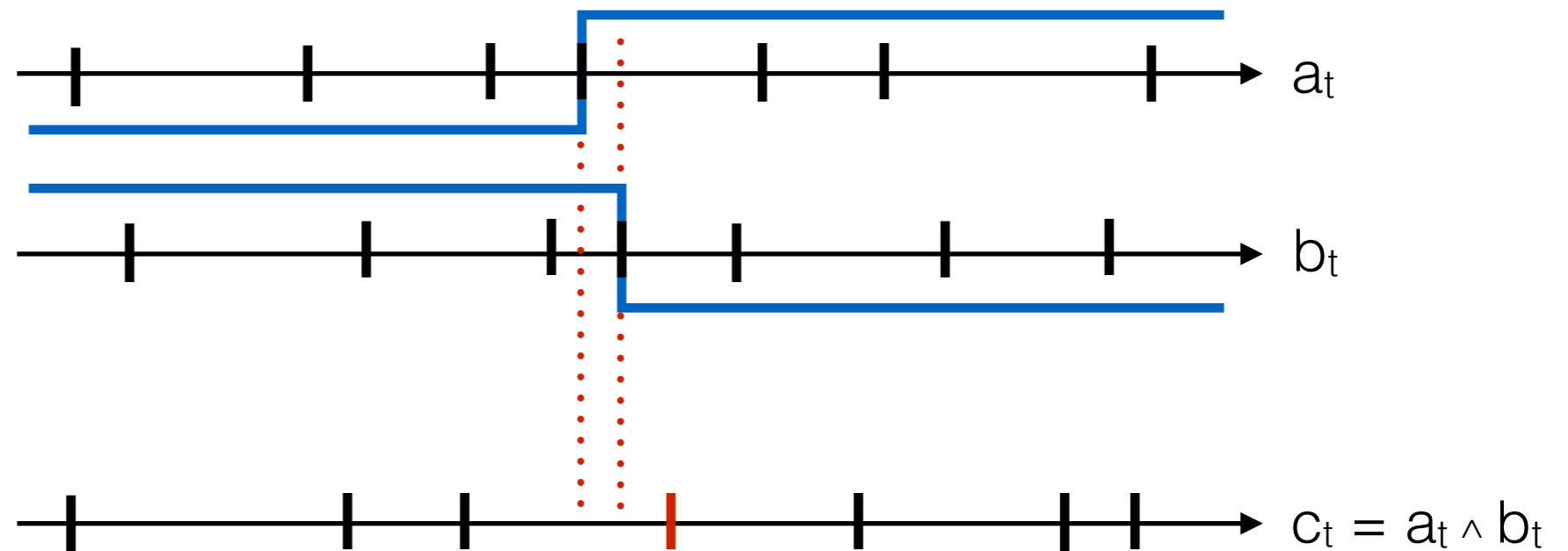
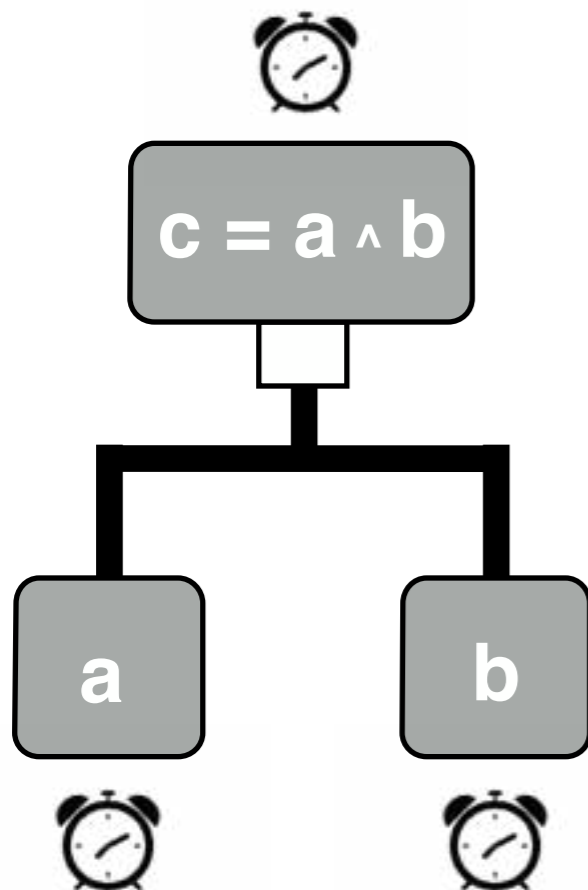
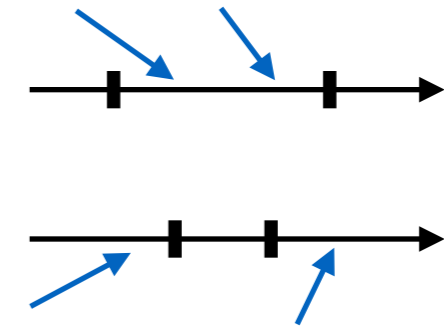
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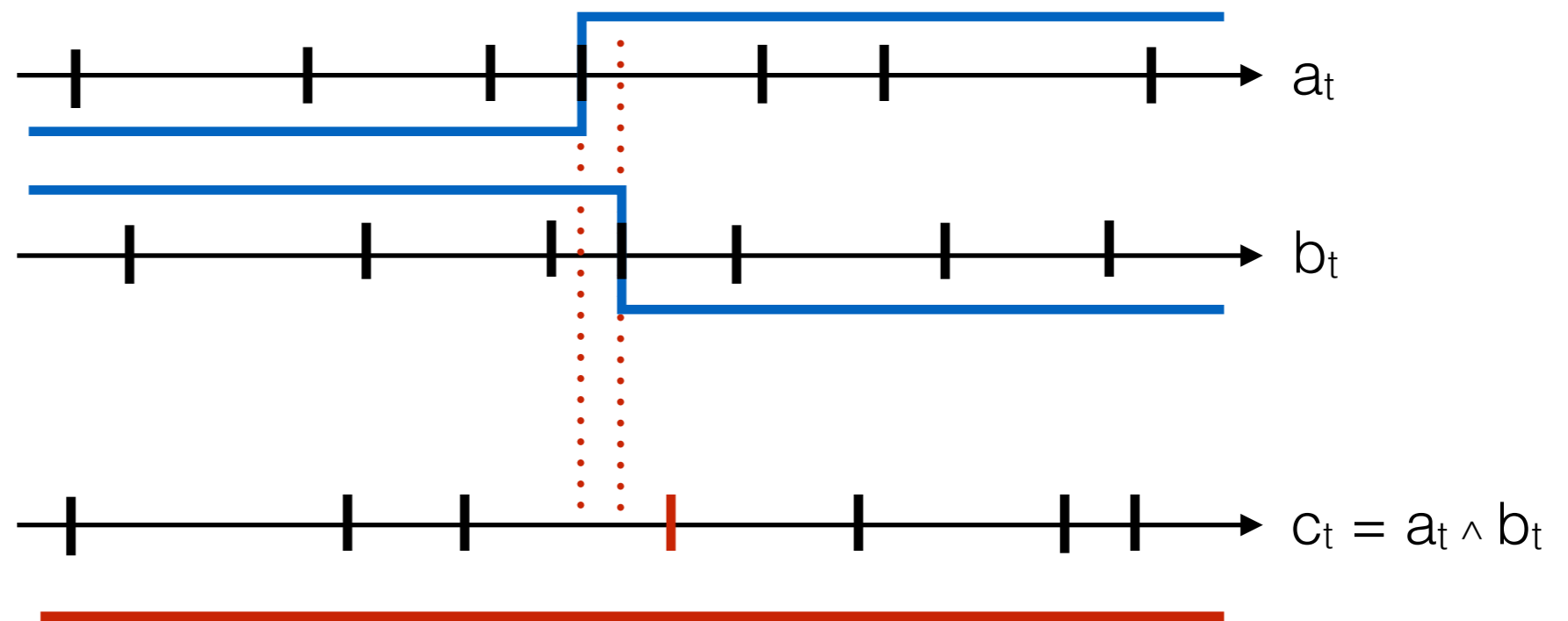
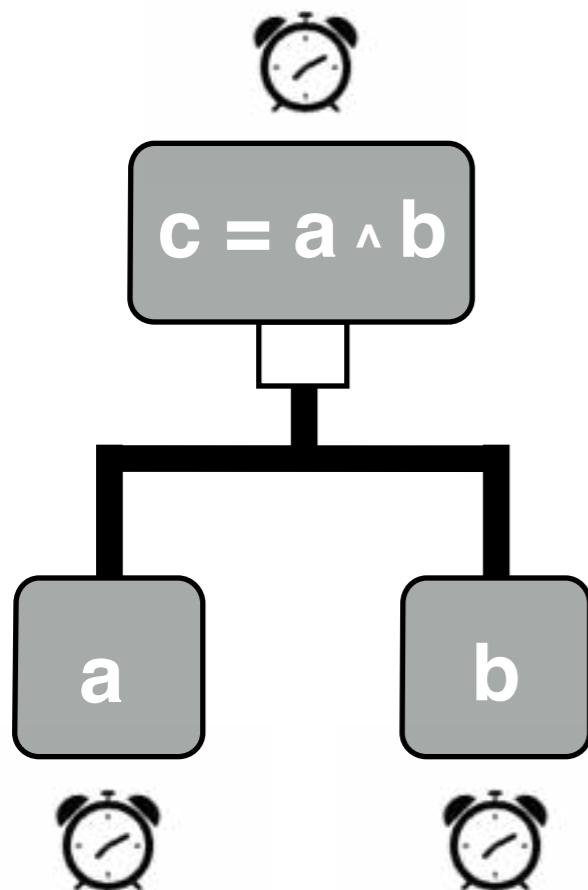
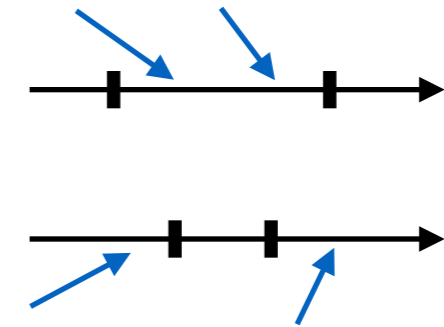
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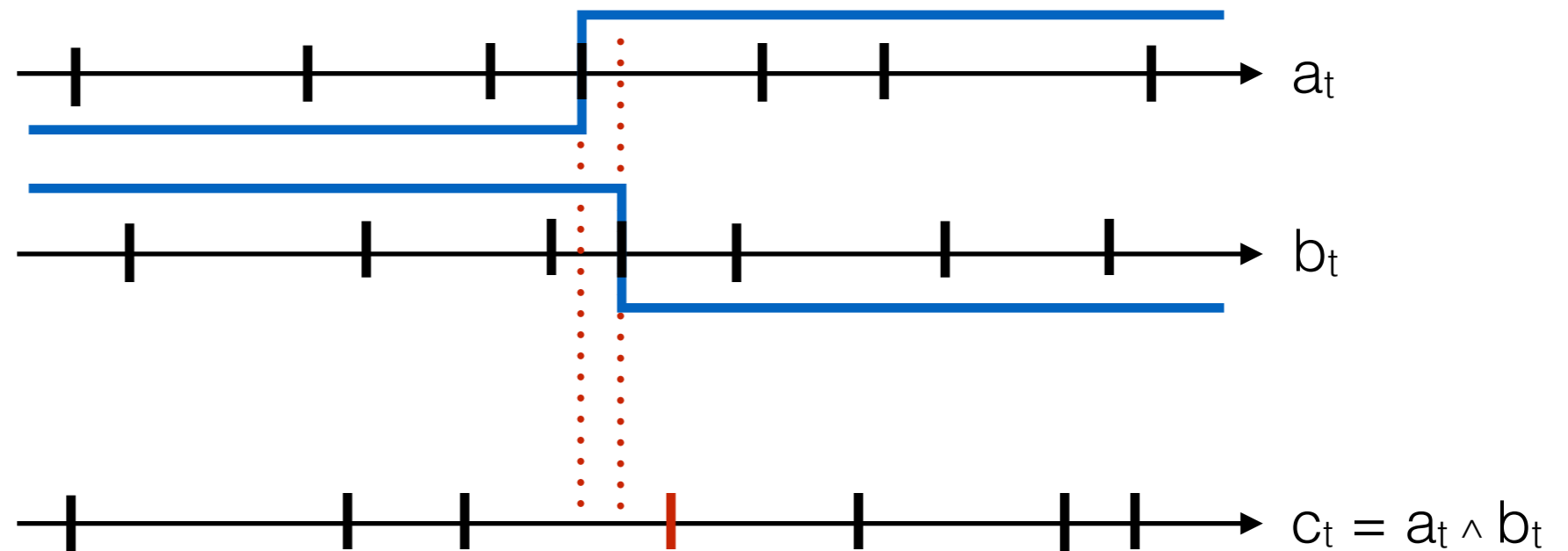
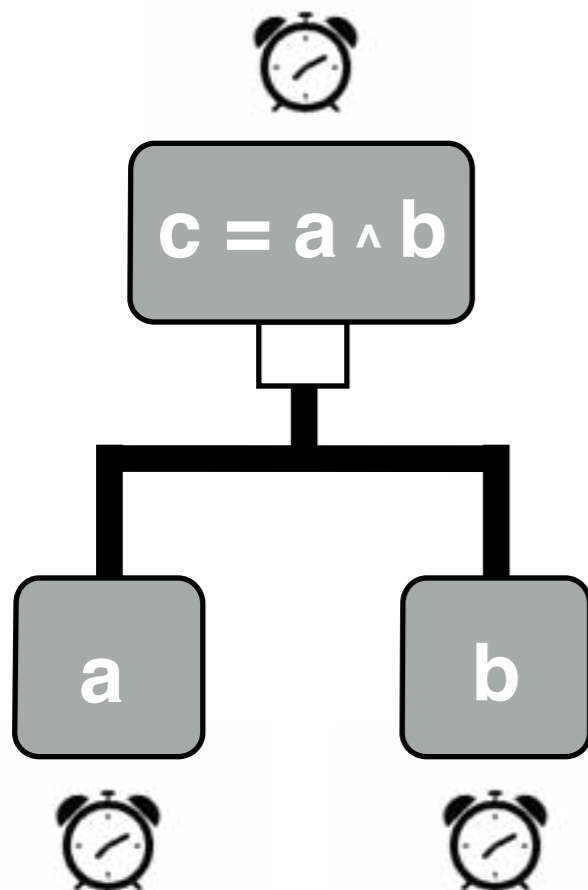
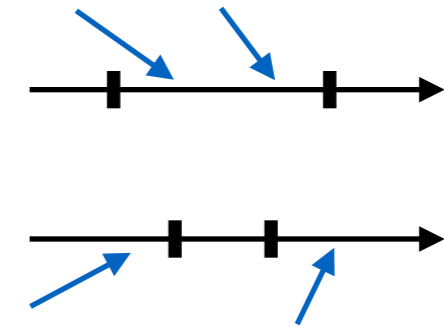
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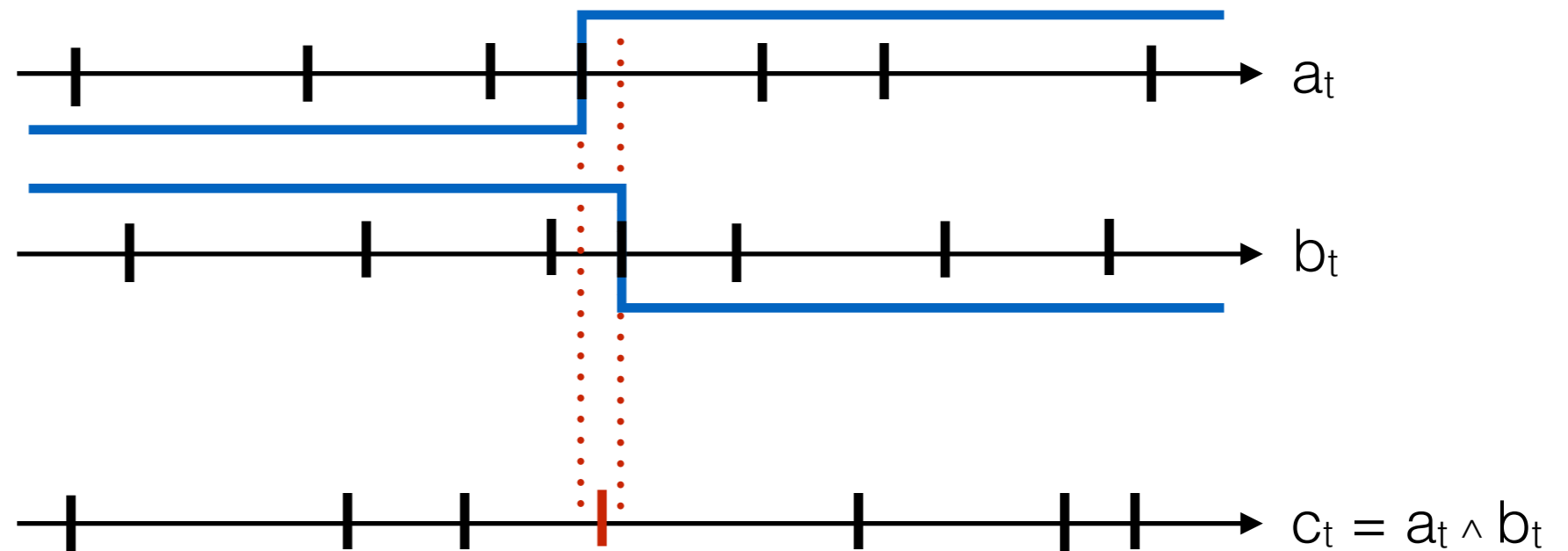
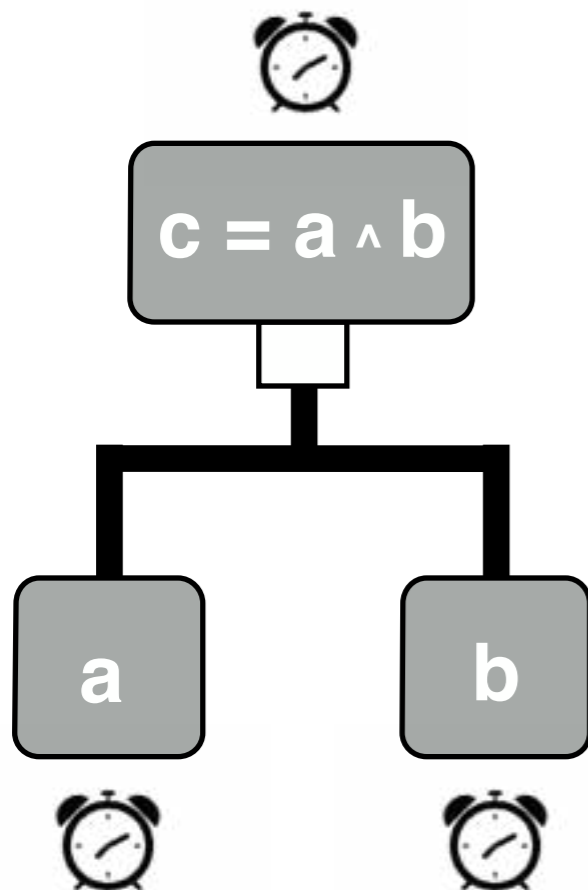
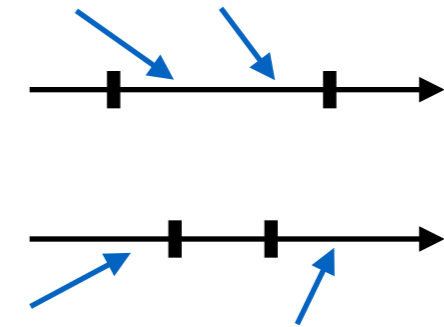
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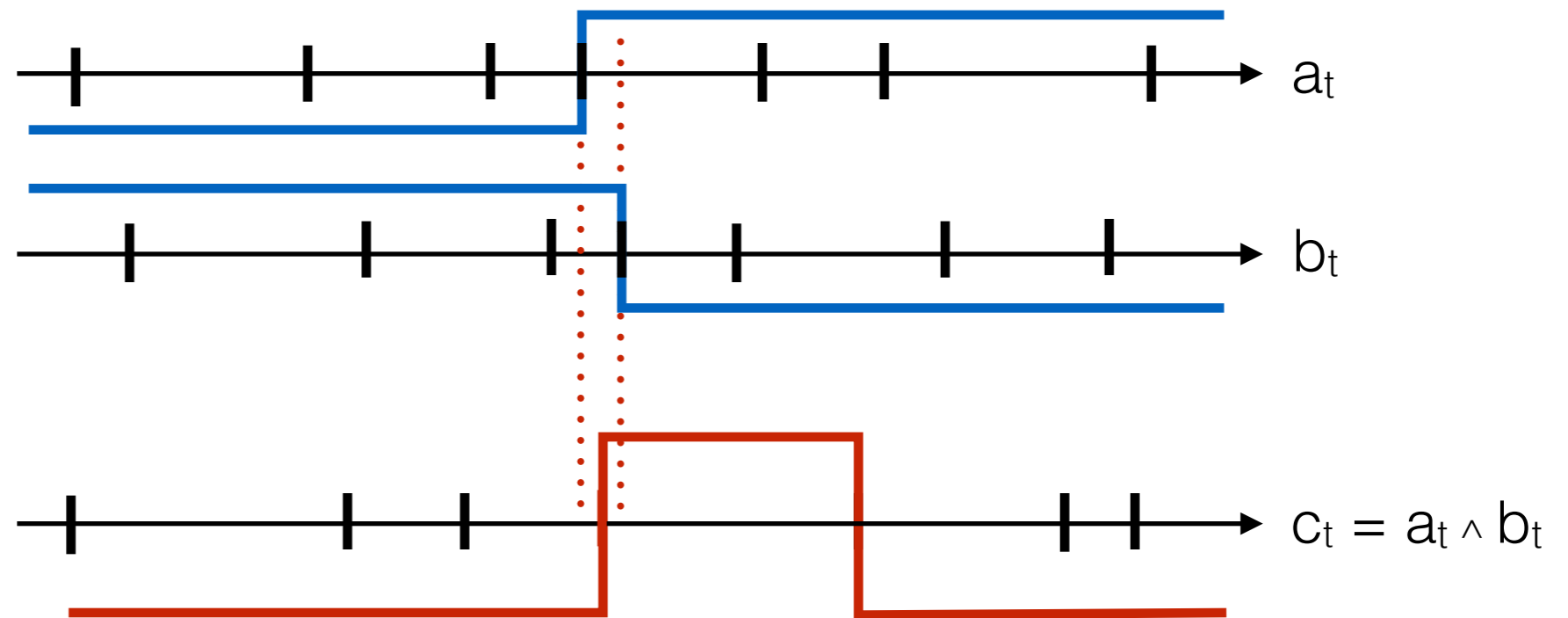
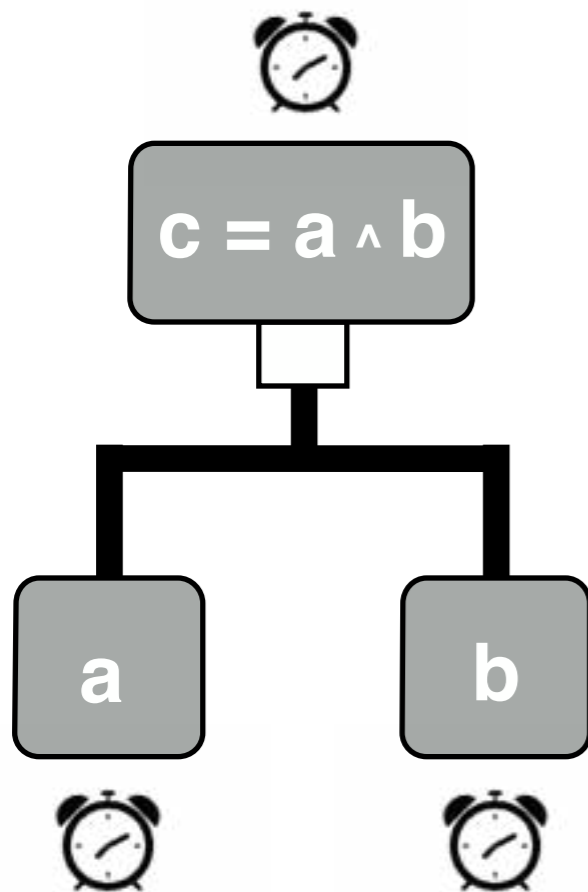
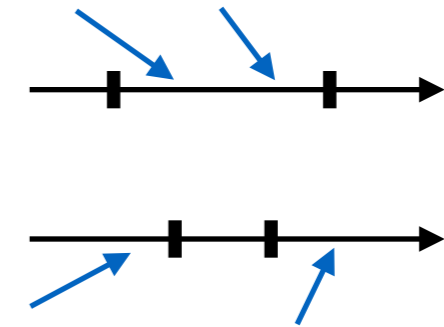
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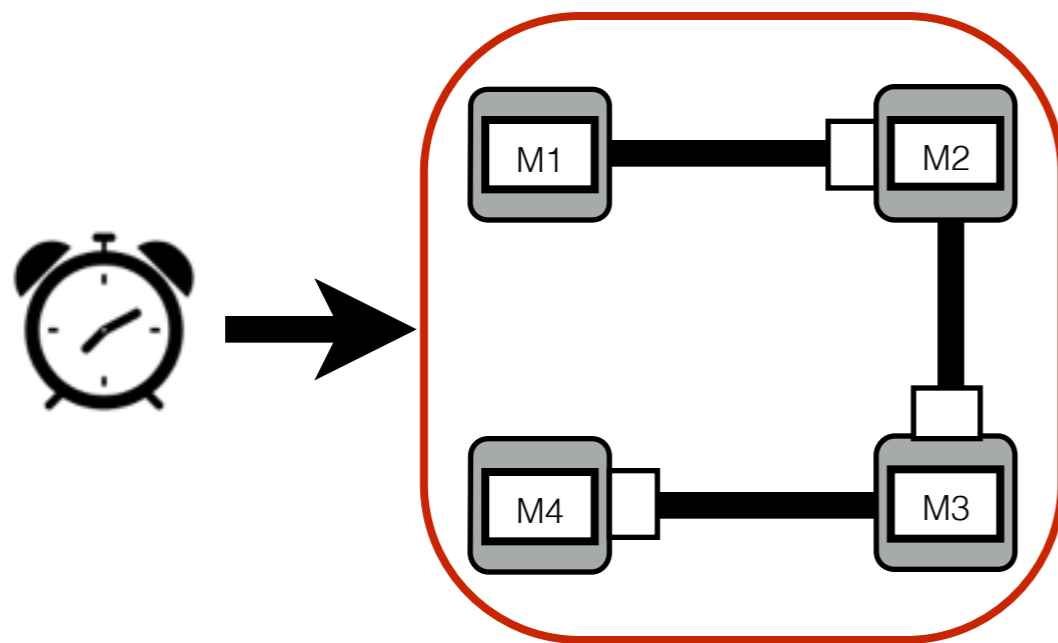
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Clock synchronization

e.g. TTA [Kopetz, Bauer 2003]



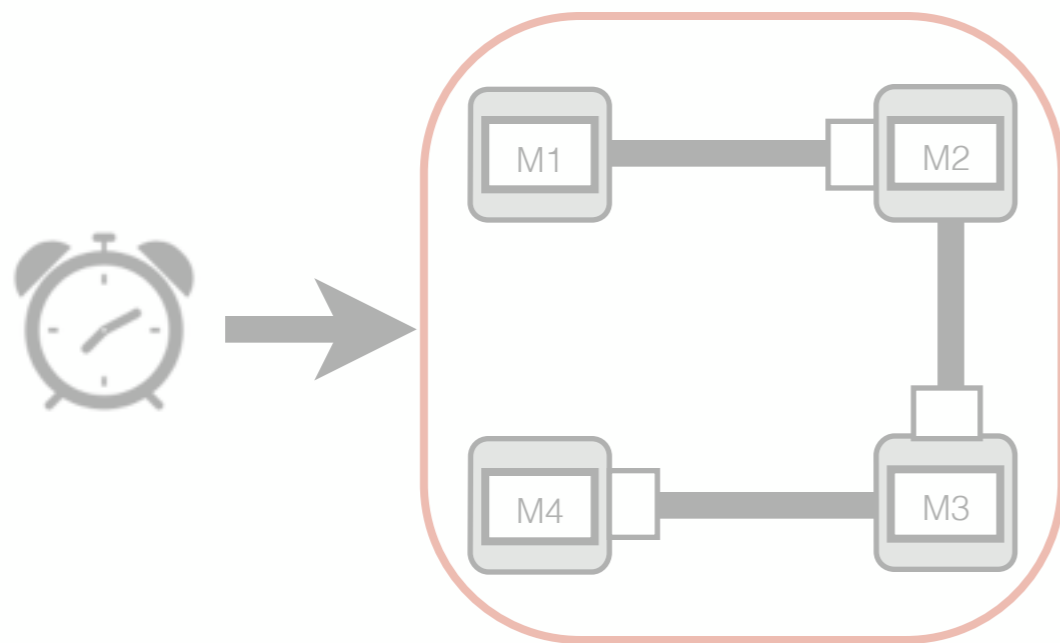
Now efficient and cheap.

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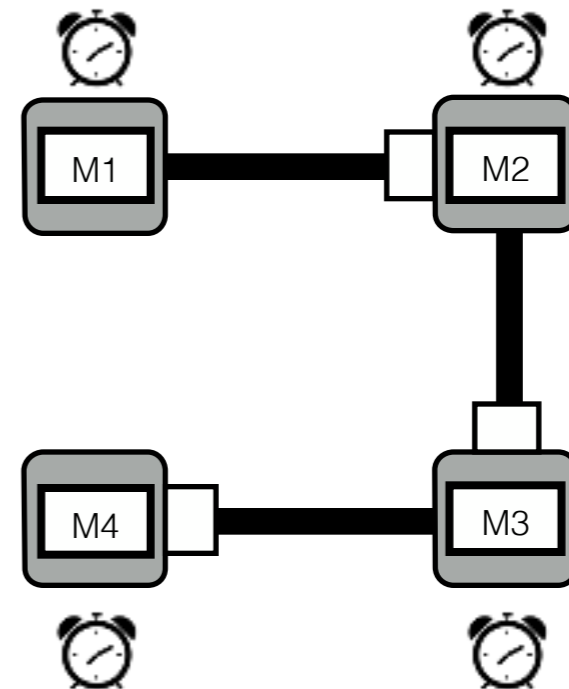
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Unsynchronized nodes + Middleware = LTTA

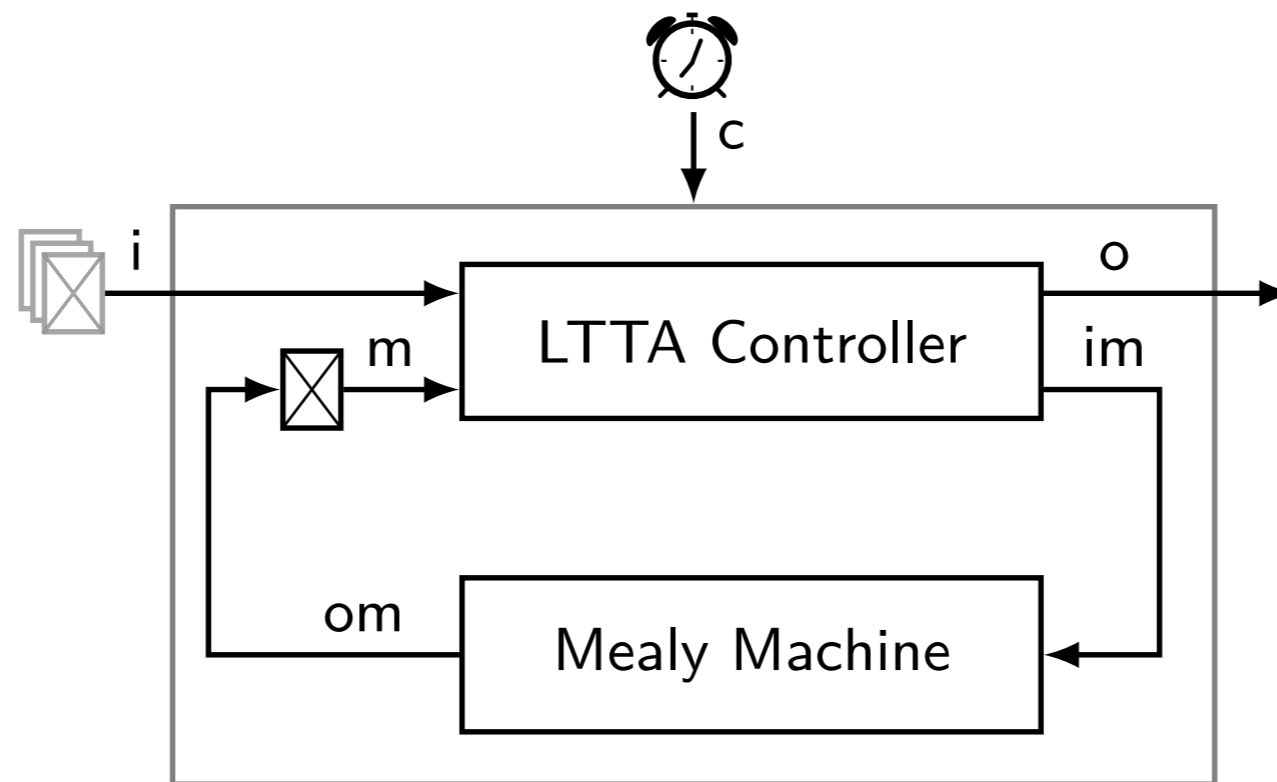


Are they a good idea?

A Synchronous Framework

Everything can be expressed as a **Zélus** program

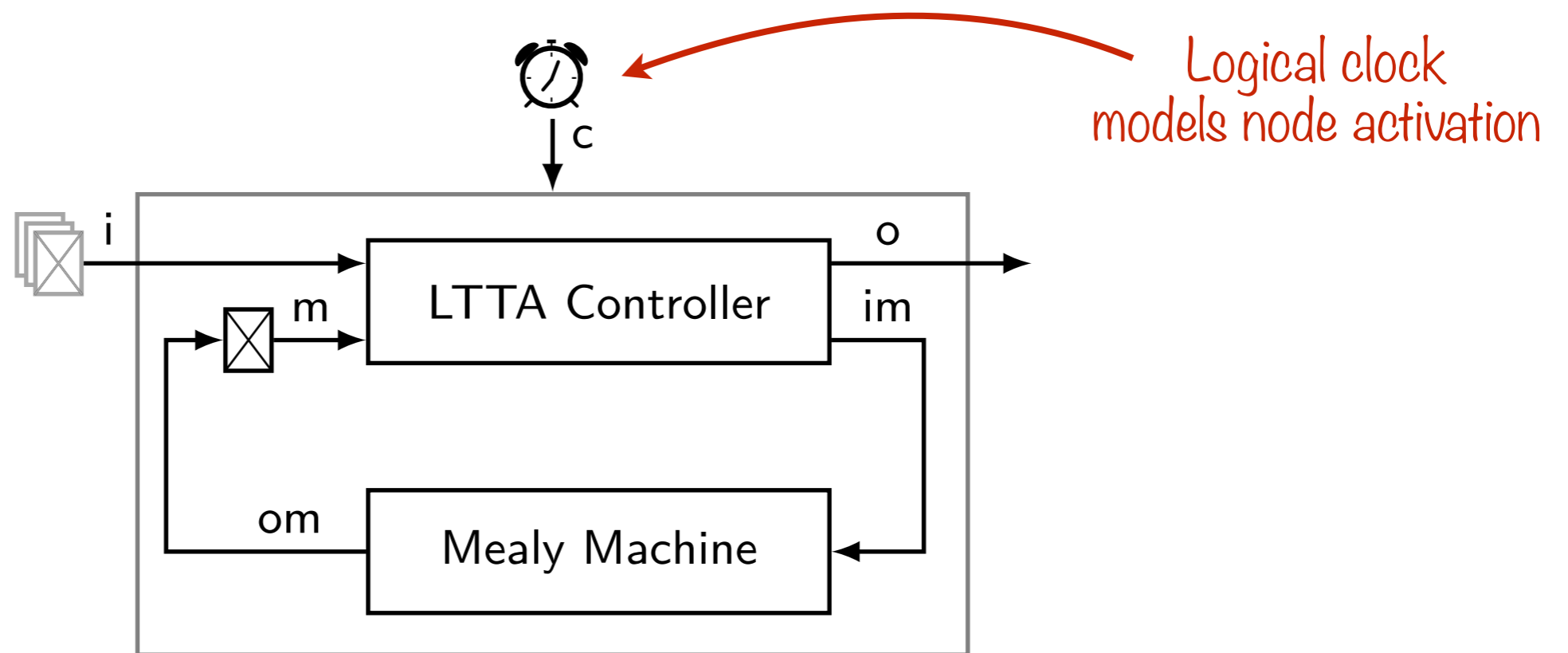
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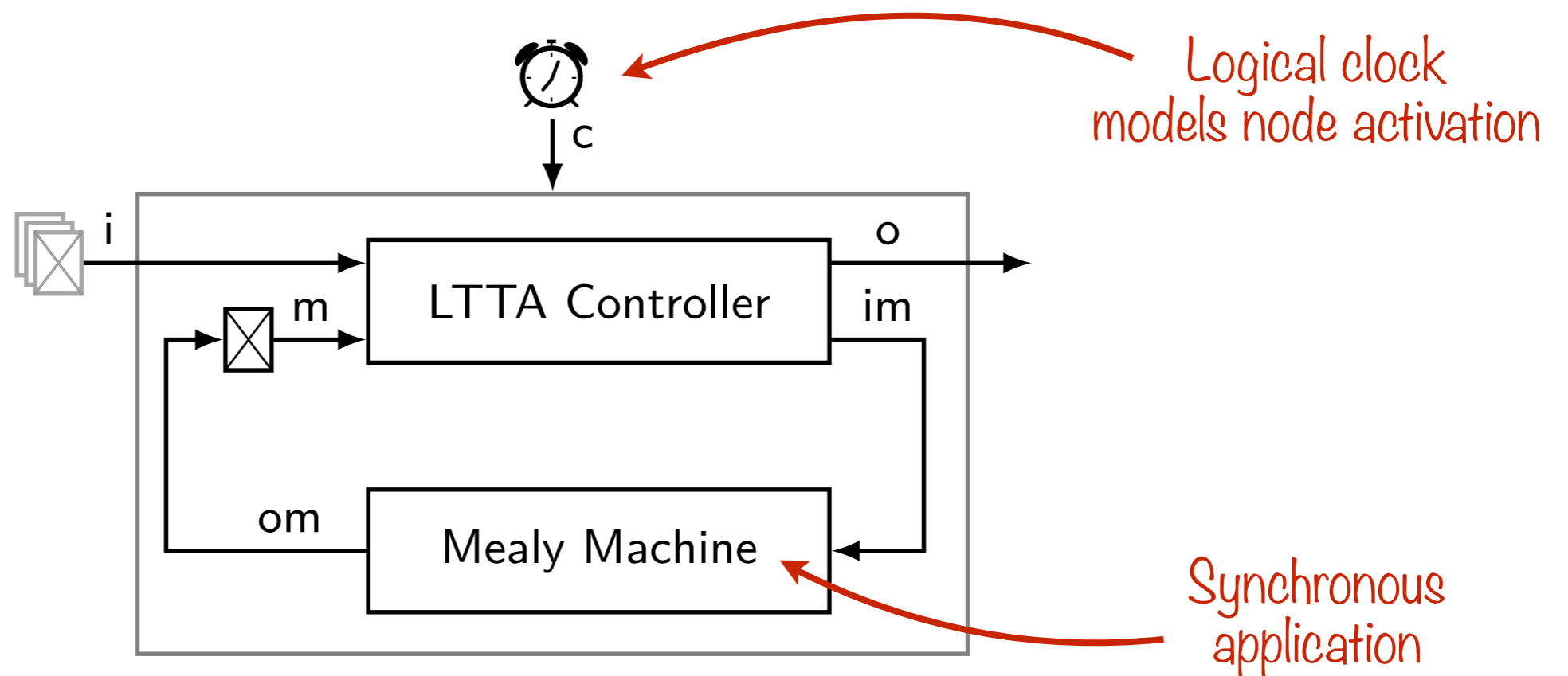
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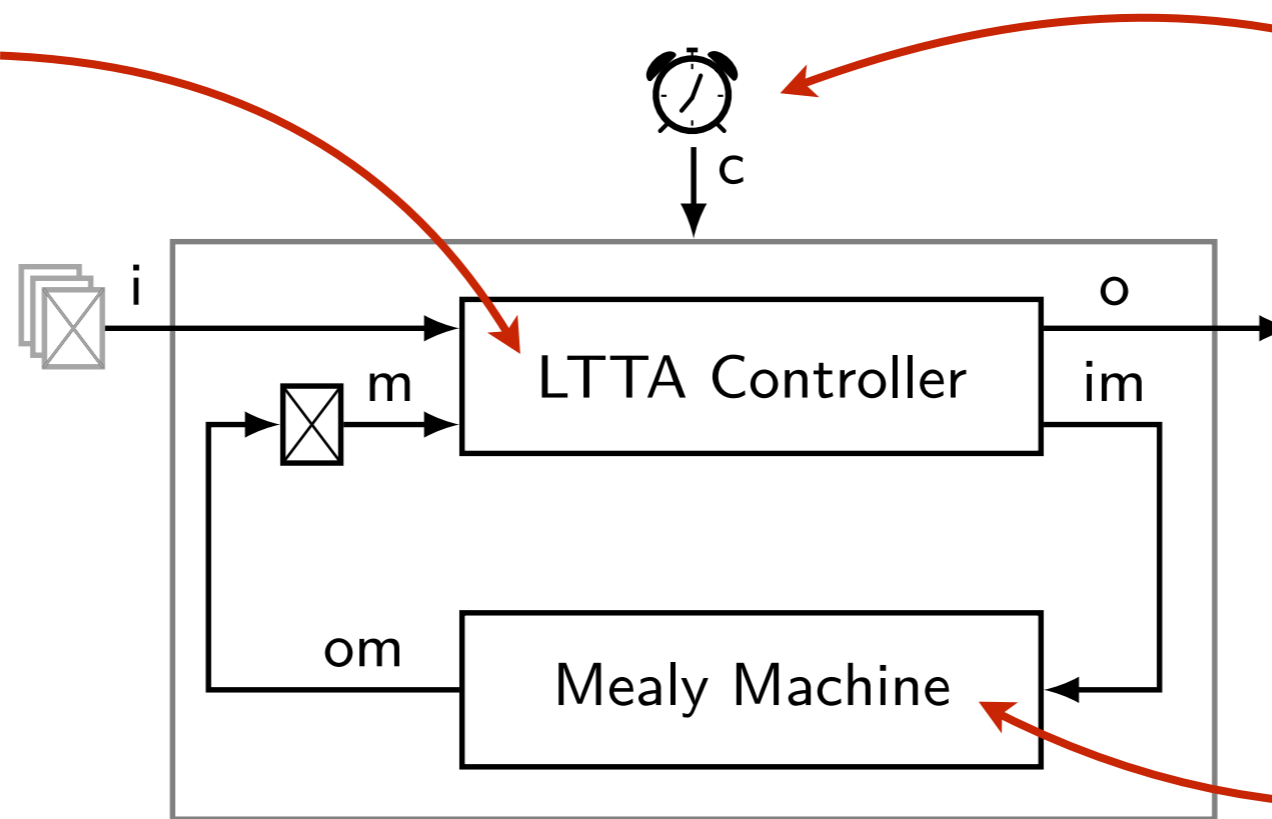


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Controls the execution of the application



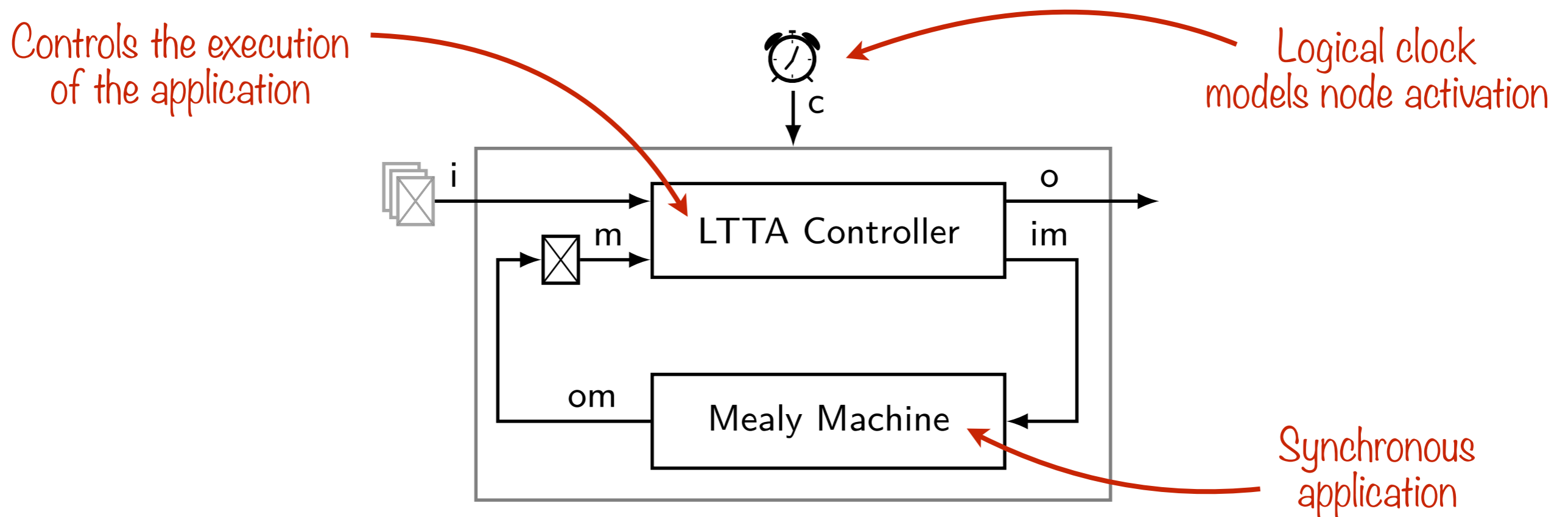
Logical clock models node activation

Synchronous application

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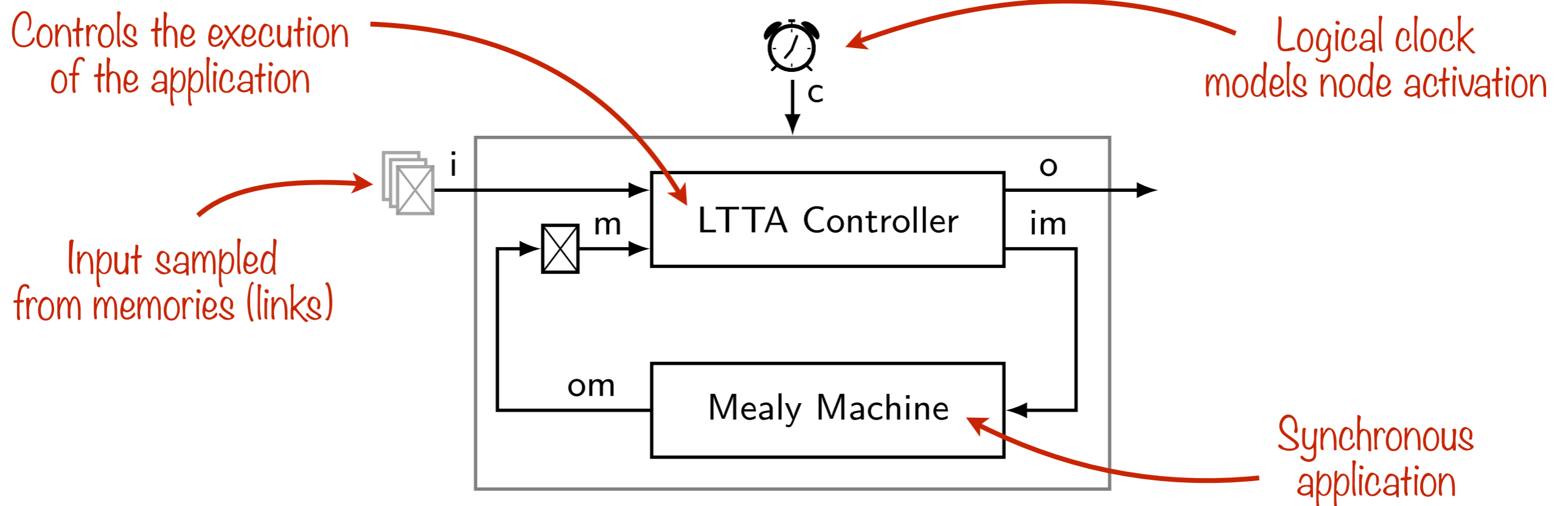


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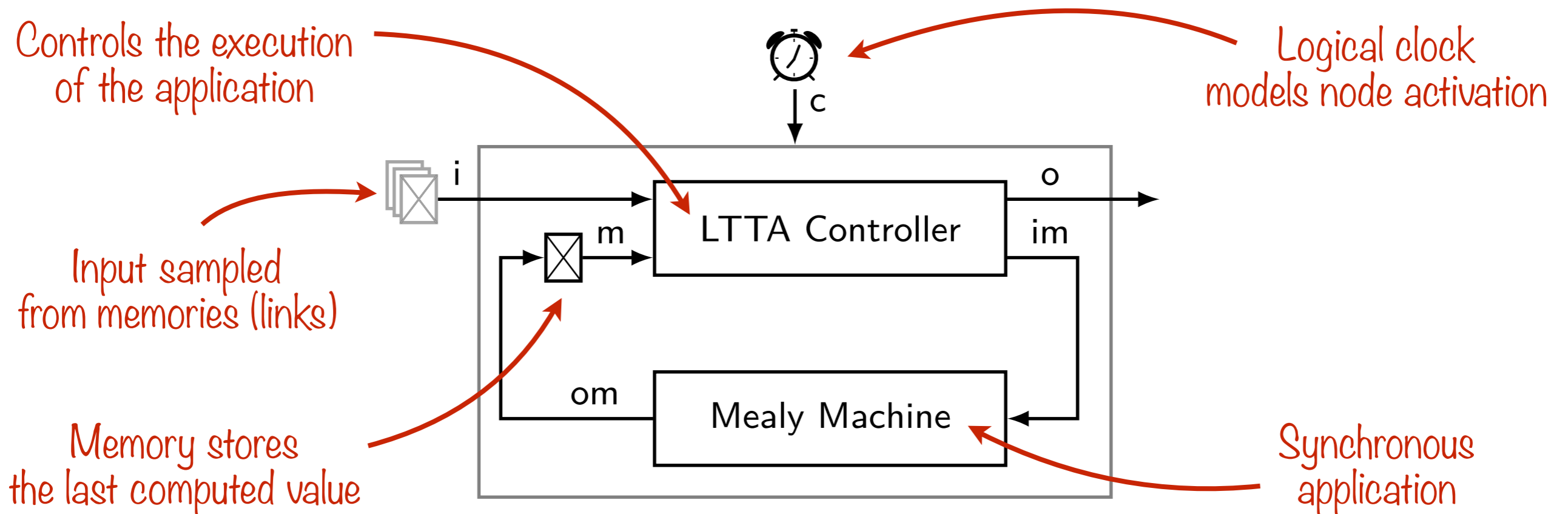


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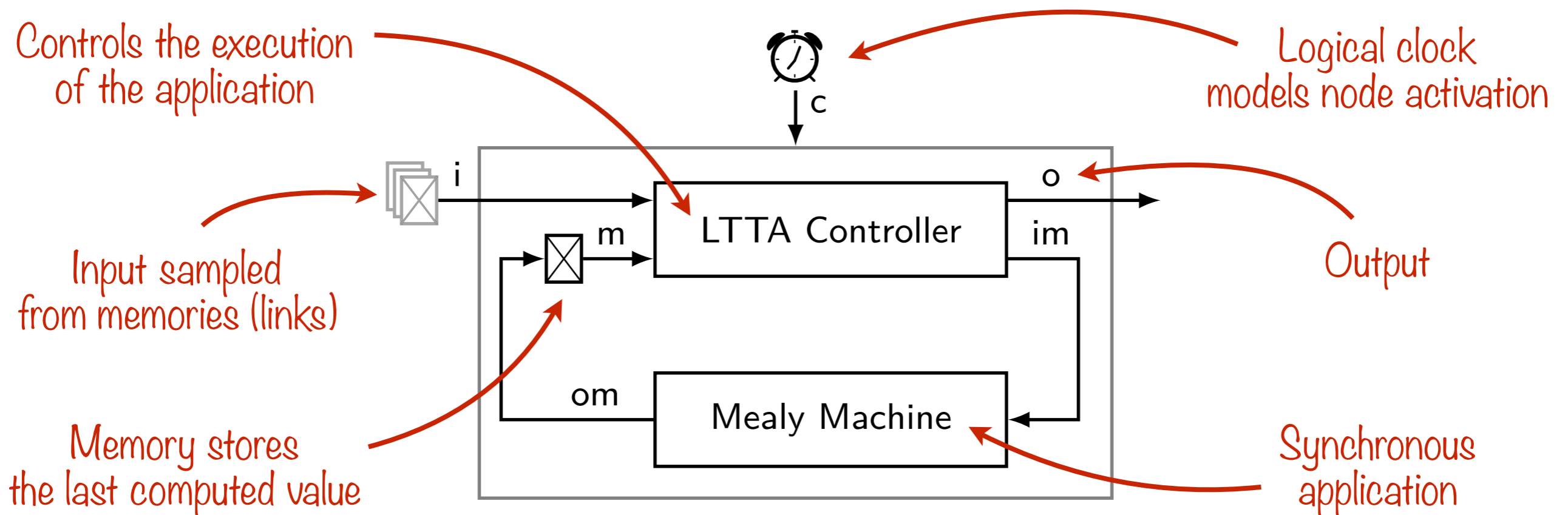


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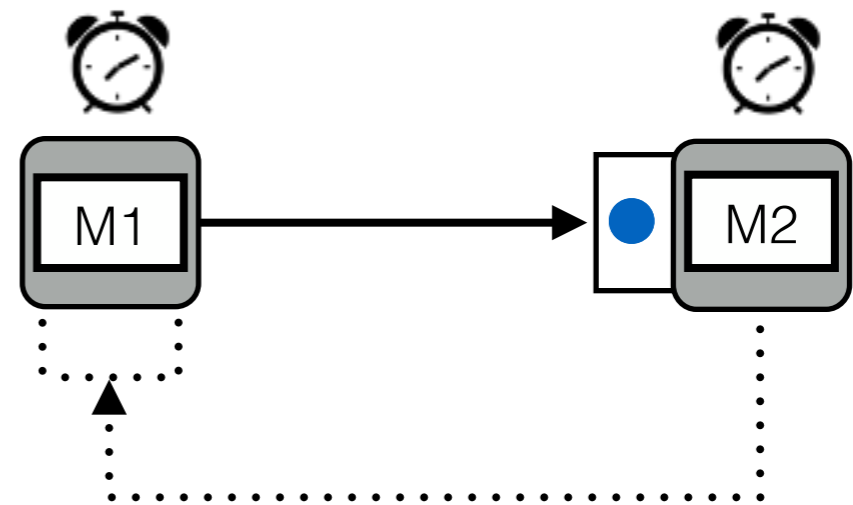
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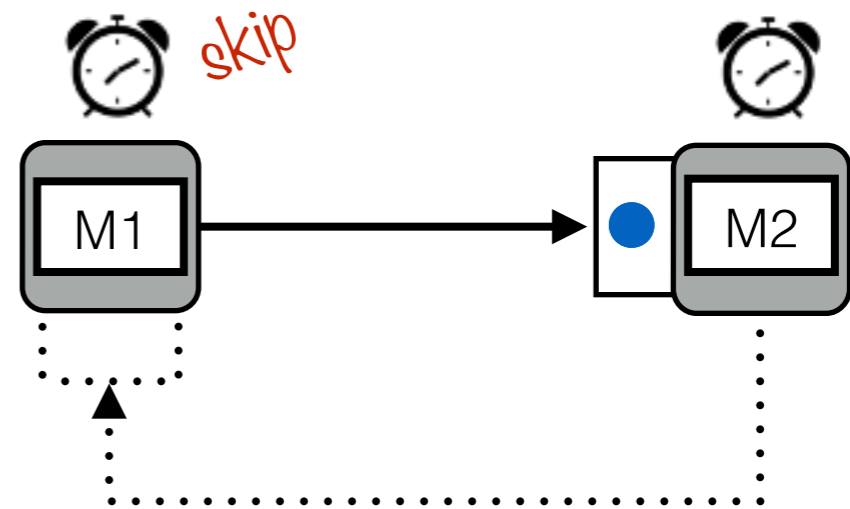
A First Idea: Back-Pressure

- A producer waits for **acknowledgements** from its consumers before sending a new value.
- Nodes **skip** when no acknowledgement or message has been received.



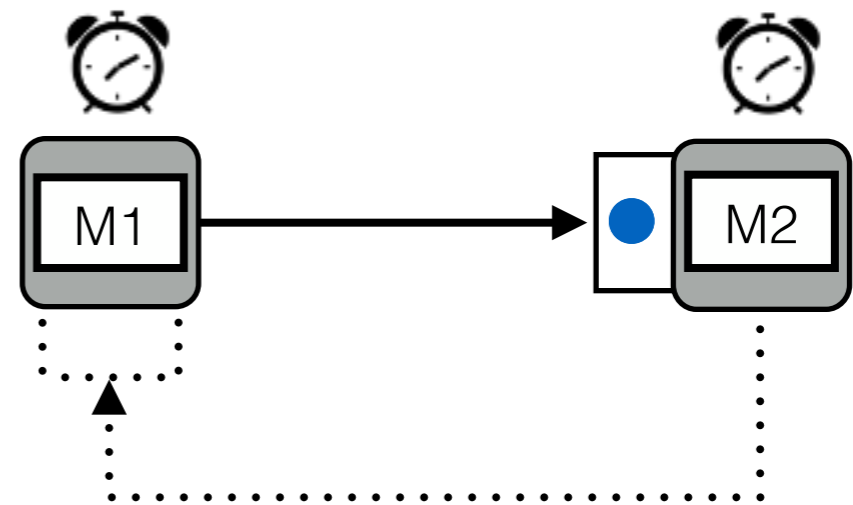
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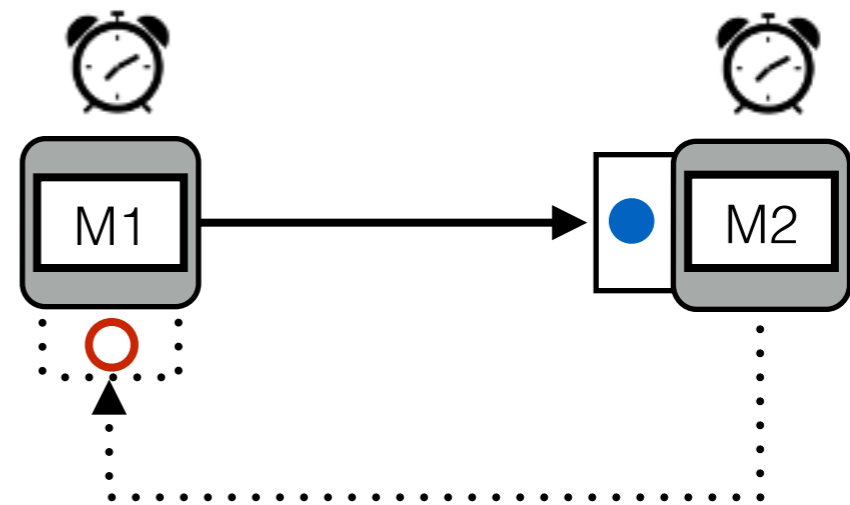
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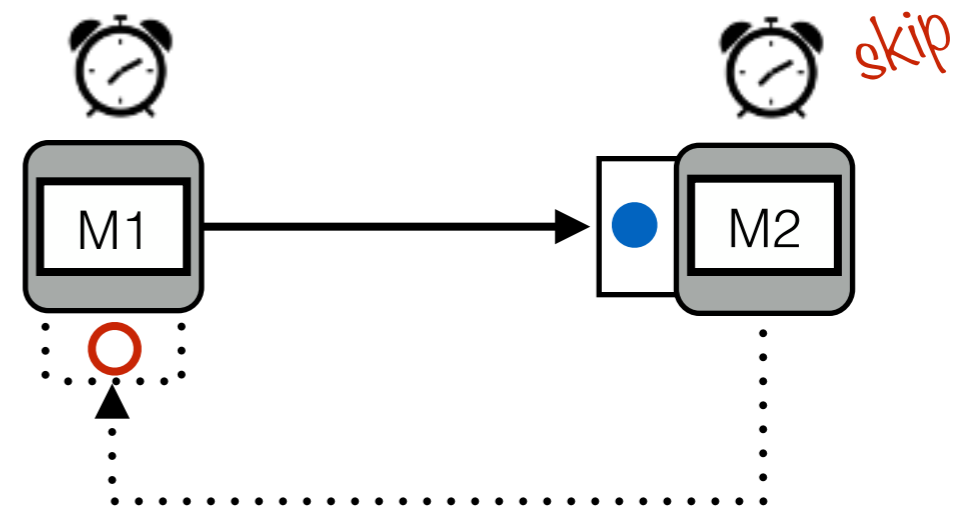
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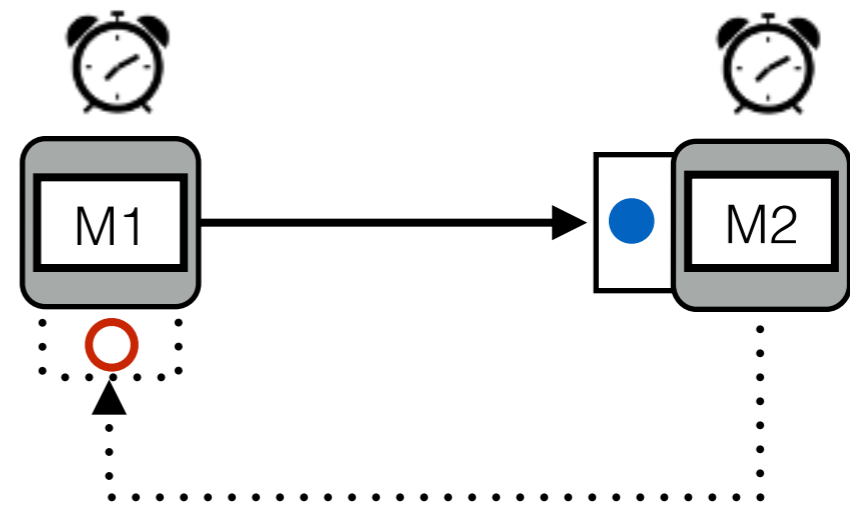
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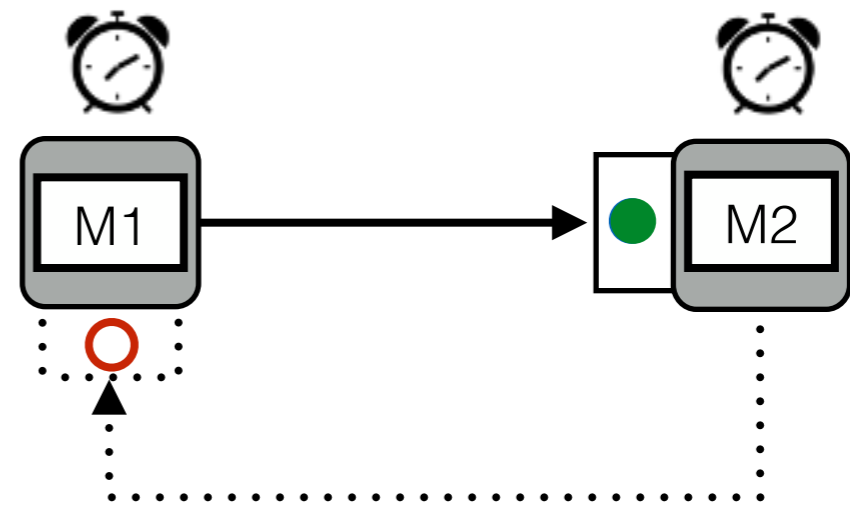
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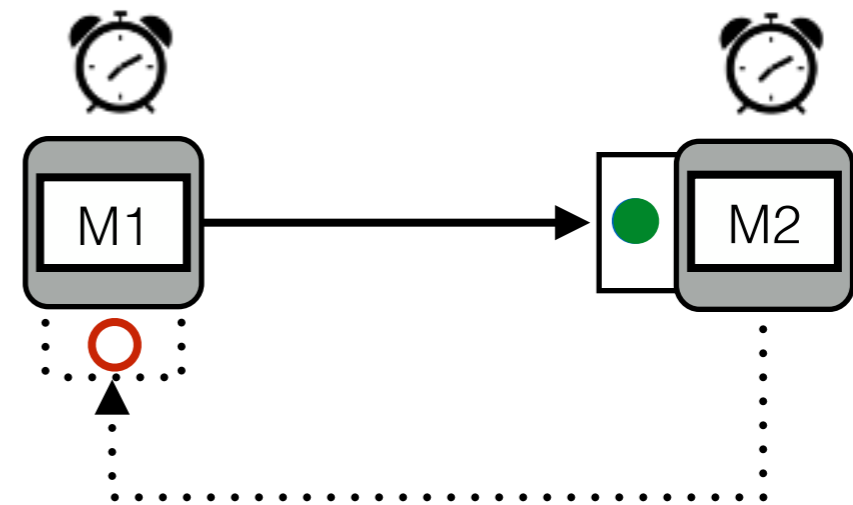
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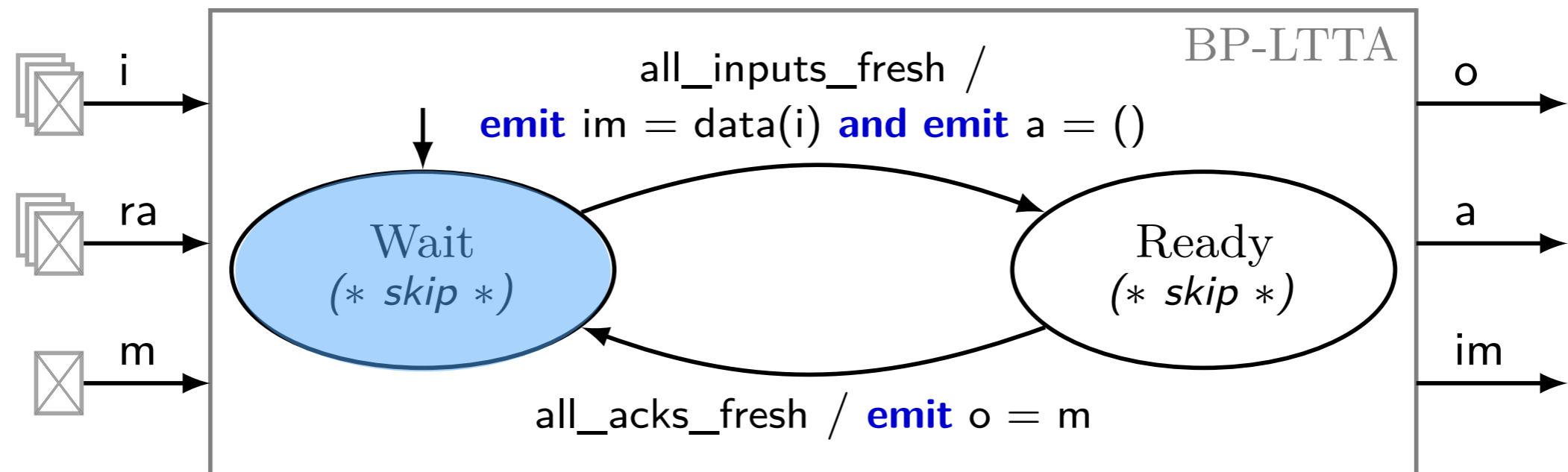
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Flexibility: there is no assumption on the architecture.

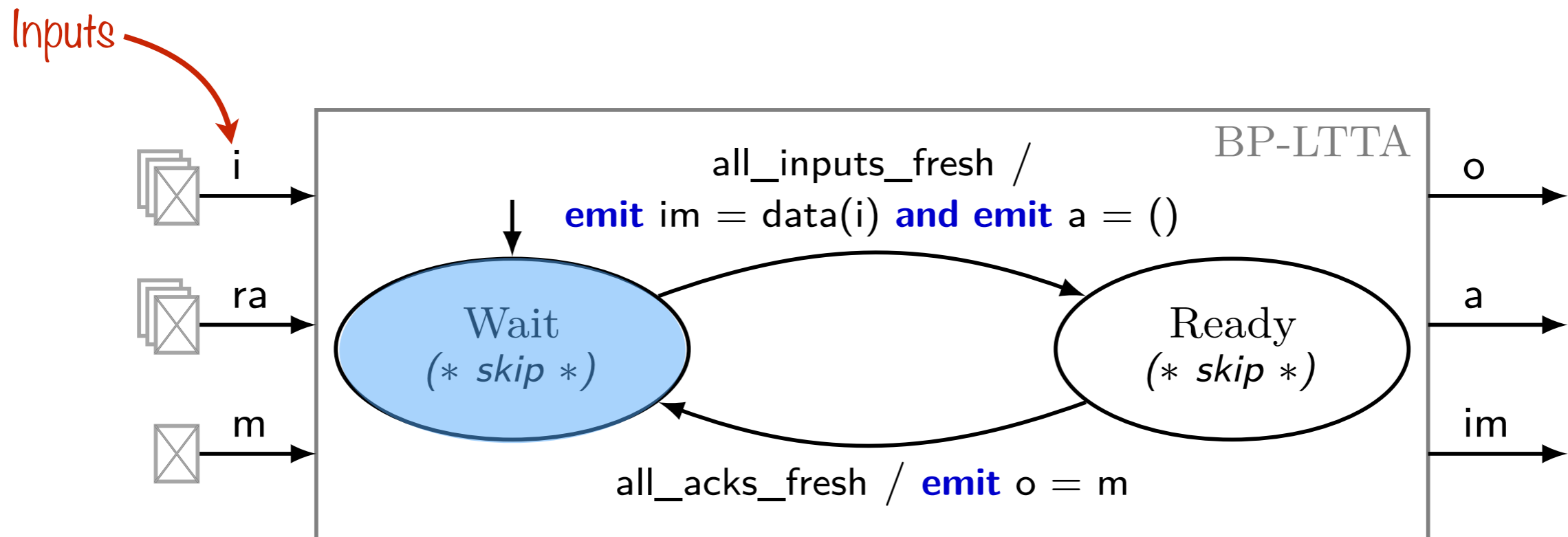
Robustness: if a node crashes the entire network is stuck.

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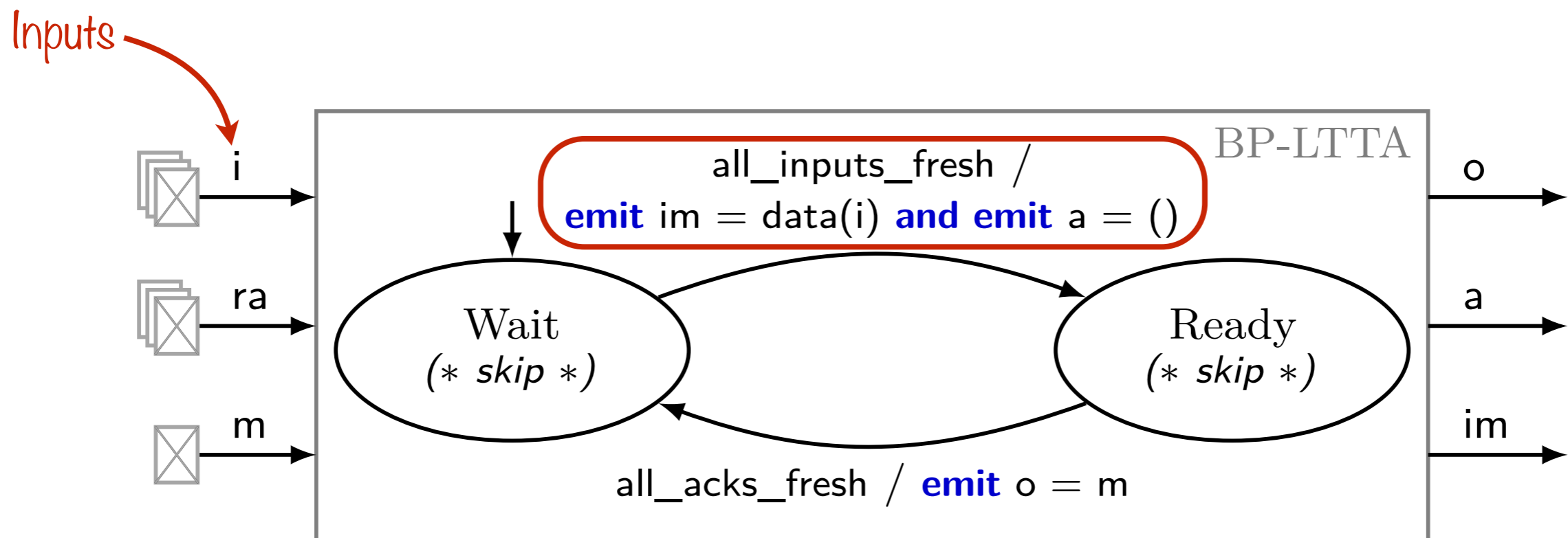
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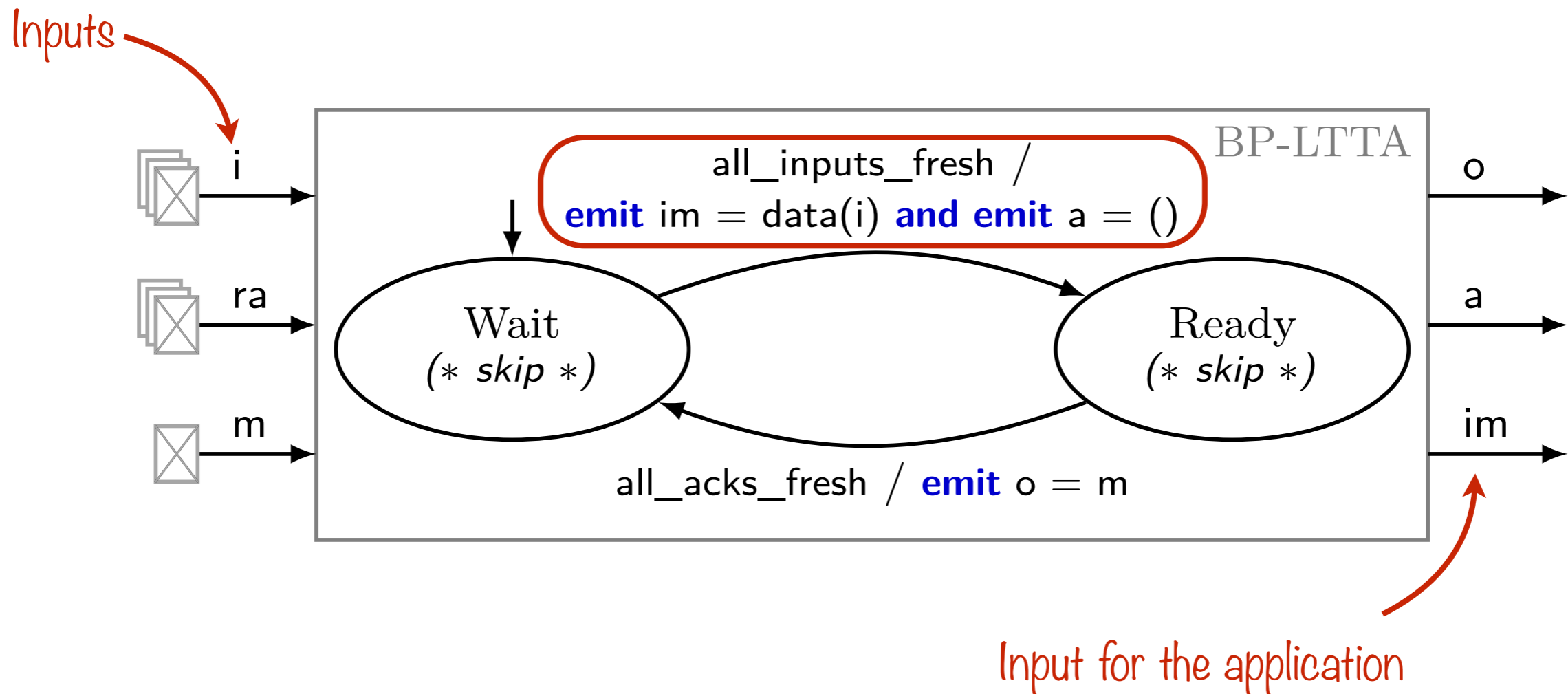
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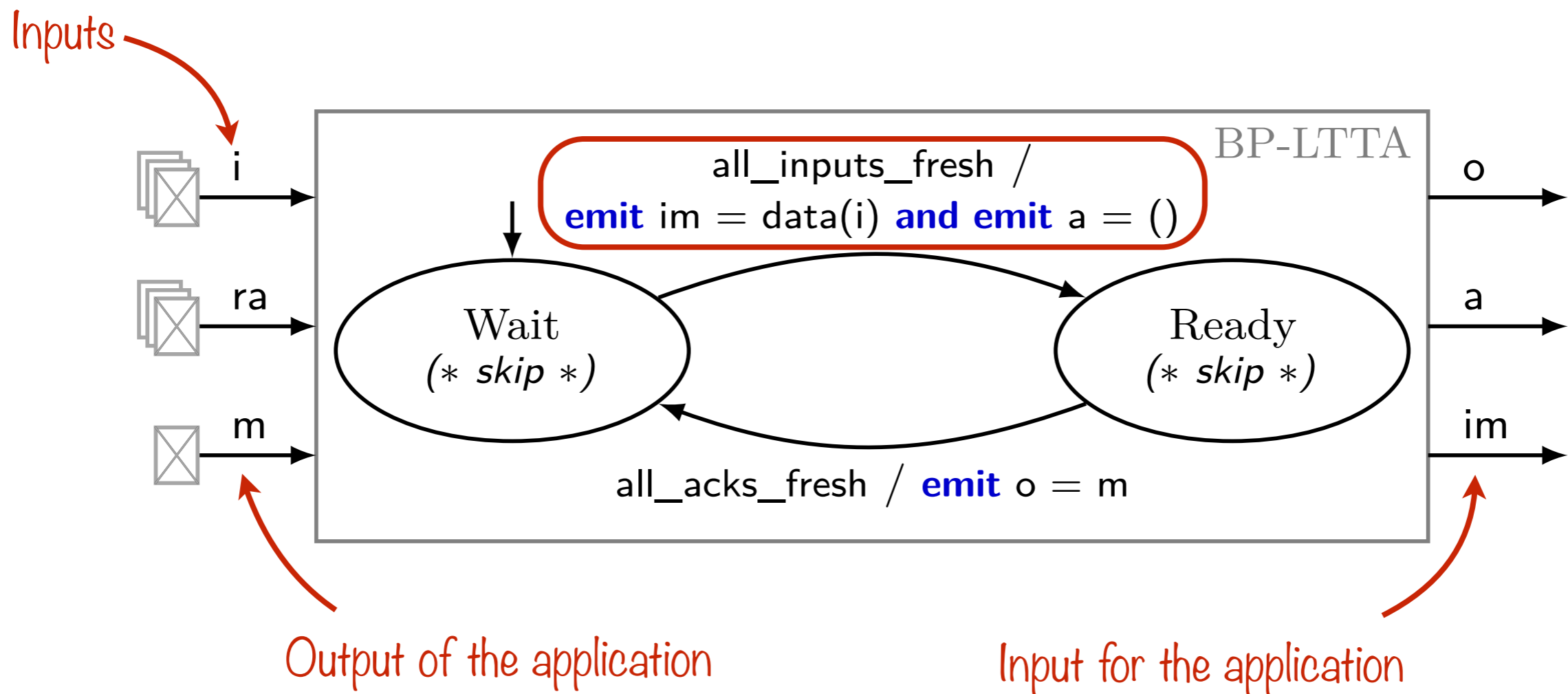
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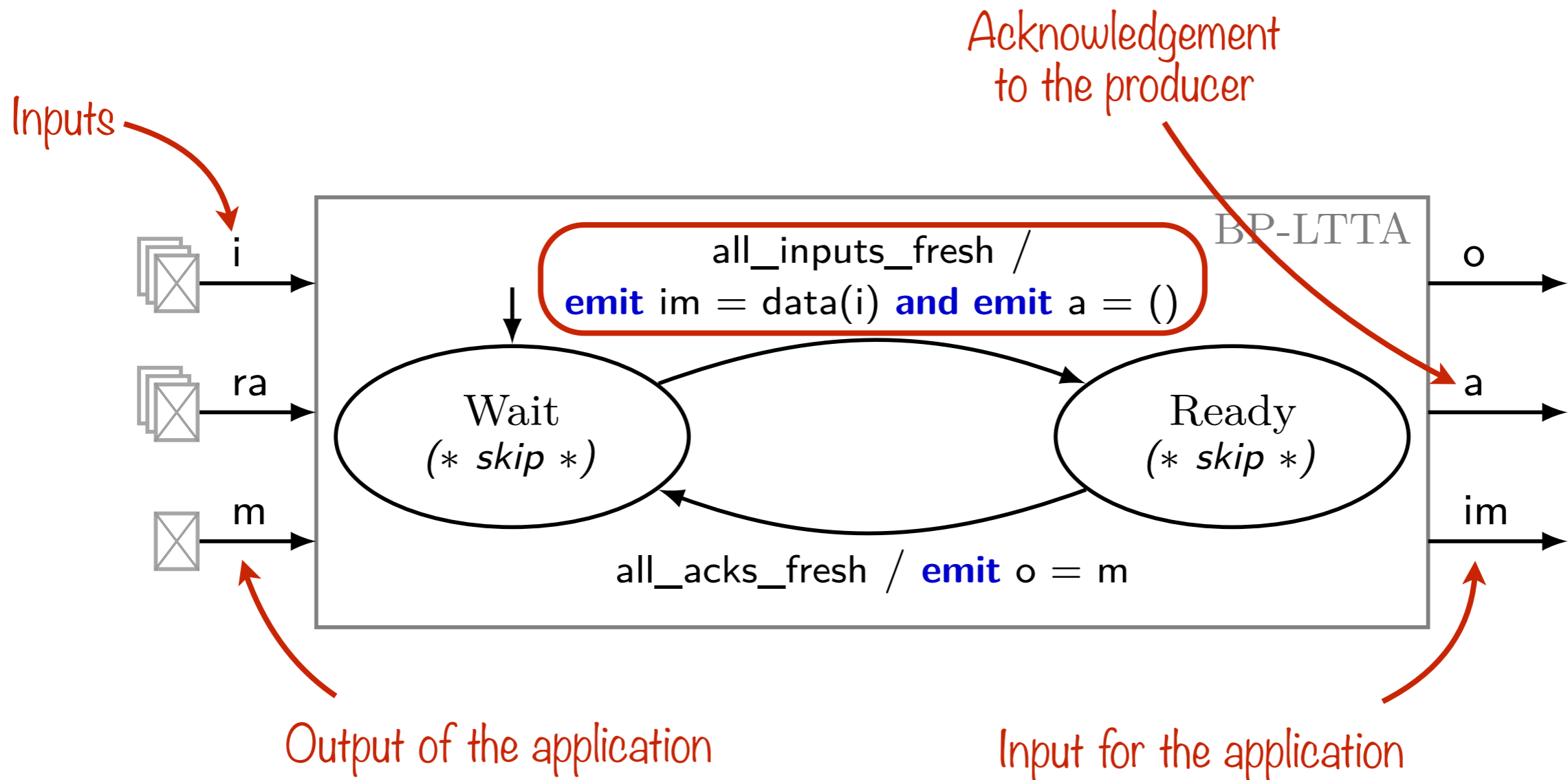
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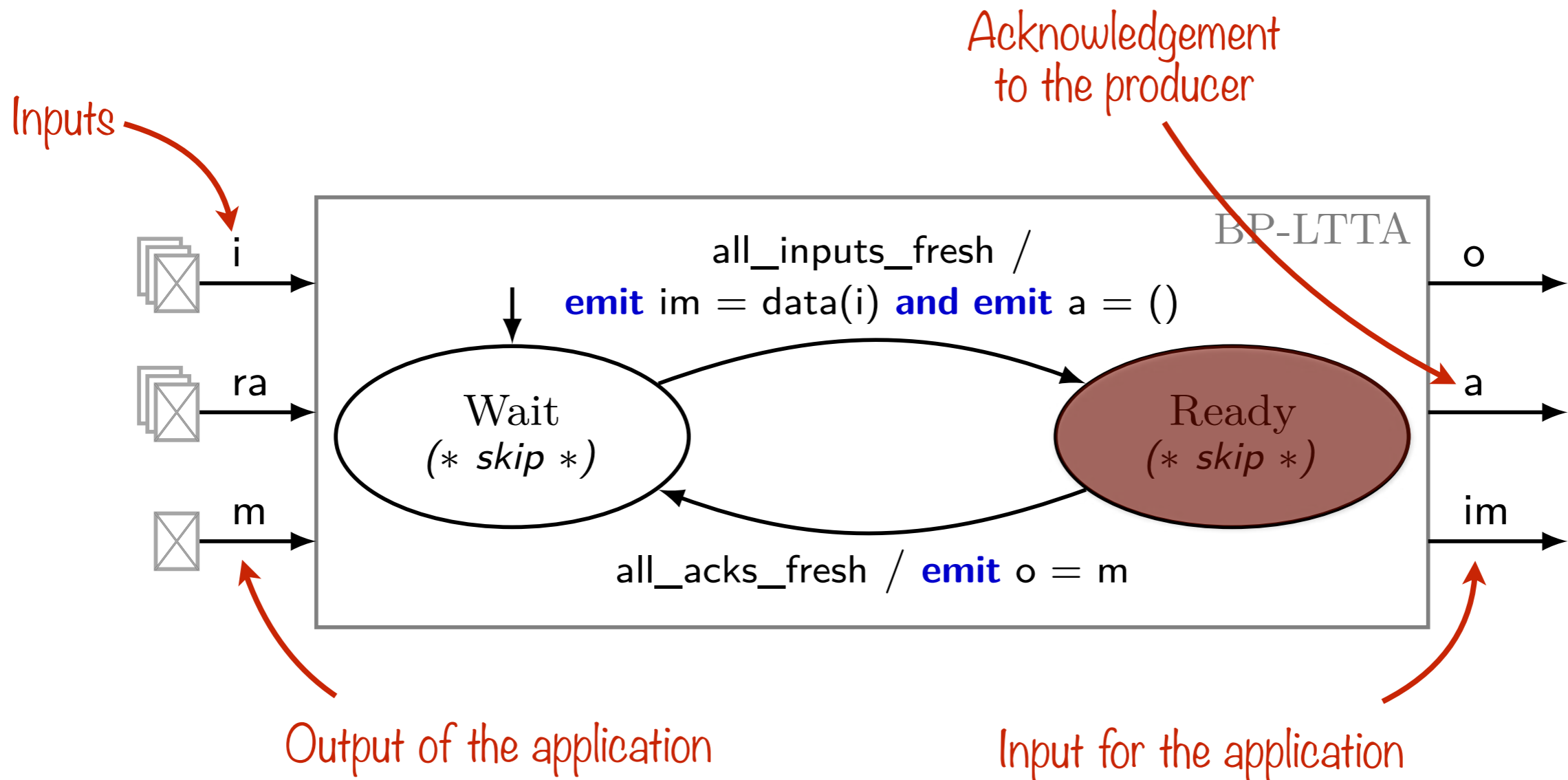
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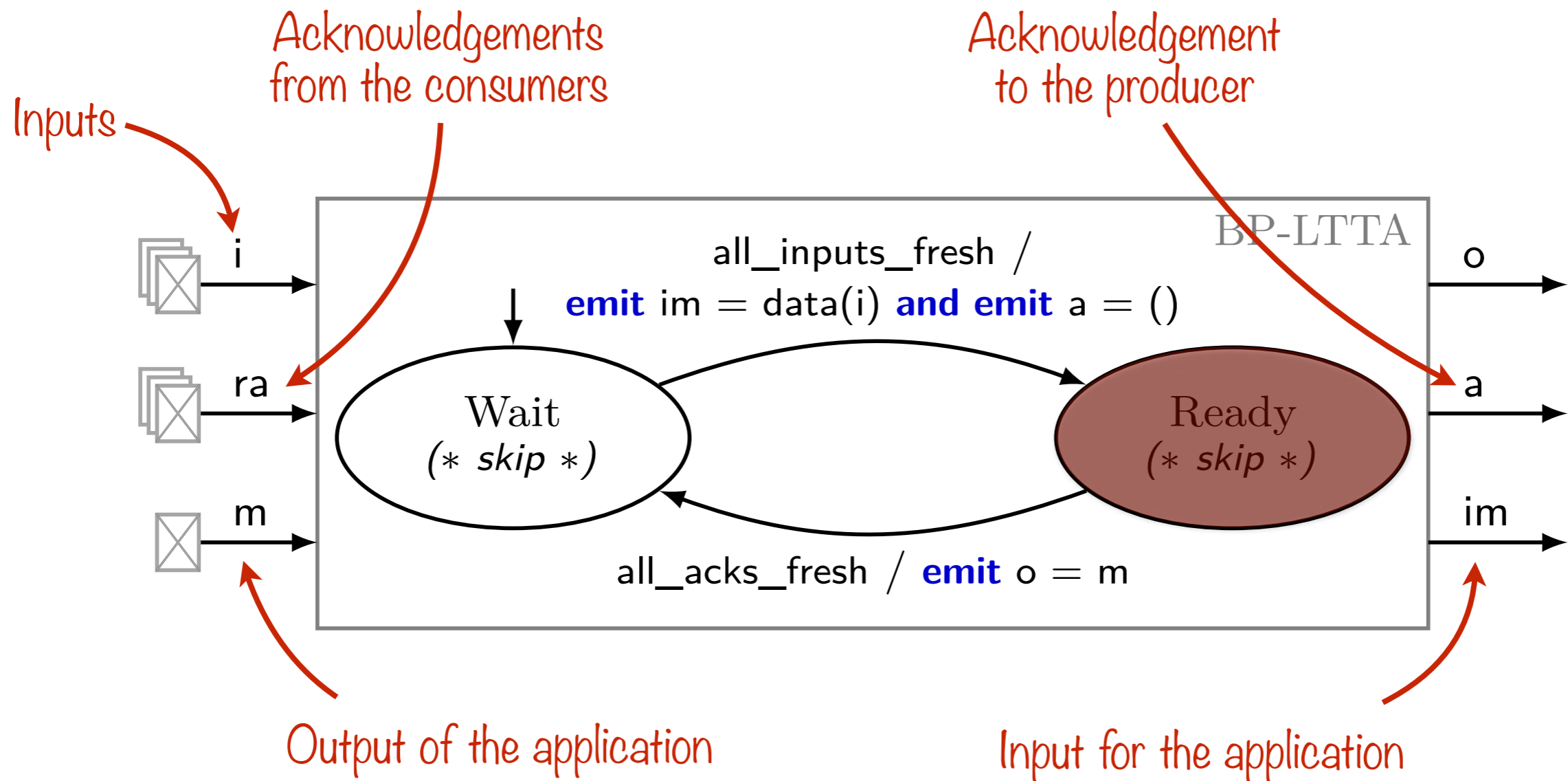
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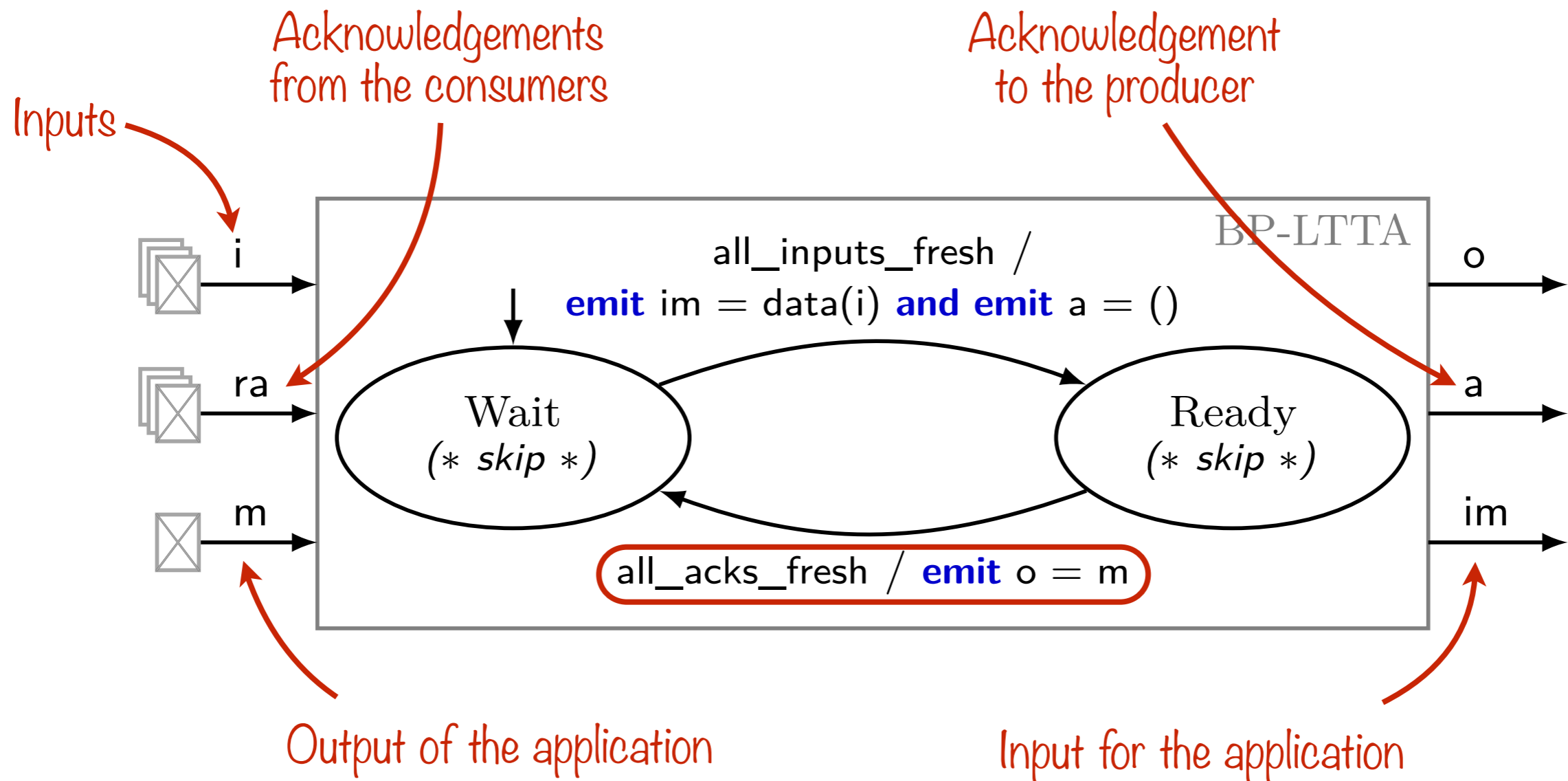
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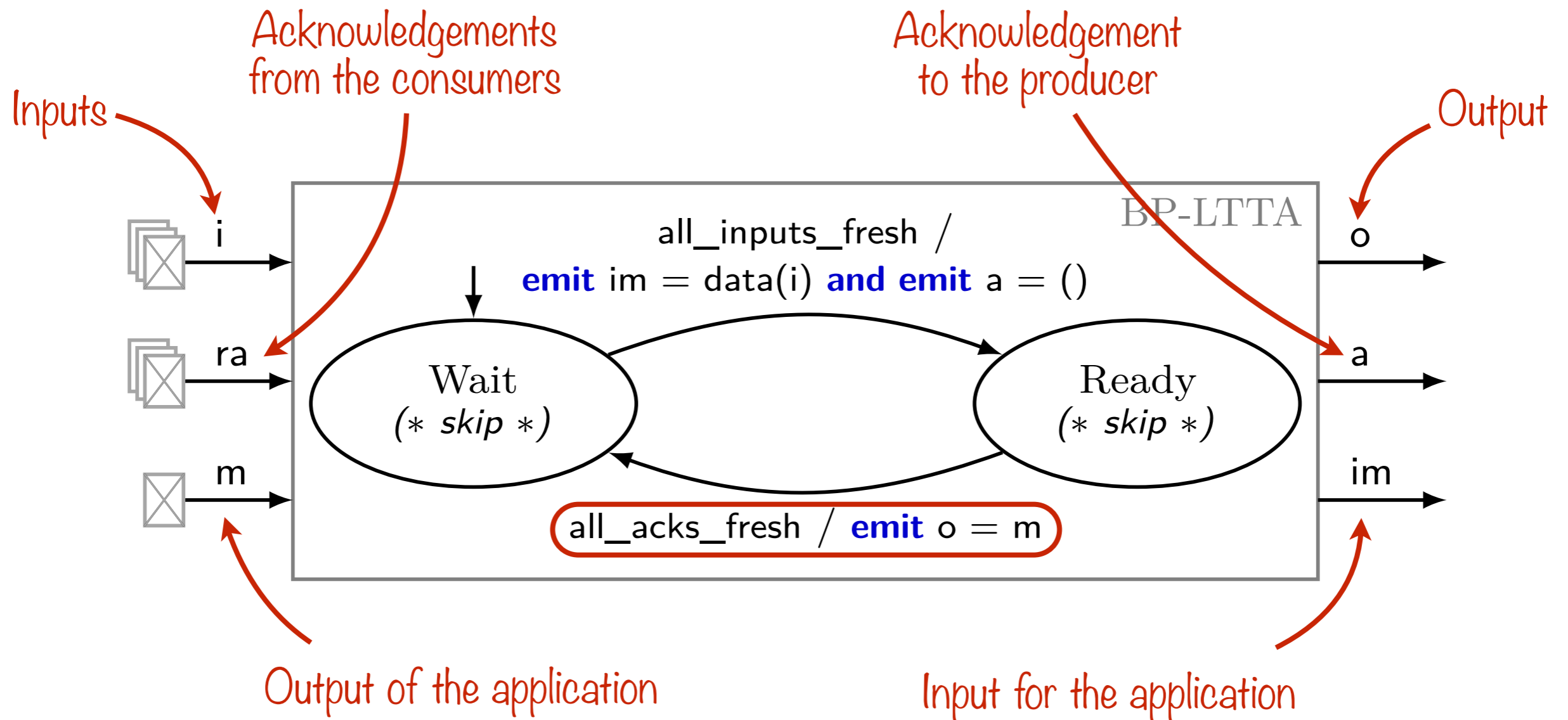
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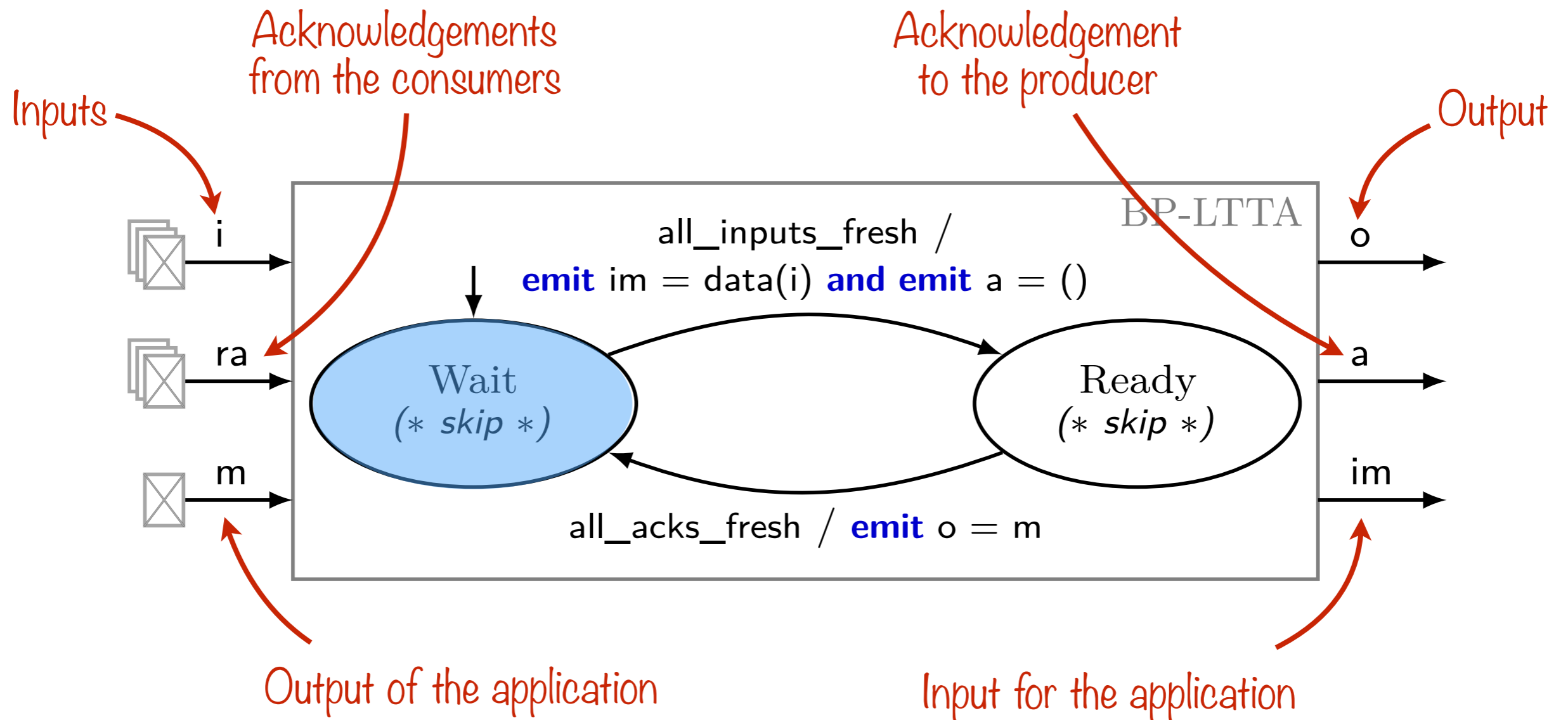
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Time-Based LTTA

Why another protocol?

Back-pressure multiplies the number of messages and memories, and **blocks if a node crashes**

We can take advantage of the **quasi-periodic** nature of the architecture to replace acknowledgment by **waiting**.

At some point, a node can be sure that:

- the last sent data has been read
- a fresh value is available in the memory

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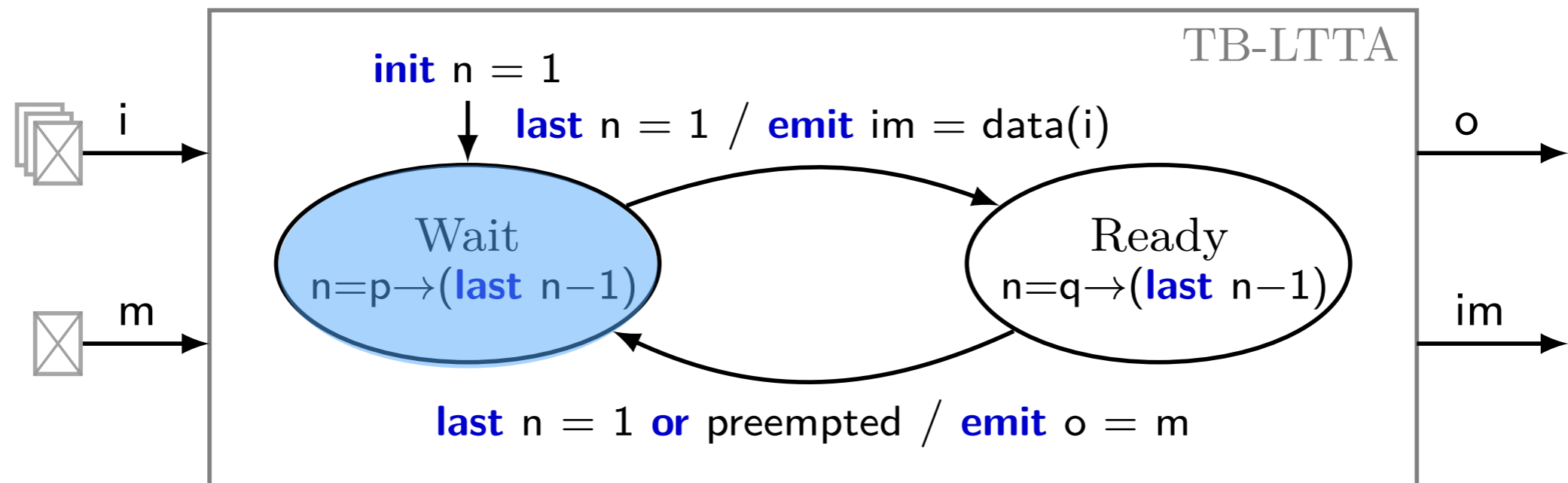
Flexibility: it requires architecture characteristics.

Robustness: controllers can run in a degraded mode.

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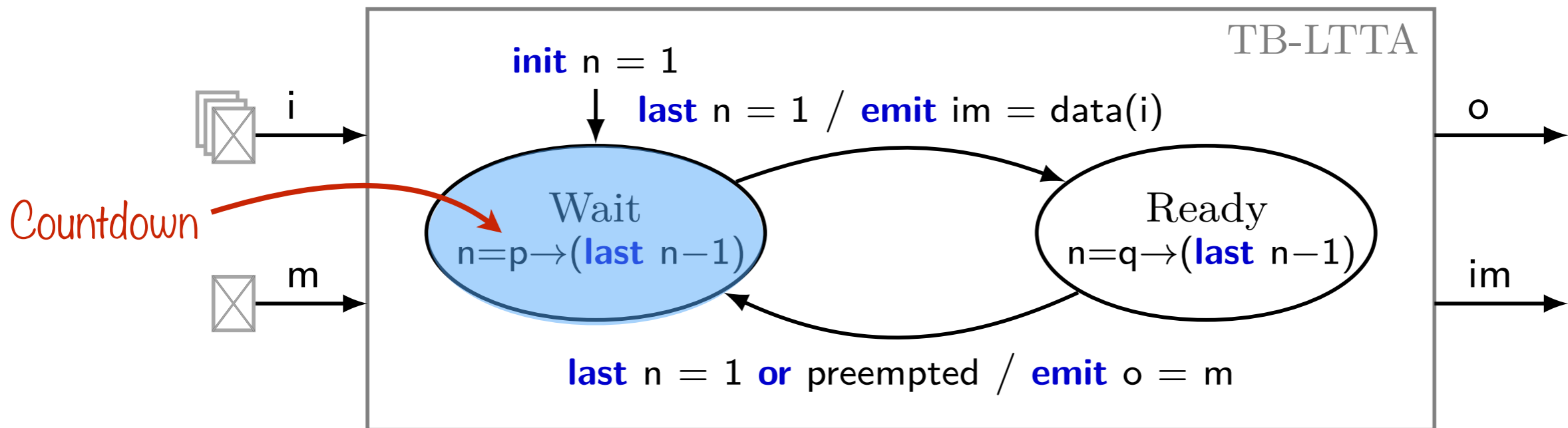
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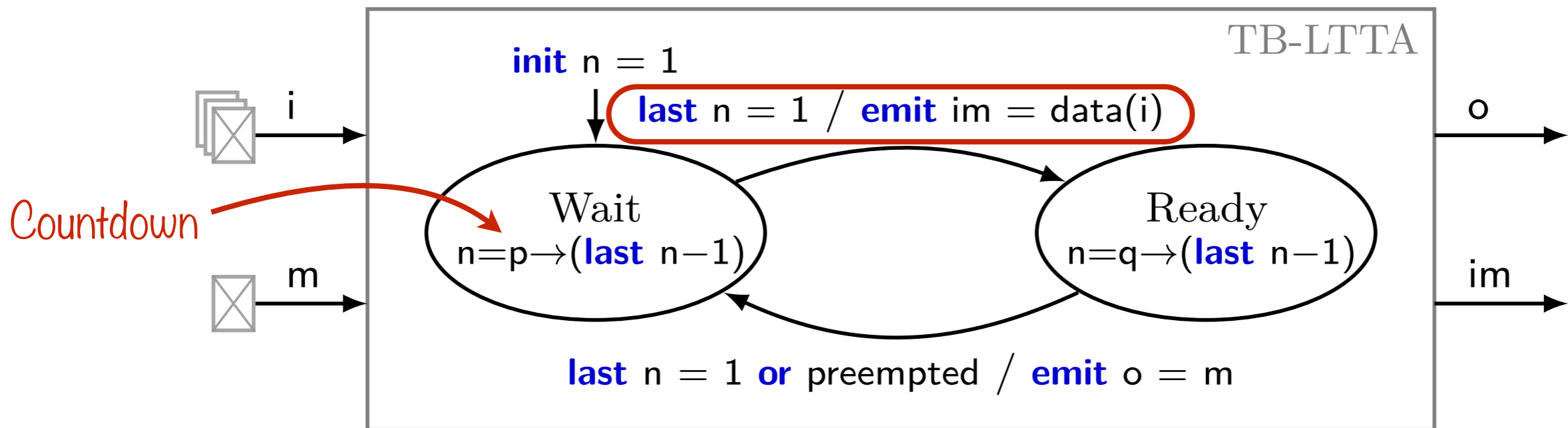
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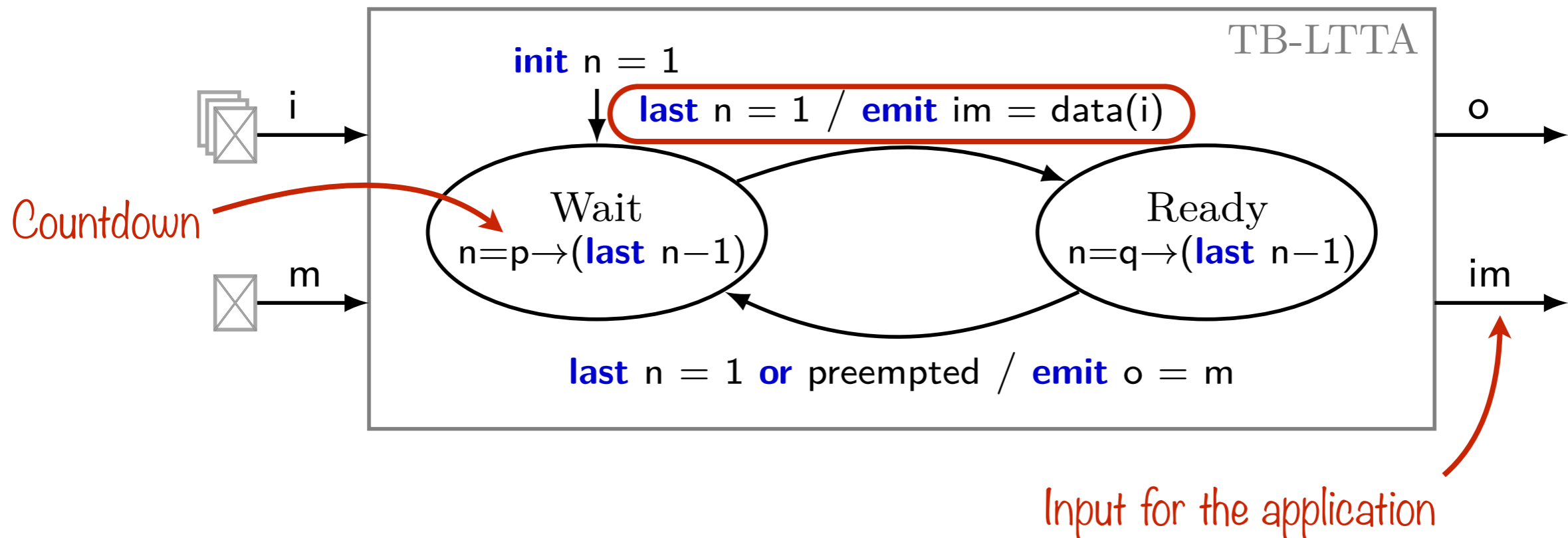
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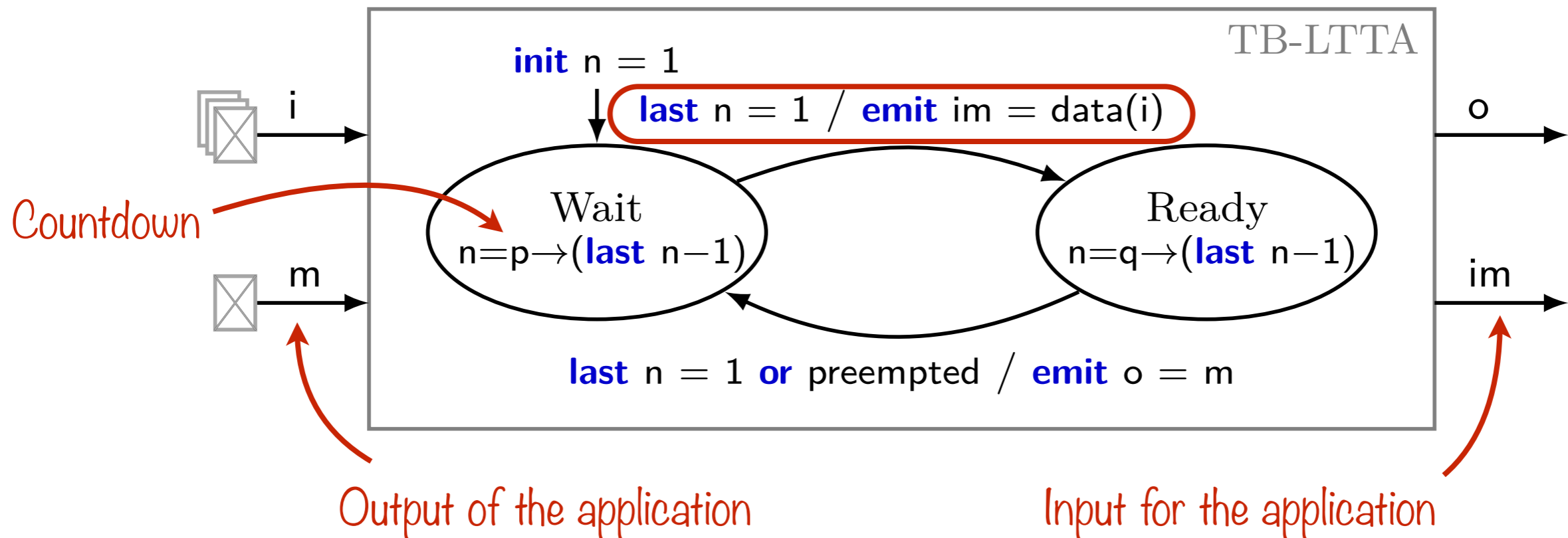
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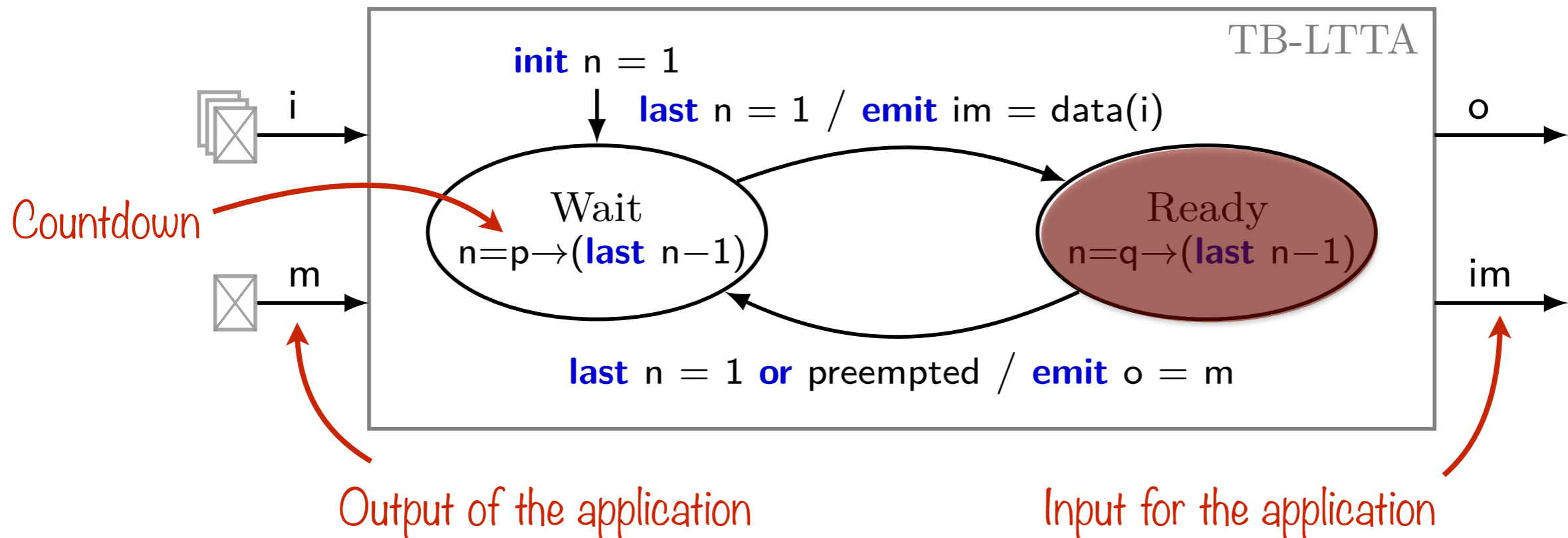
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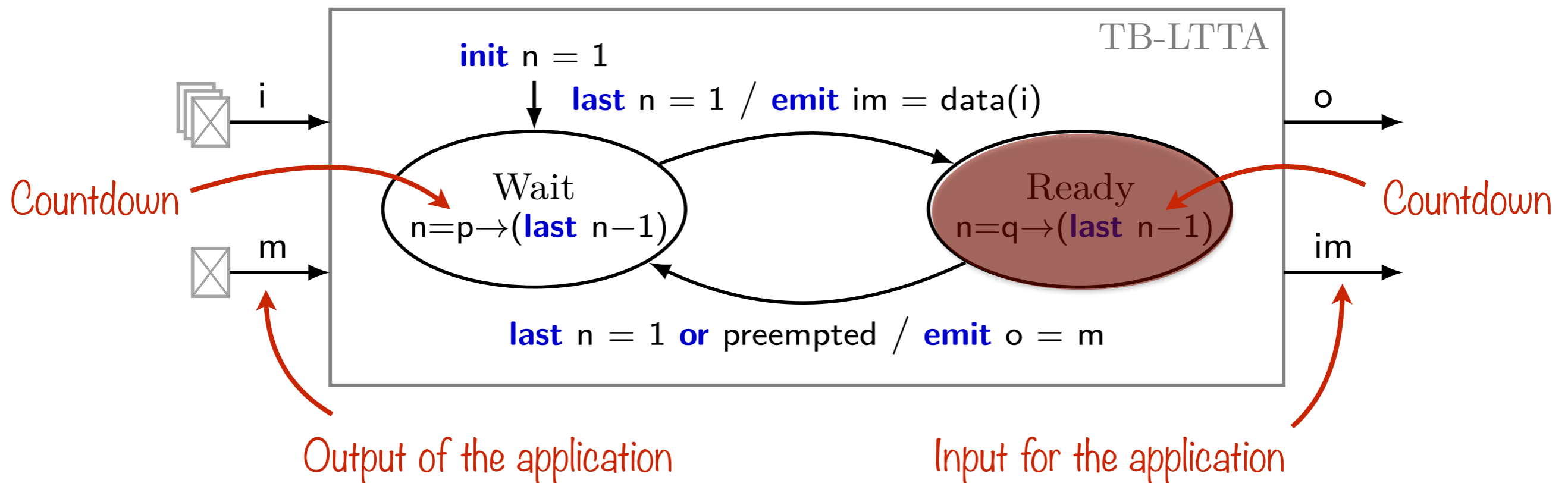
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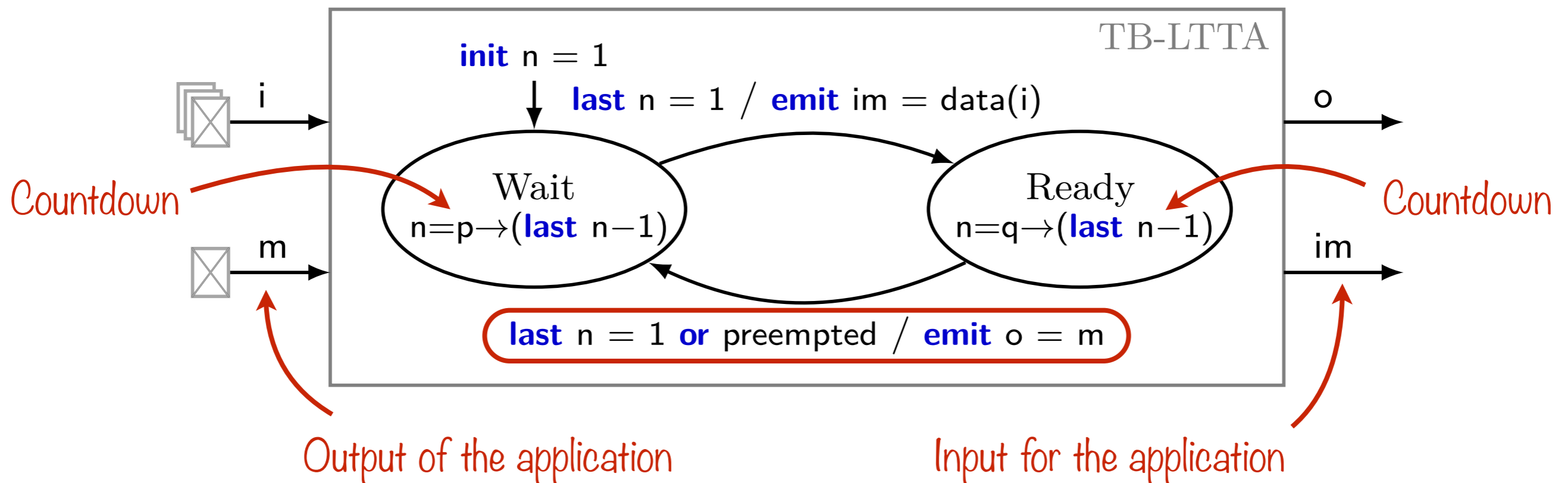
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Time-Based LTTA

Wait: await the publication of the slowest node.

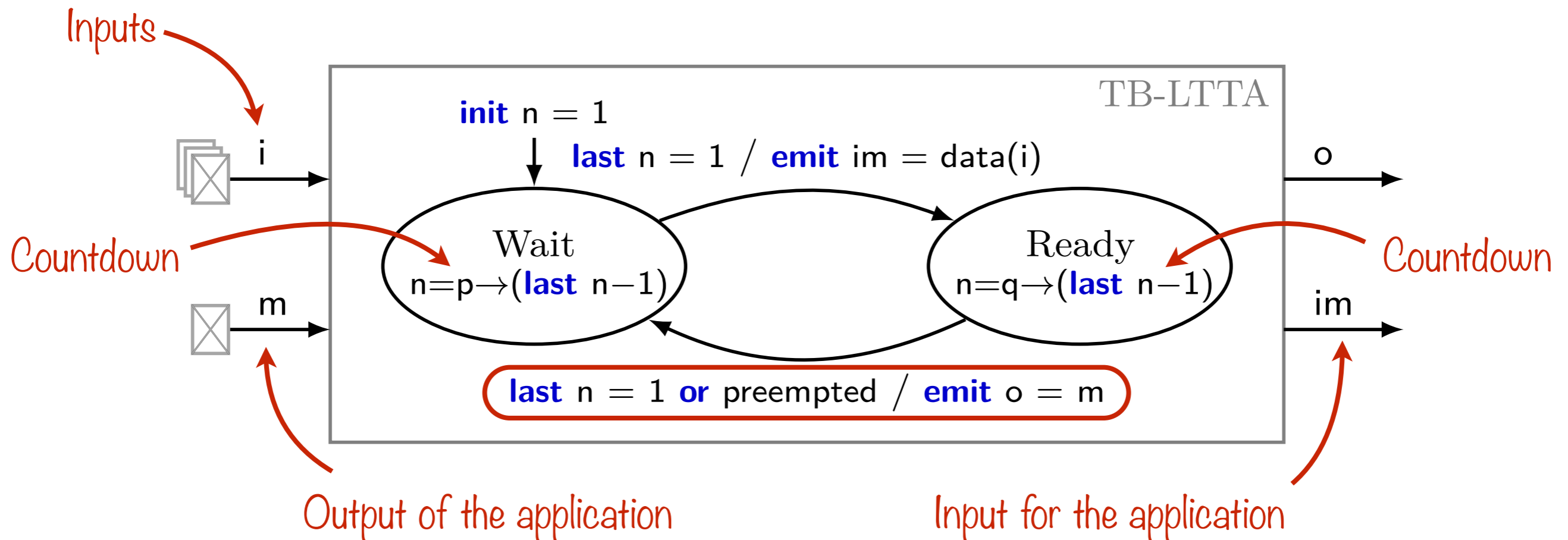
Ready: resynchronize with the fastest node.



Time-Based LTTA

Wait: await the publication of the slowest node.

Ready: resynchronize with the fastest node.

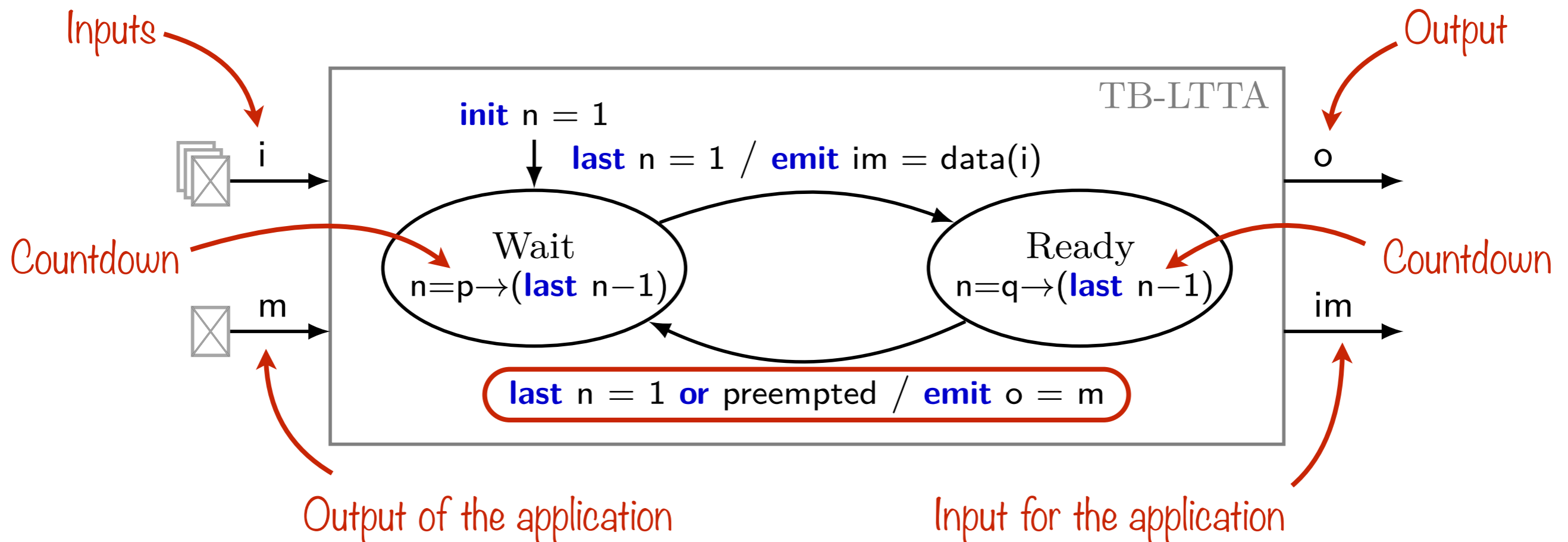


Preemption: when a publication is detected, the consumers have finished executing

Time-Based LTTA

Wait: await the publication of the slowest node.

Ready: resynchronize with the fastest node.

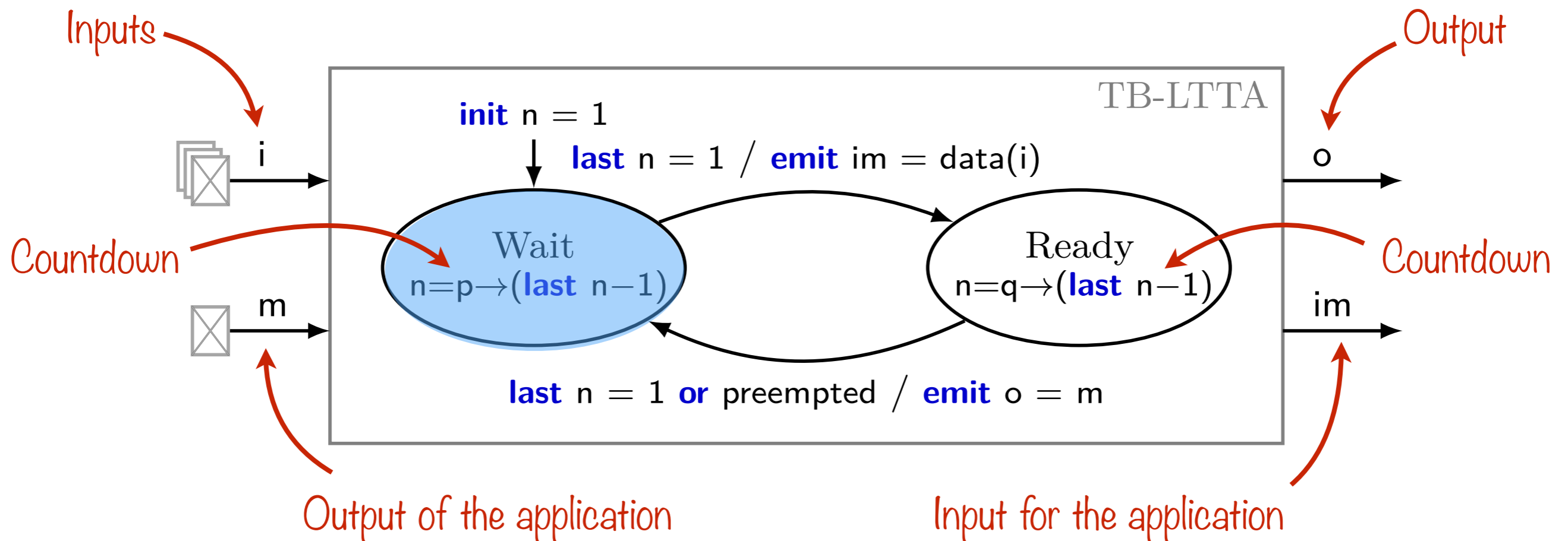


Preemption: when a publication is detected, the consumers have finished executing

Time-Based LTTA

Wait: await the publication of the slowest node.

Ready: resynchronize with the fastest node.

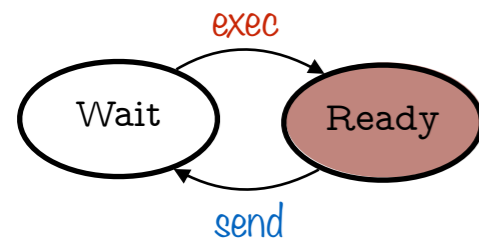
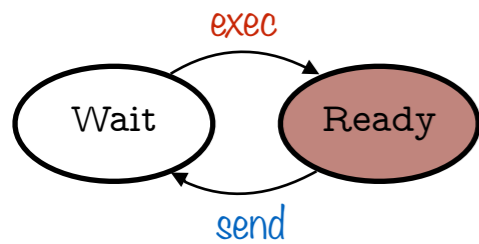
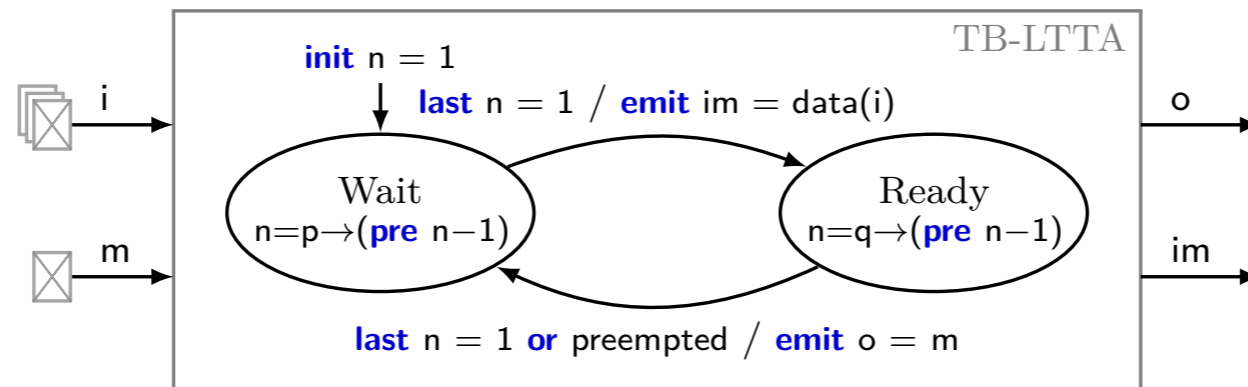


Preemption: when a publication is detected, the consumers have finished executing

Time-Based LTTA

Simulation $p=3$ $q=2$

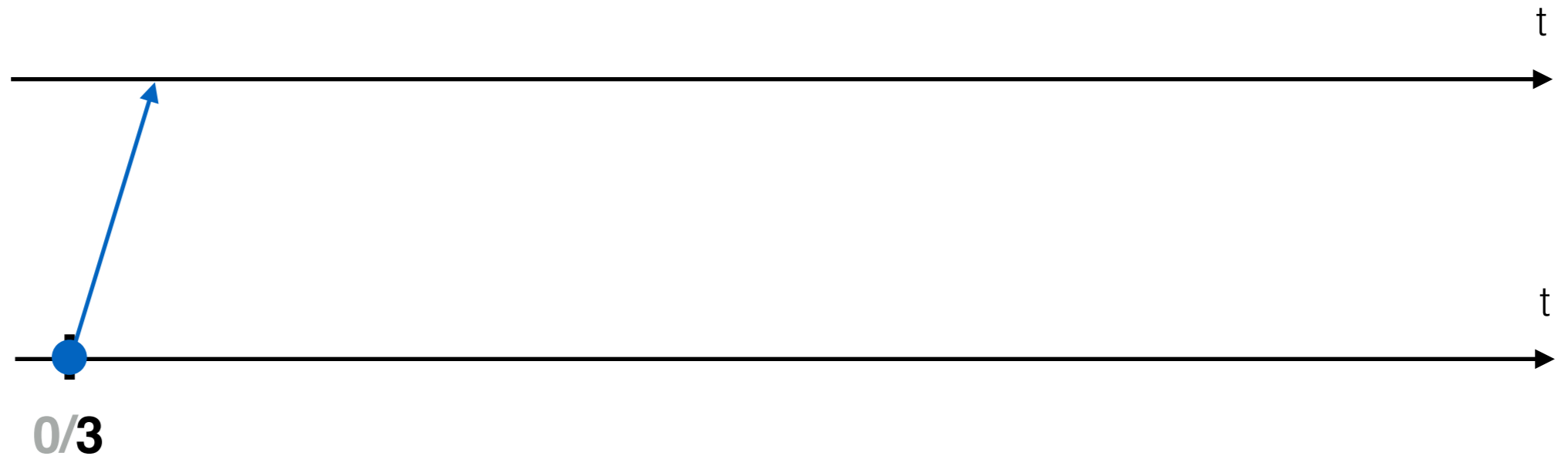
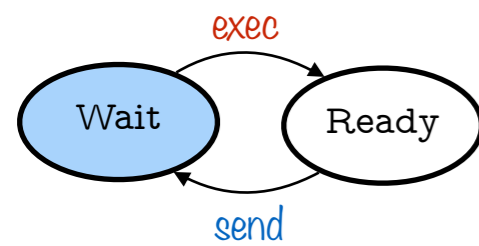
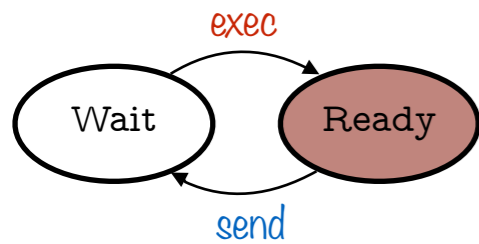
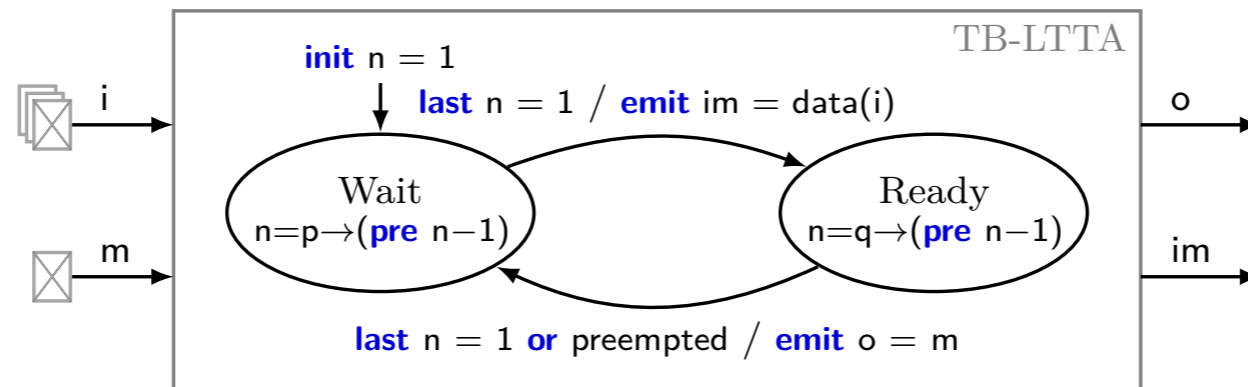
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

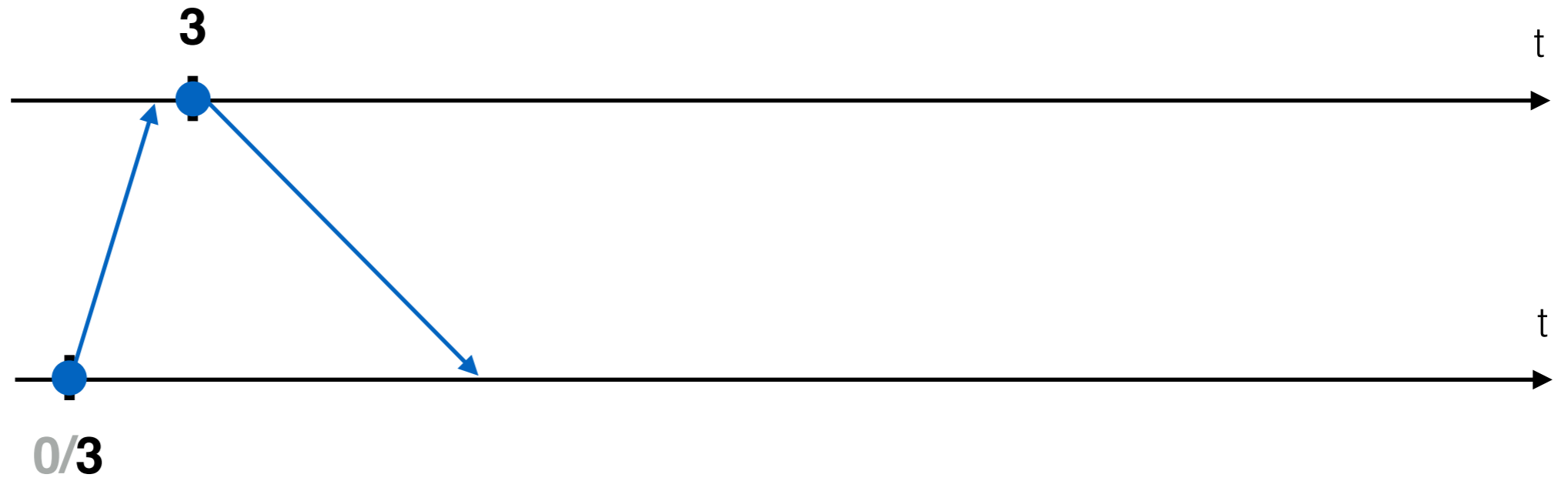
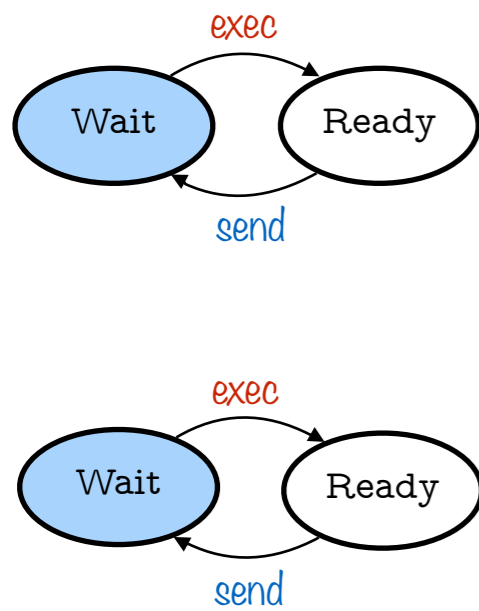
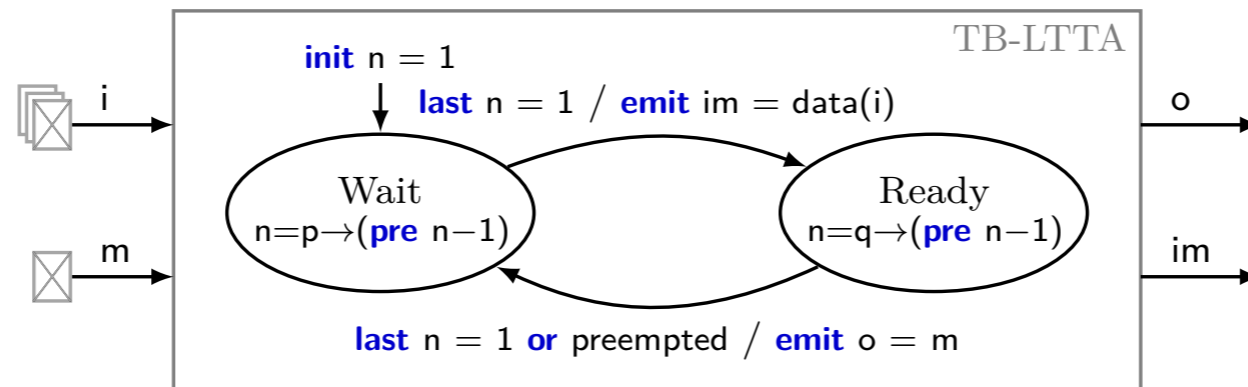
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

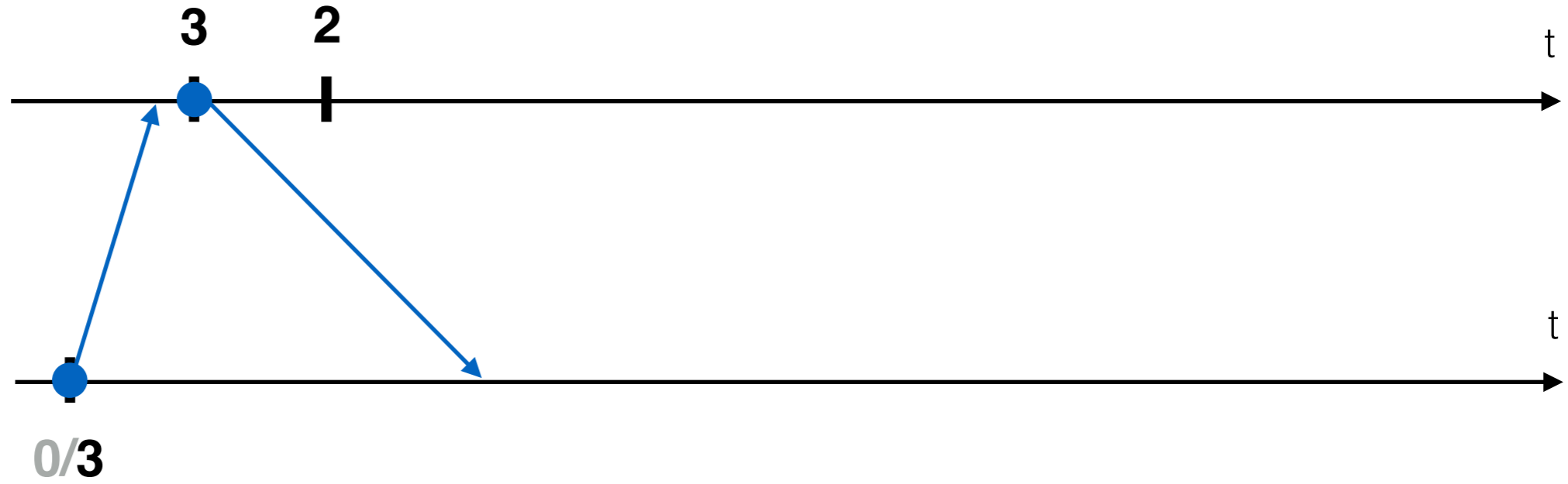
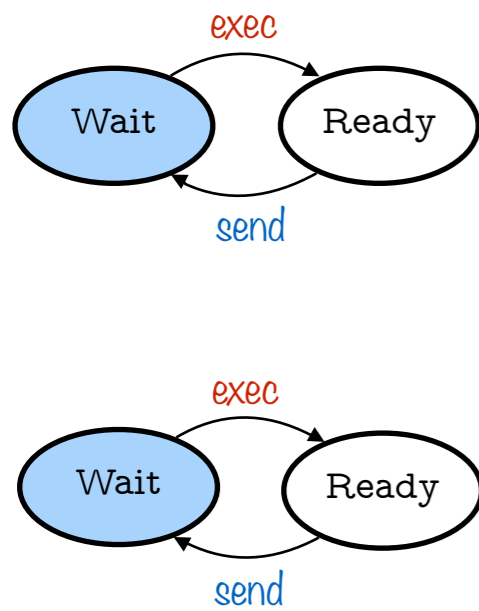
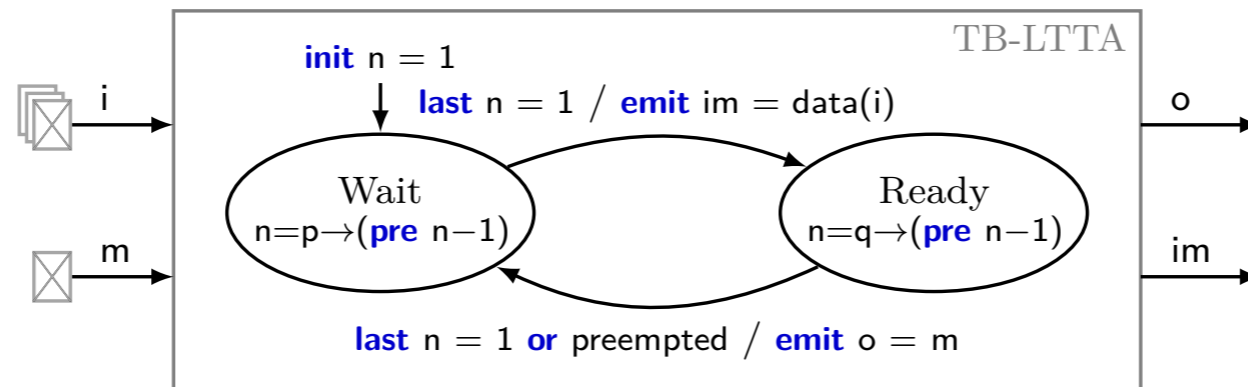
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

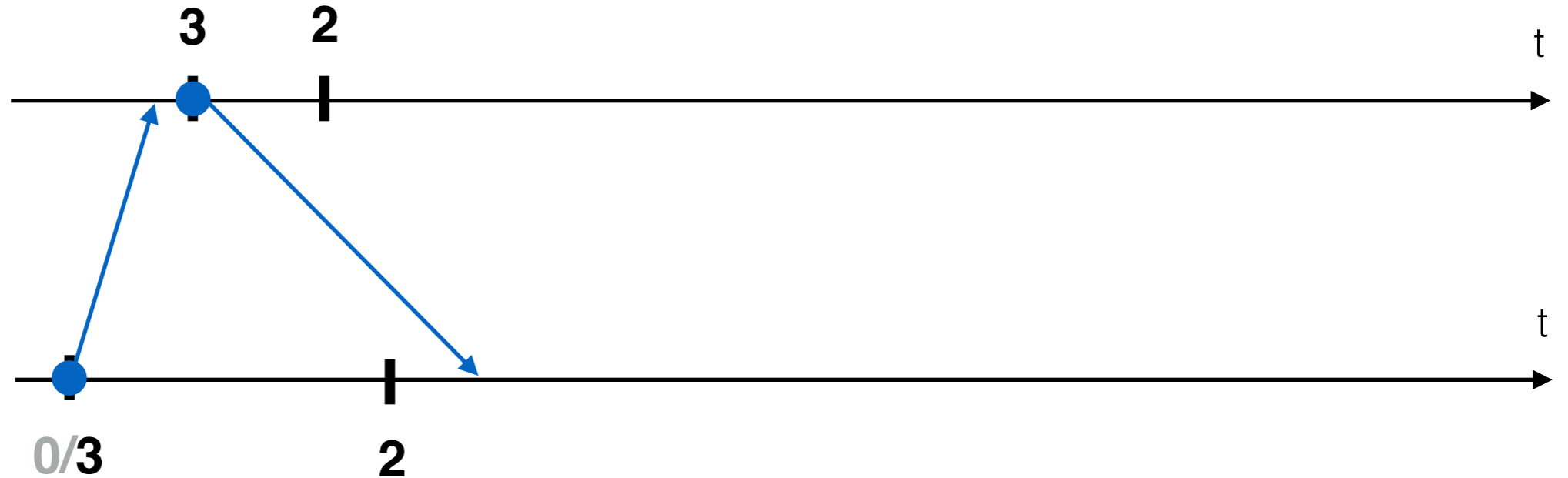
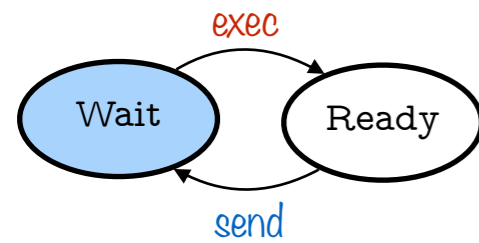
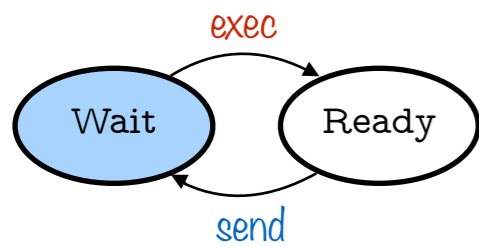
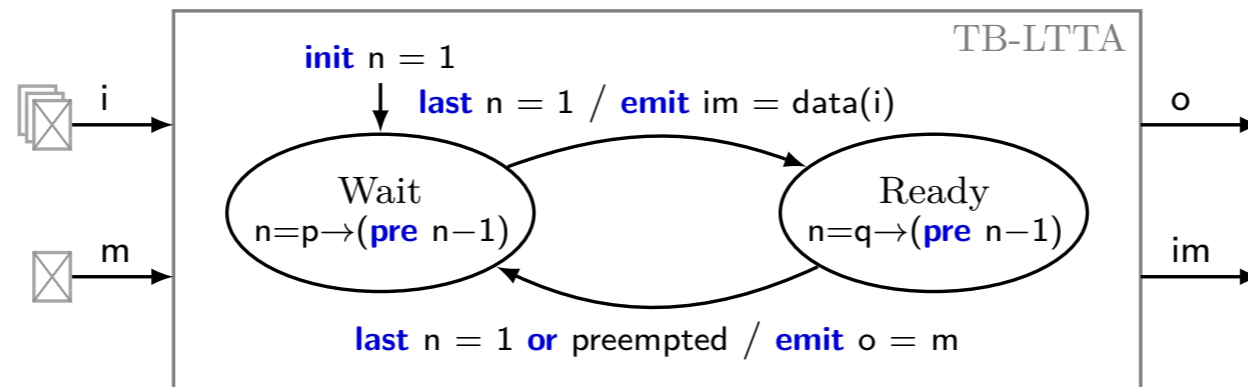
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

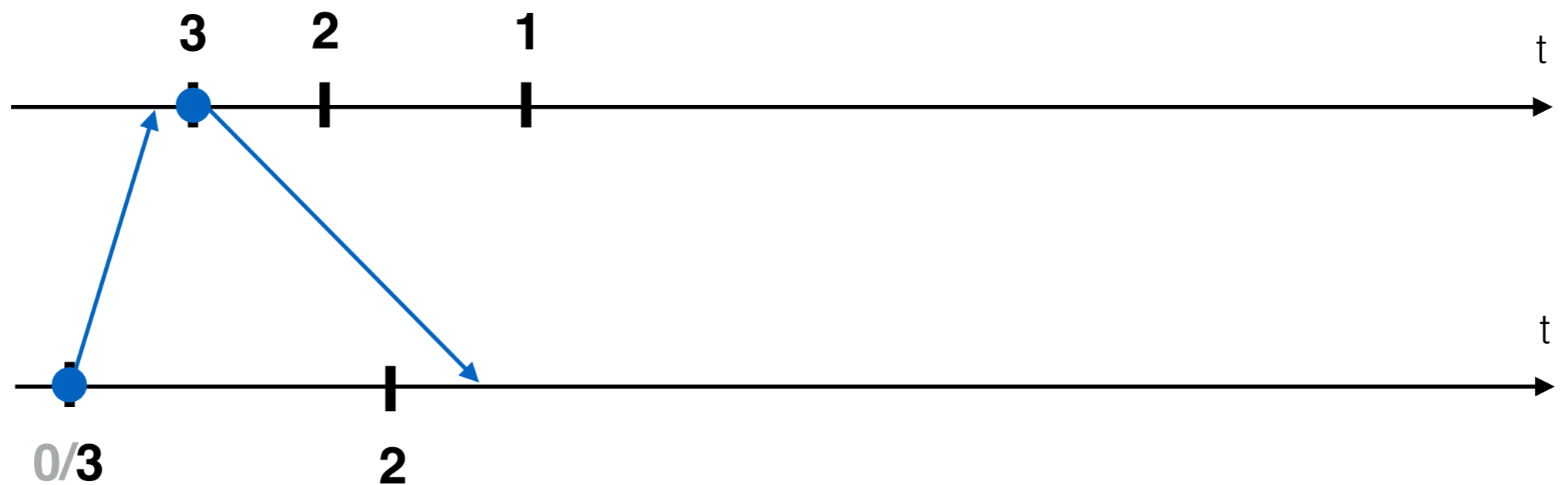
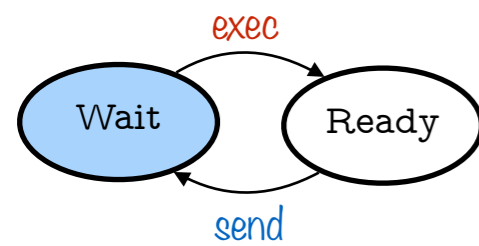
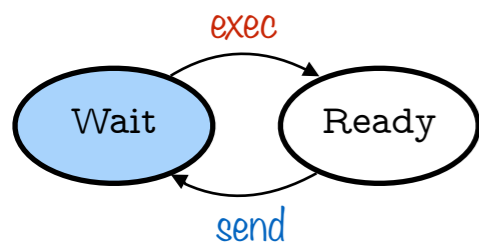
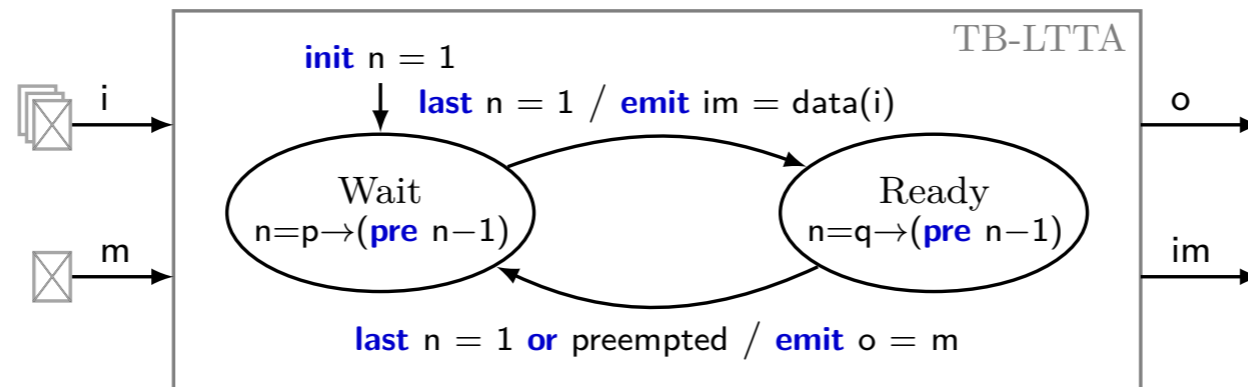
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

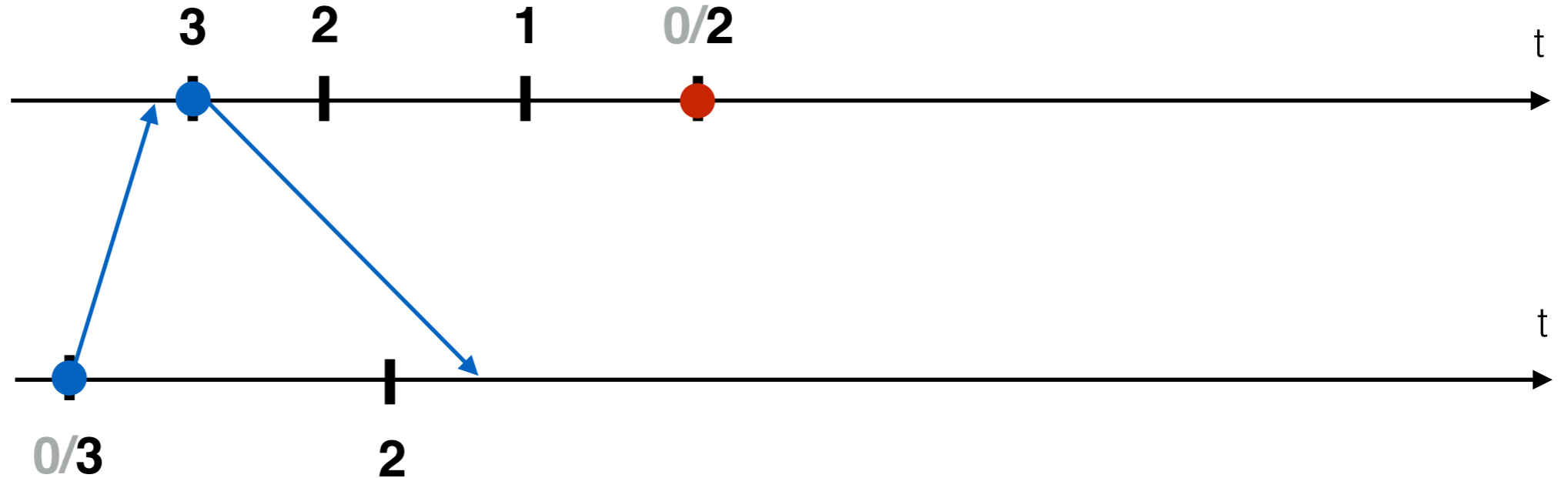
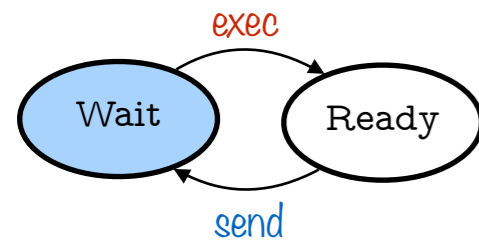
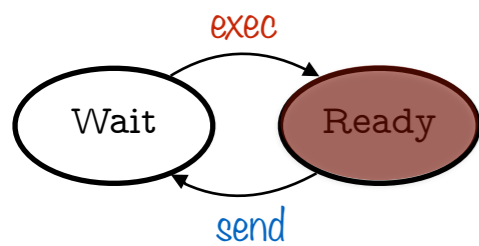
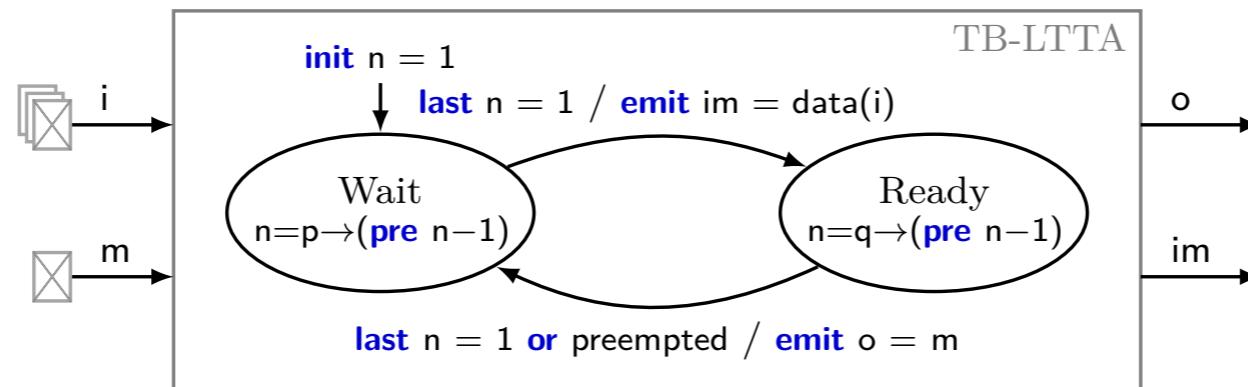
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

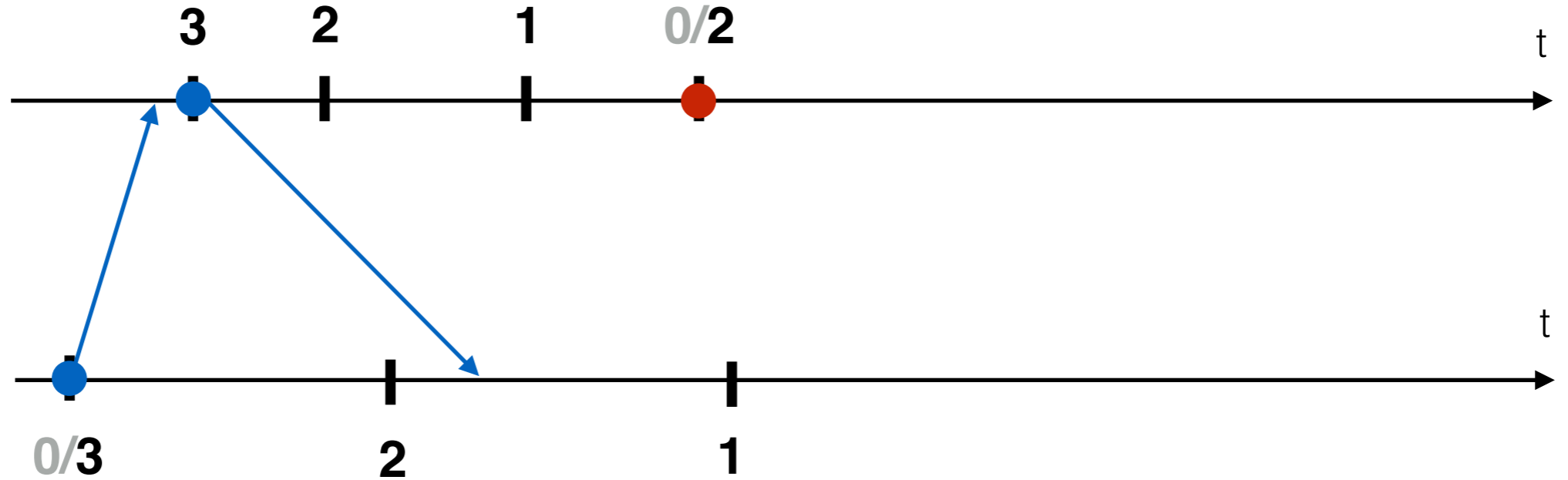
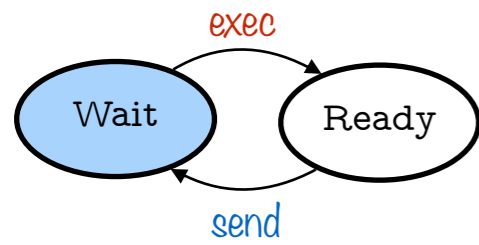
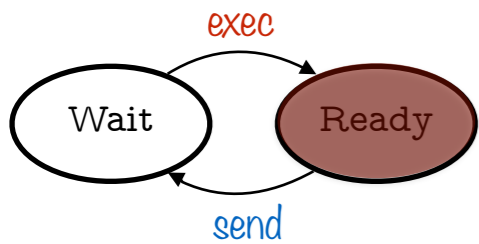
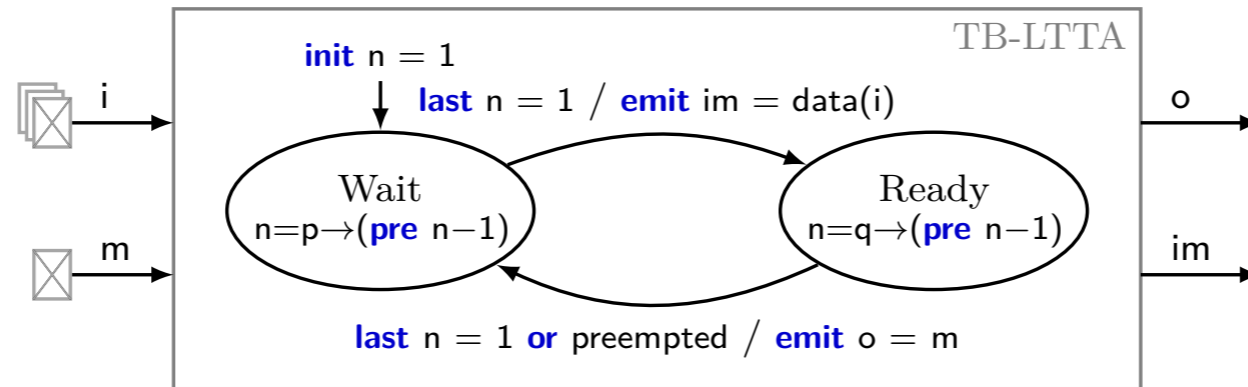
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

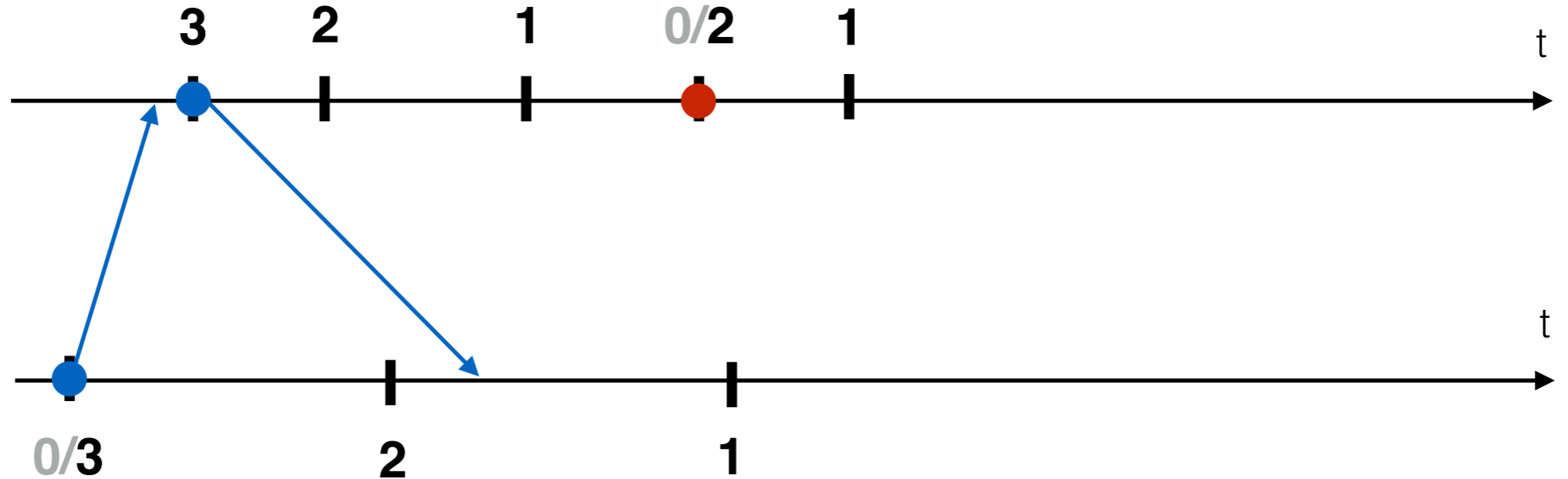
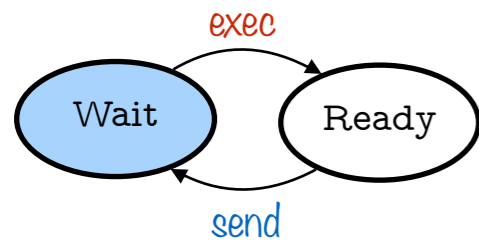
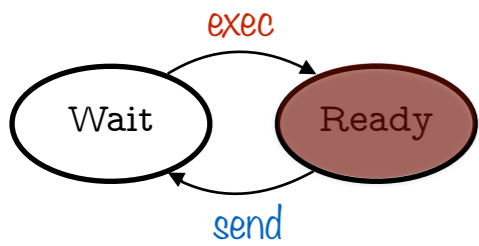
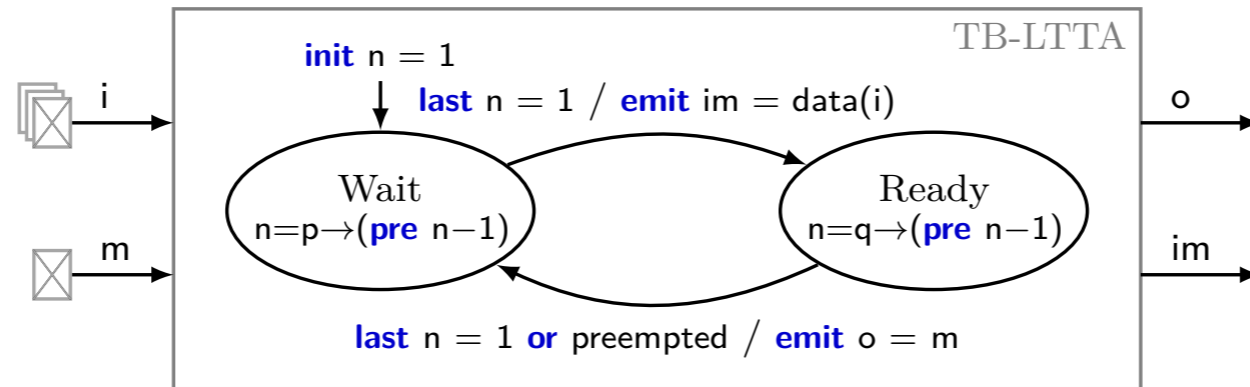
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

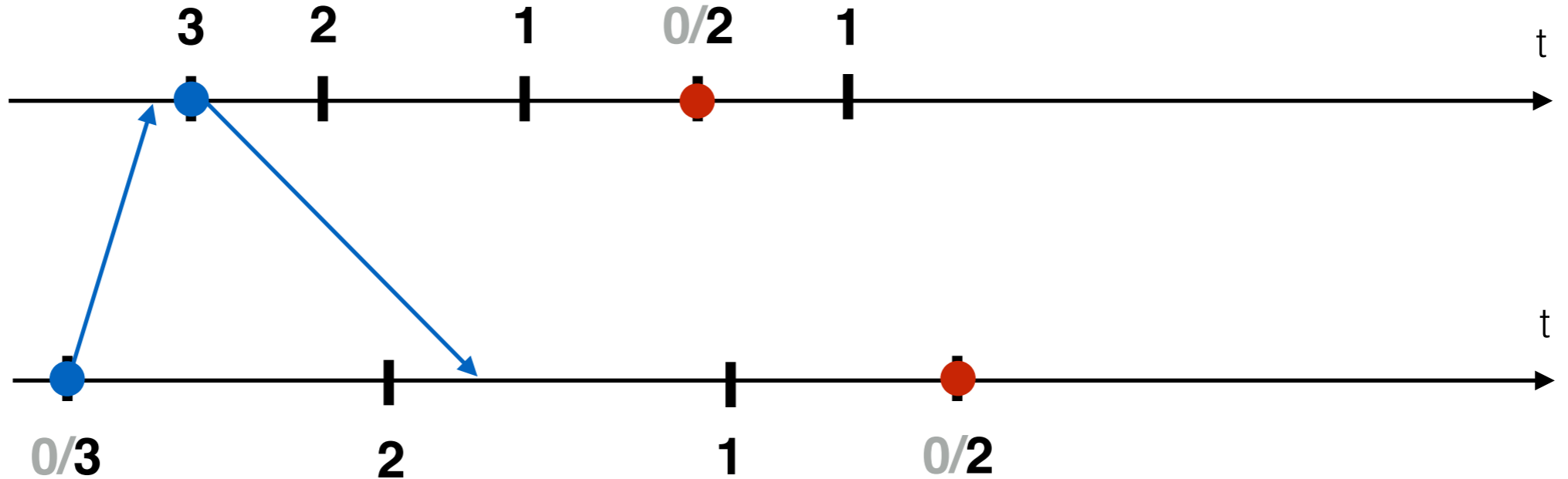
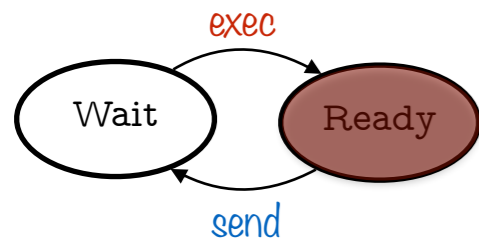
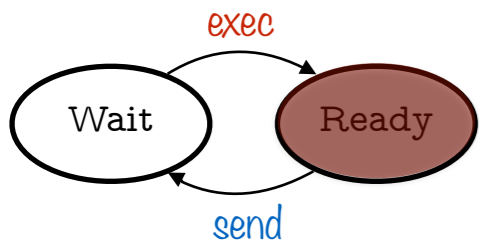
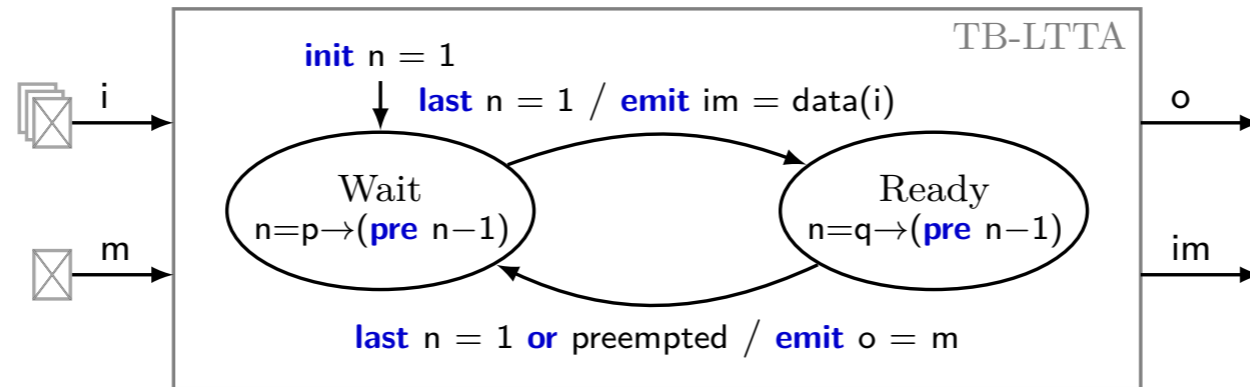
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

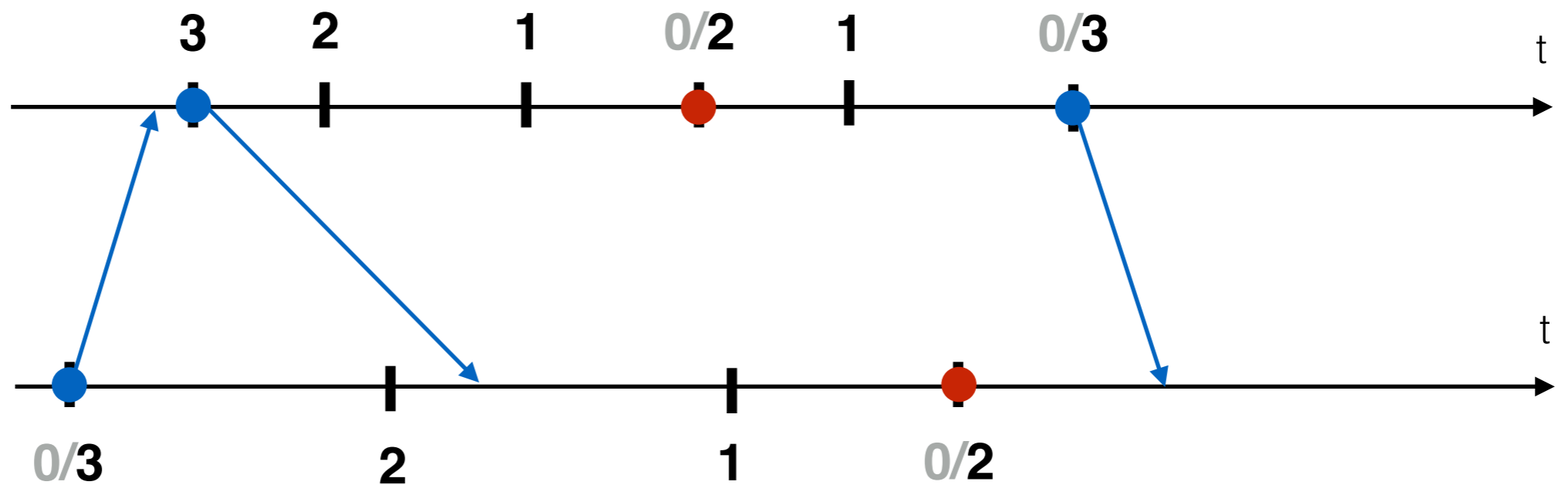
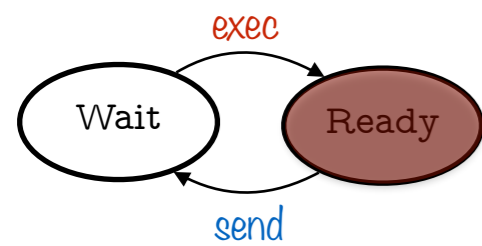
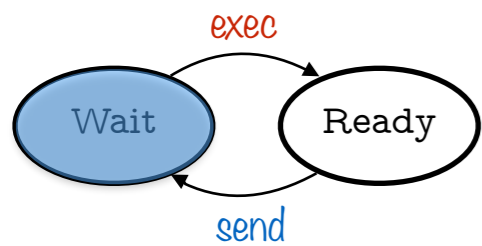
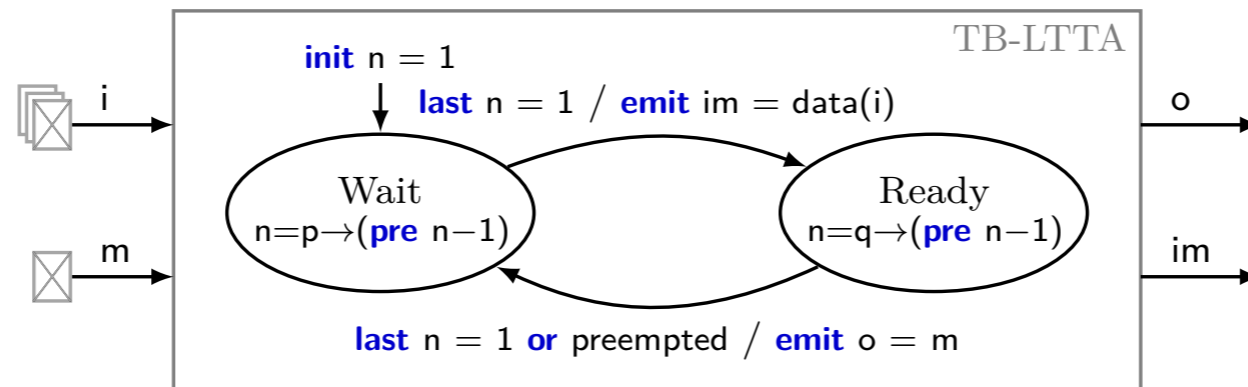
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

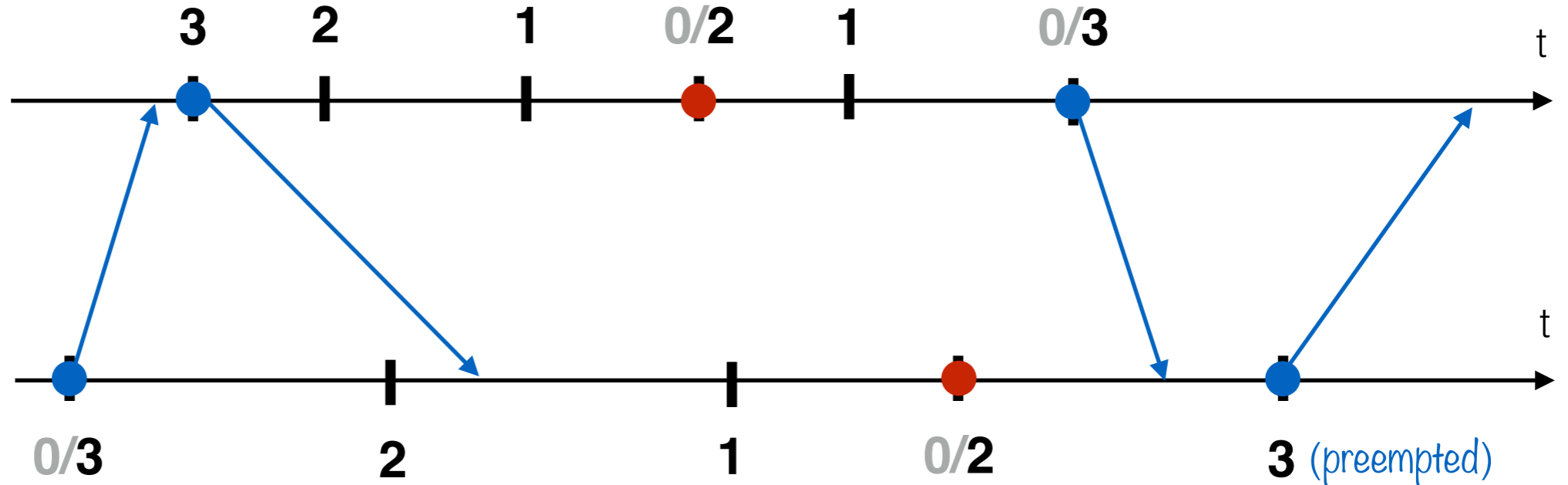
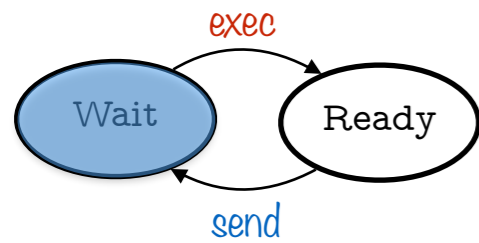
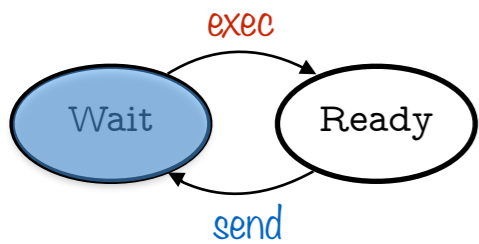
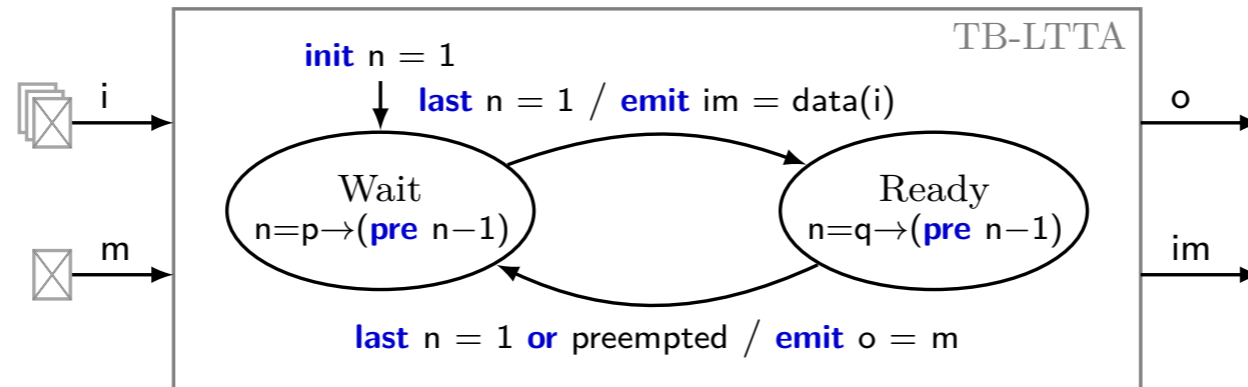
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

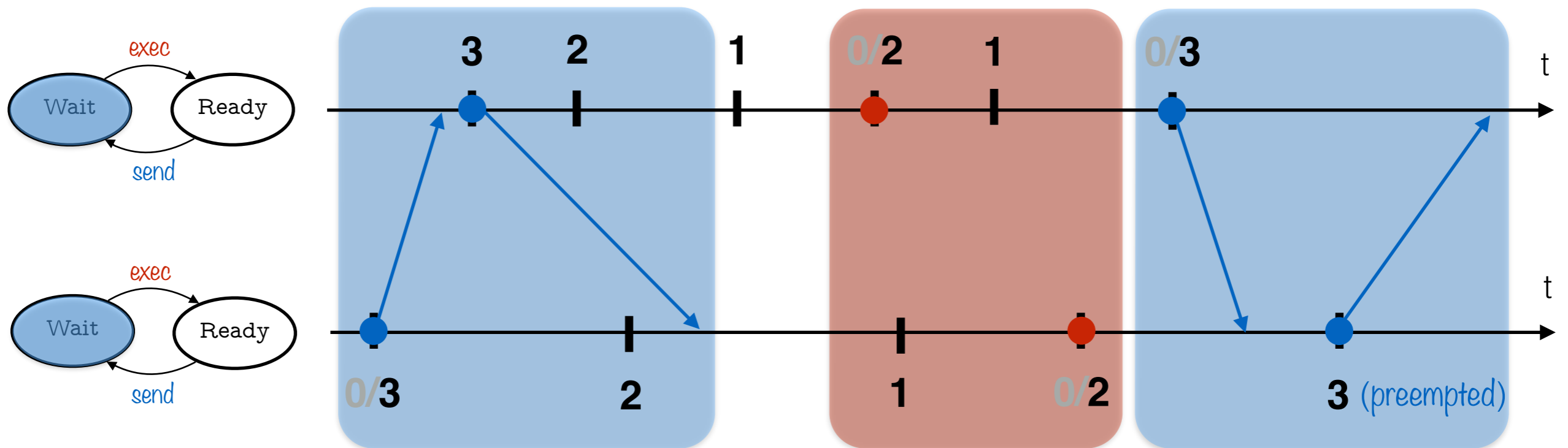
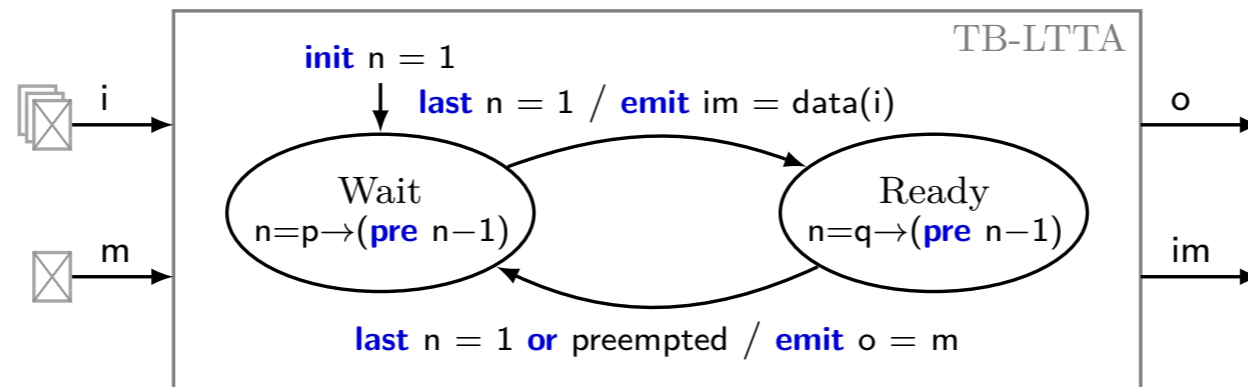
- Send
- Exec



Time-Based LTTA

Simulation $p=3$ $q=2$

● Send
● Exec



Nodes alternate between **send** and **exec** phases

Time-Based LTTA

Theorem 1:

The composition of the controller and the application is always well-defined (no causality cycle).

Theorem 2:

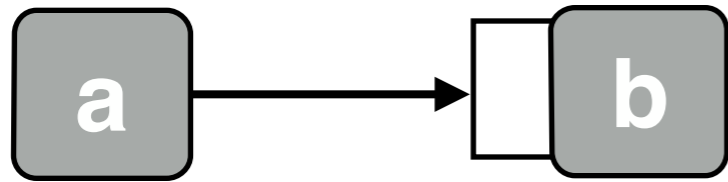
The following constraints on the initial counter values ensure the preservation of the semantics

$$p > \frac{2\tau_{max} + T_{max}}{T_{min}}$$
$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Theorem 3:

The worst case throughput is given by $1/\lambda_{TB} = (p + q)T_{max}$

Preservation of the Semantics

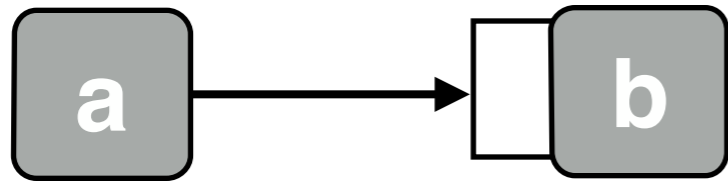


$$p > \frac{2\tau_{max} + T_{max}}{T_{min}}$$

$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$

Preservation of the Semantics



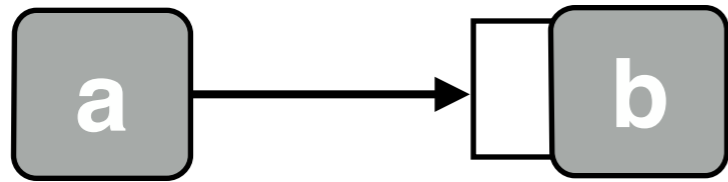
$$p > \frac{2\tau_{max} + T_{max}}{T_{min}}$$

$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$

$$S_{k-1}^b$$

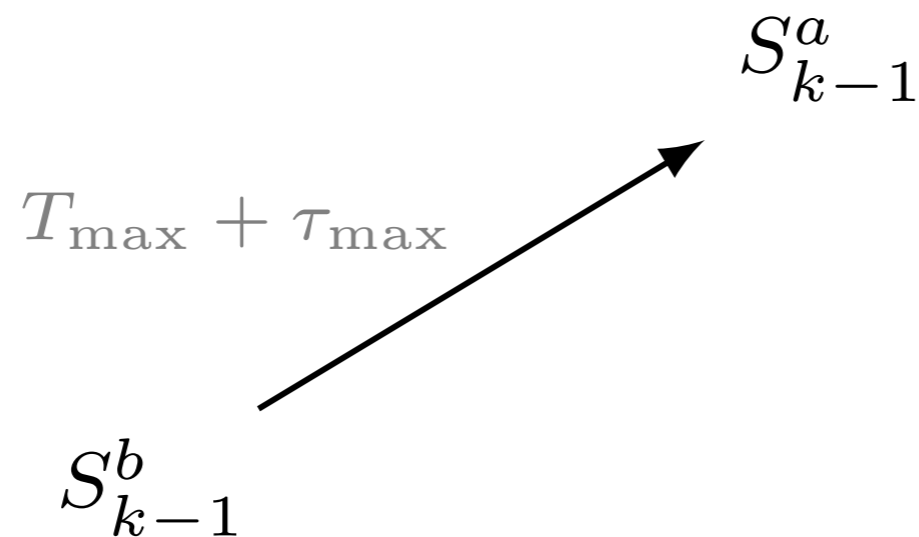
Preservation of the Semantics



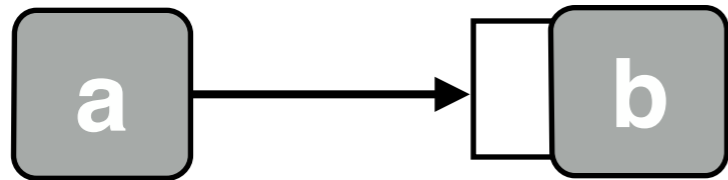
$$p > \frac{2\tau_{max} + T_{max}}{T_{min}}$$

$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$



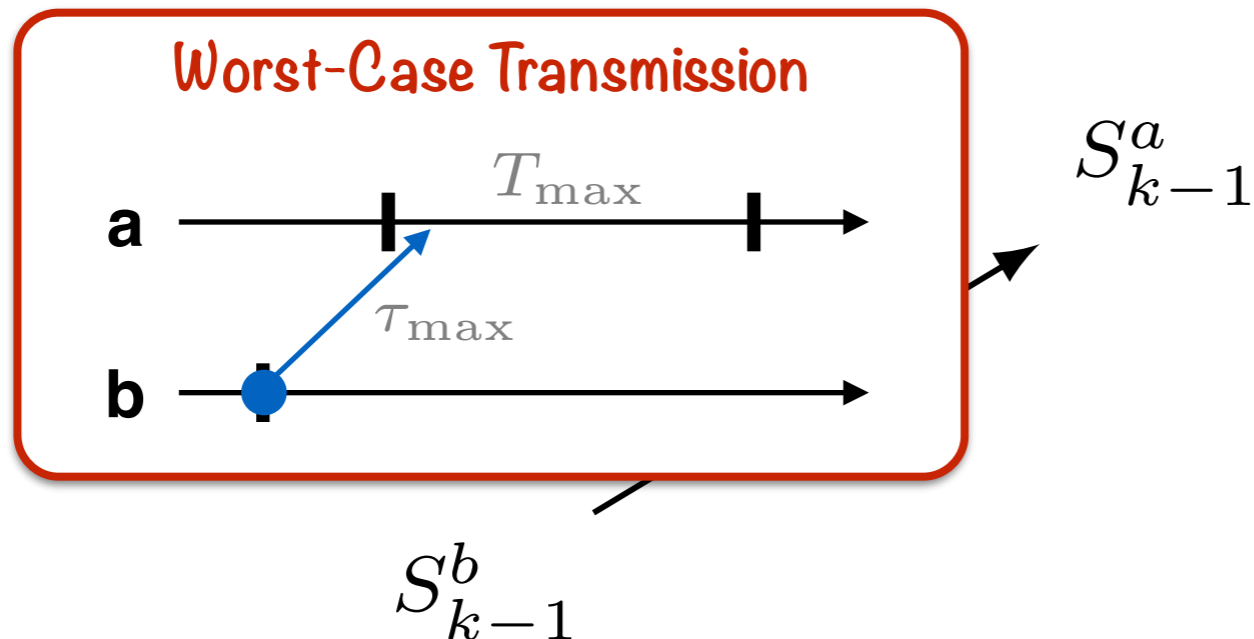
Preservation of the Semantics



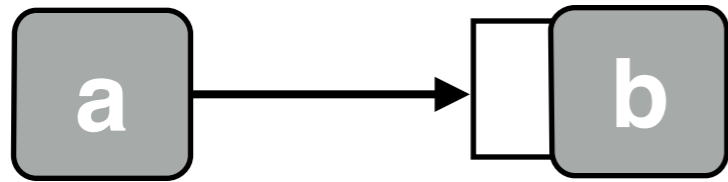
$$p > \frac{2\tau_{max} + T_{max}}{T_{min}}$$

$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$



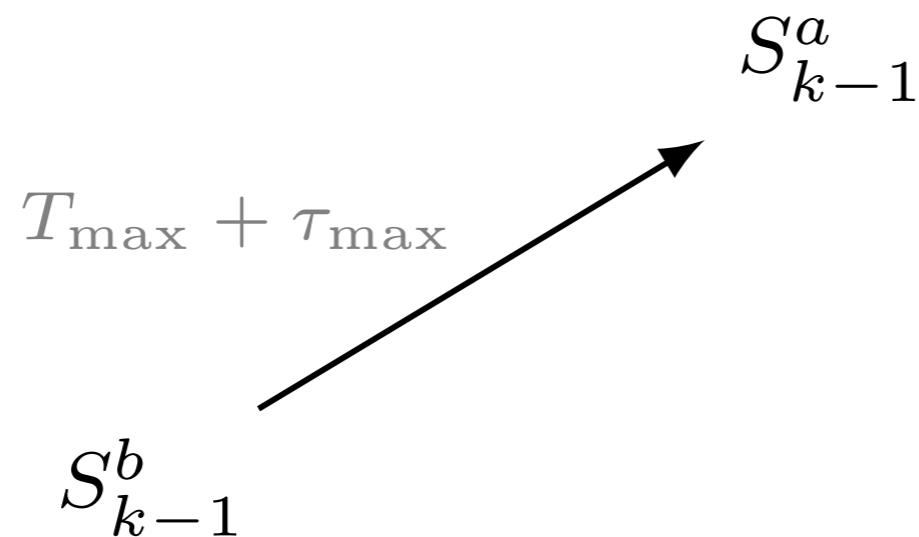
Preservation of the Semantics



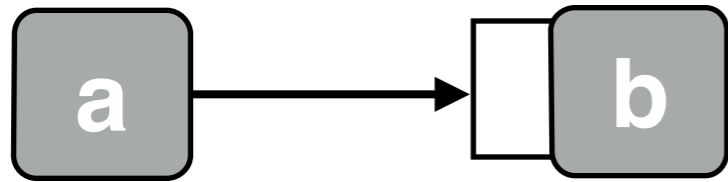
$$p > \frac{2\tau_{max} + T_{max}}{T_{min}}$$

$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$



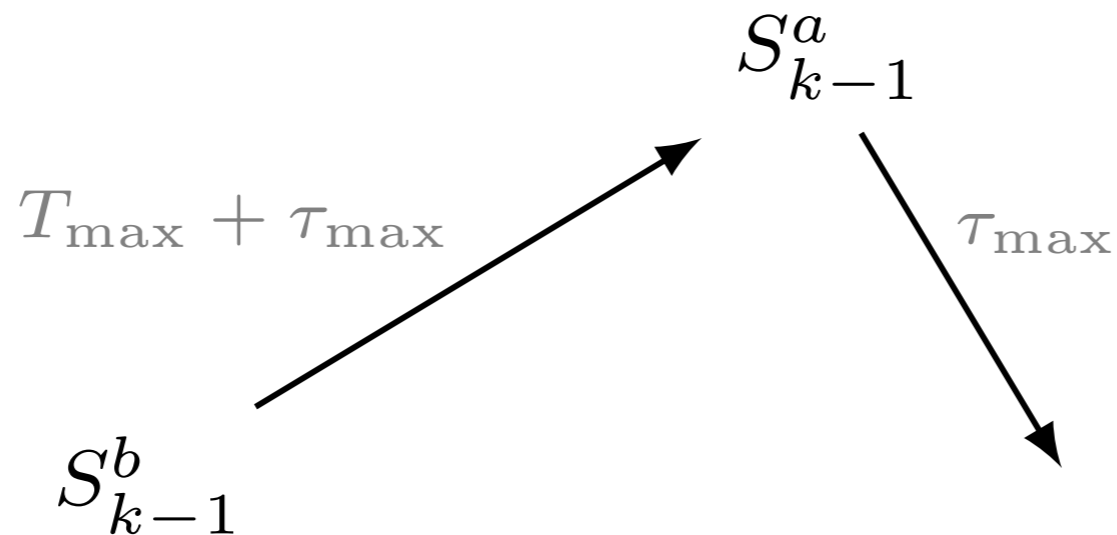
Preservation of the Semantics



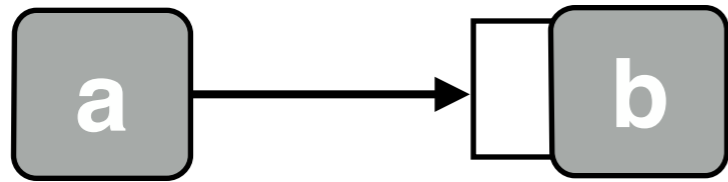
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Property 1: $S_{k-1}^a \prec E_k^b$



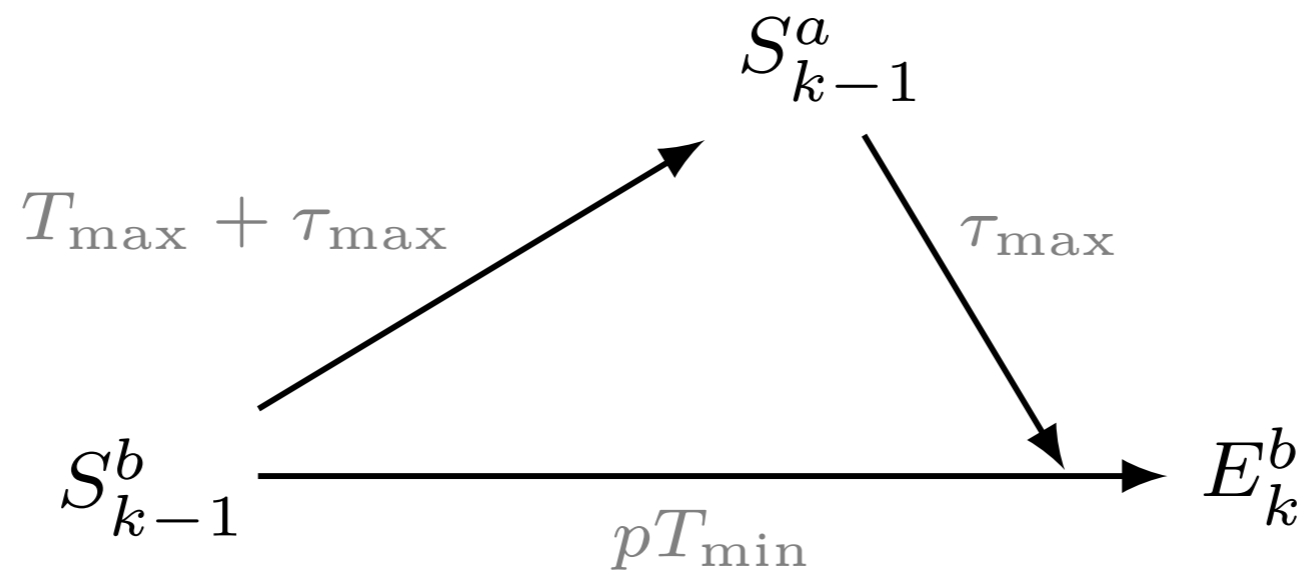
Preservation of the Semantics



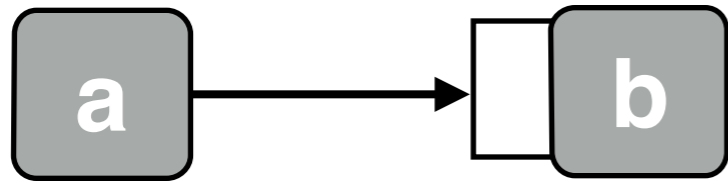
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$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$



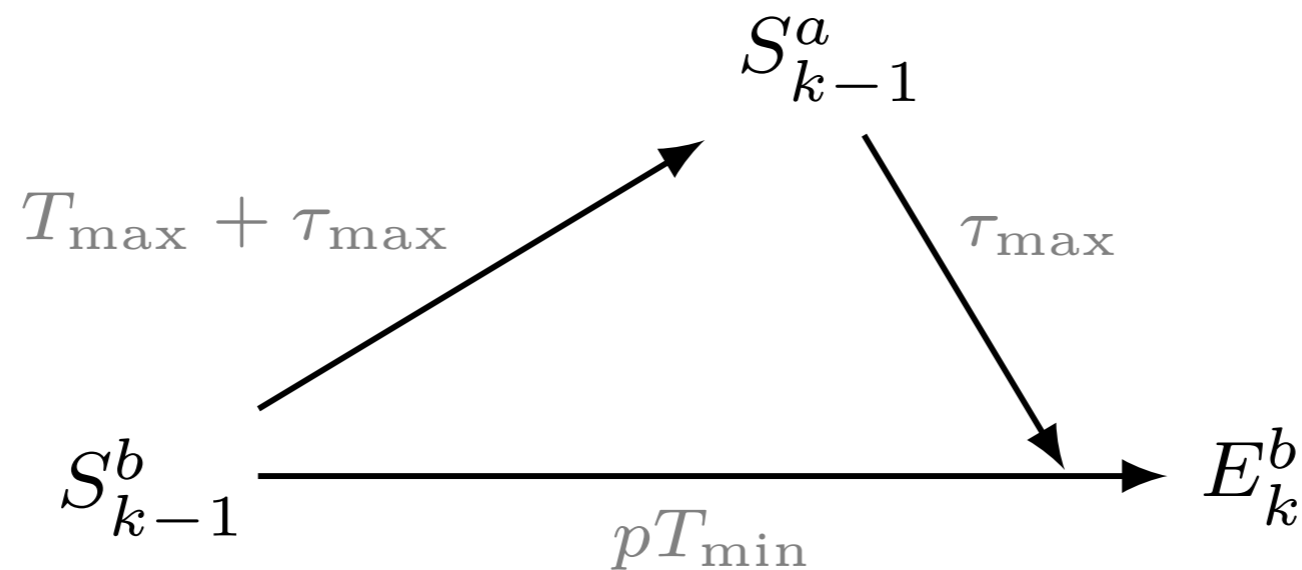
Preservation of the Semantics



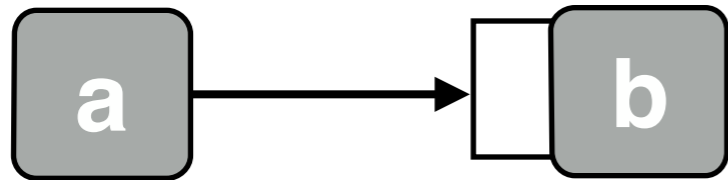
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$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$



Preservation of the Semantics



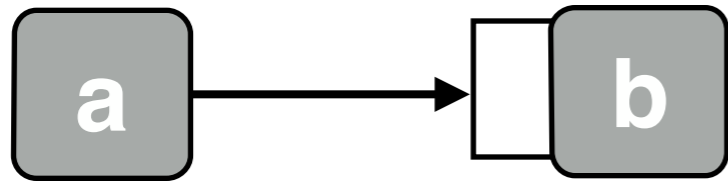
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$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$

Property 2: $E_k^b \prec S_k^a$

Preservation of the Semantics



$$p > \frac{2\tau_{max} + T_{max}}{T_{min}}$$

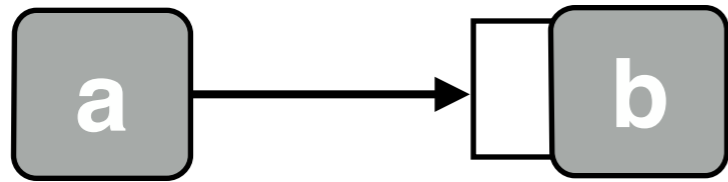
$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$

Property 2: $E_k^b \prec S_k^a$

S_{k-1}^a

Preservation of the Semantics

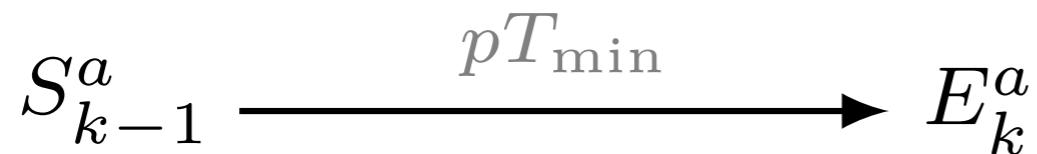


$$p > \frac{2\tau_{max} + T_{max}}{T_{min}}$$

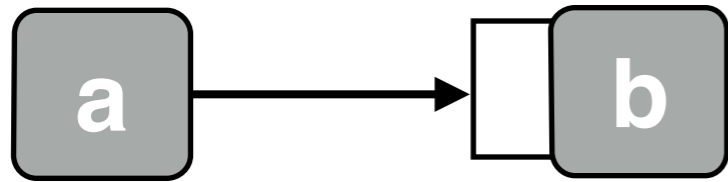
$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$

Property 2: $E_k^b \prec S_k^a$



Preservation of the Semantics



$$p > \frac{2\tau_{max} + T_{max}}{T_{min}}$$

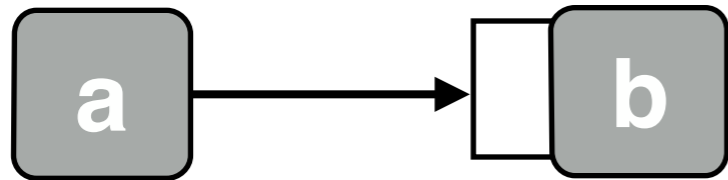
$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$

Property 2: $E_k^b \prec S_k^a$



Preservation of the Semantics

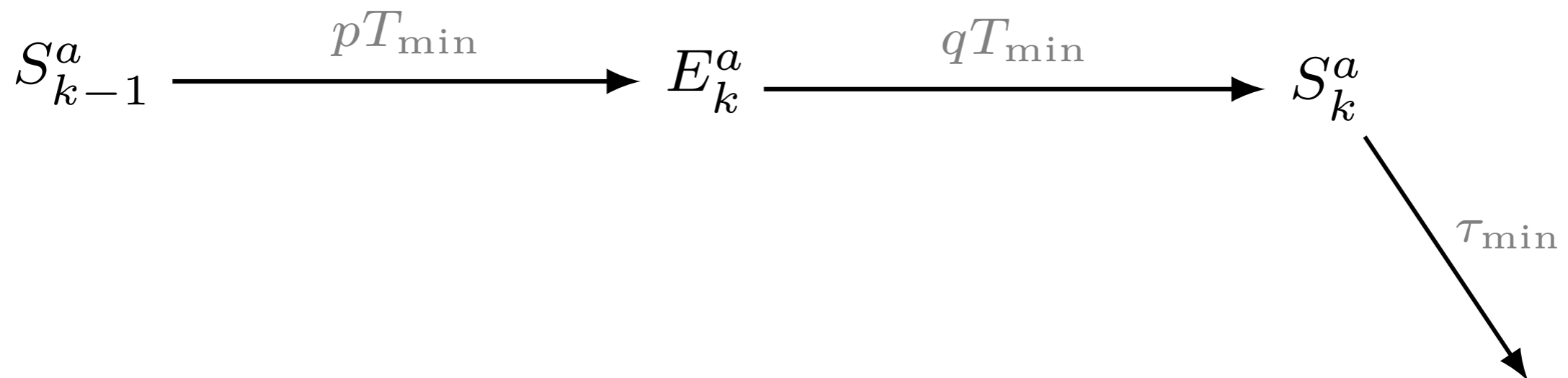


$$p > \frac{2\tau_{max} + T_{min}}{T_{min}}$$

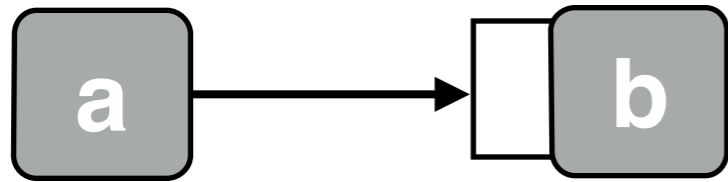
$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$

Property 2: $E_k^b \prec S_k^a$



Preservation of the Semantics

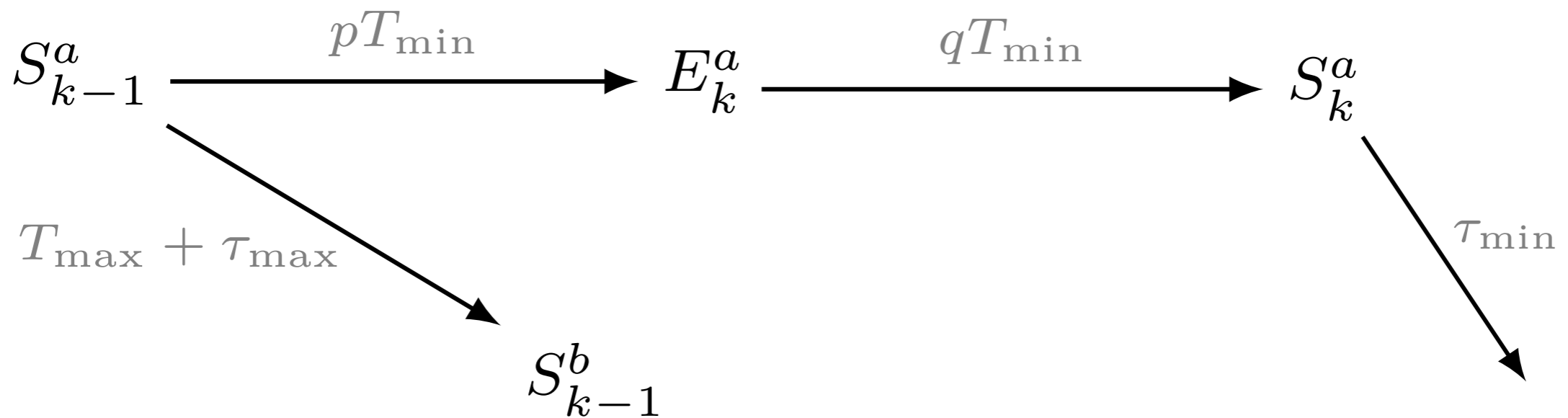


$$p > \frac{2\tau_{max} + T_{max}}{T_{min}}$$

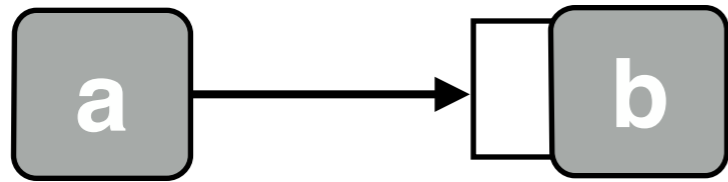
$$q > \frac{\tau_{max} - \tau_{min} + (p + 1)T_{max}}{T_{min}} - p$$

Property 1: $S_{k-1}^a \prec E_k^b$

Property 2: $E_k^b \prec S_k^a$



Preservation of the Semantics

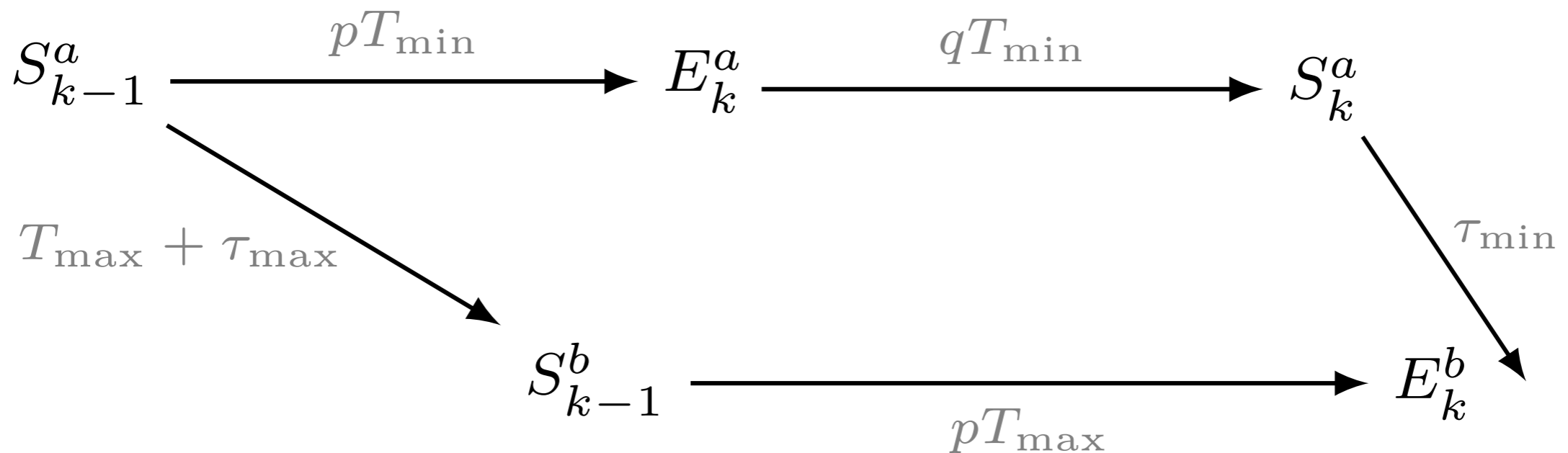


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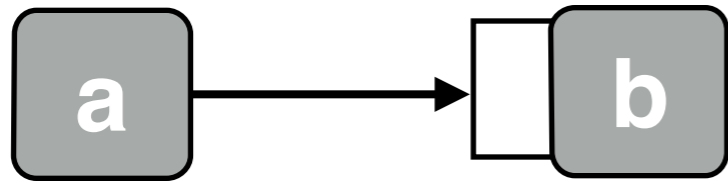
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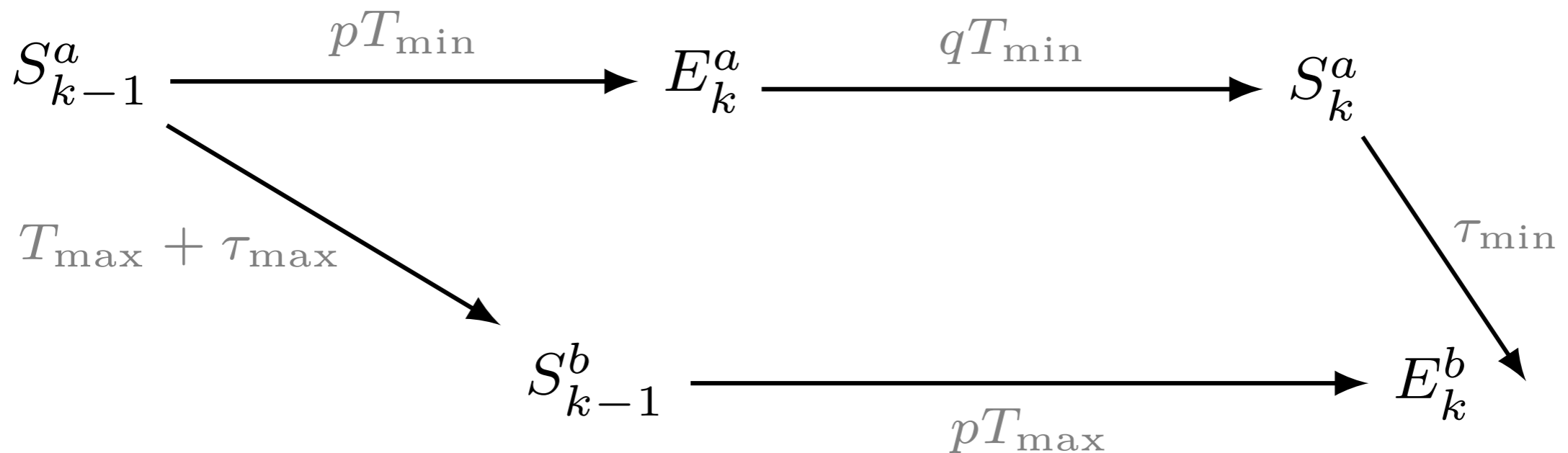


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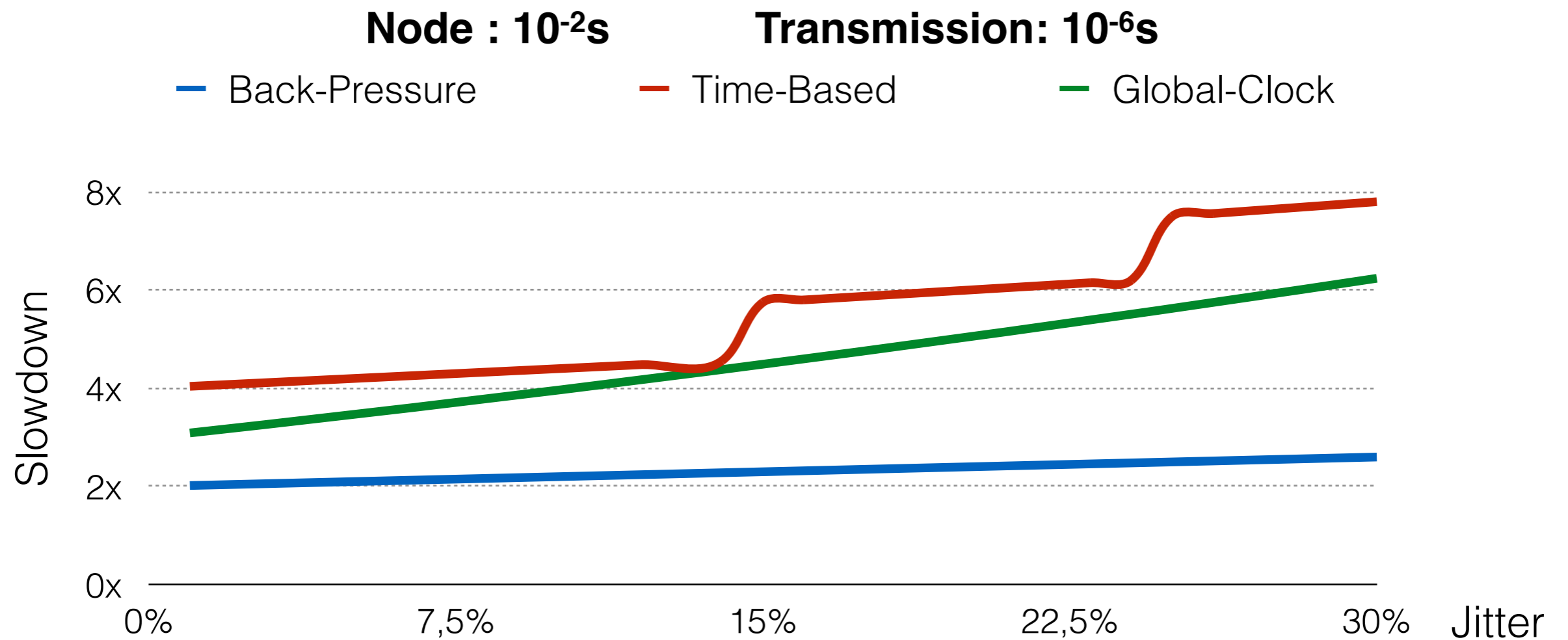
Property 2: $E_k^b \prec S_k^a$



**What about
Clock Synchronization?**

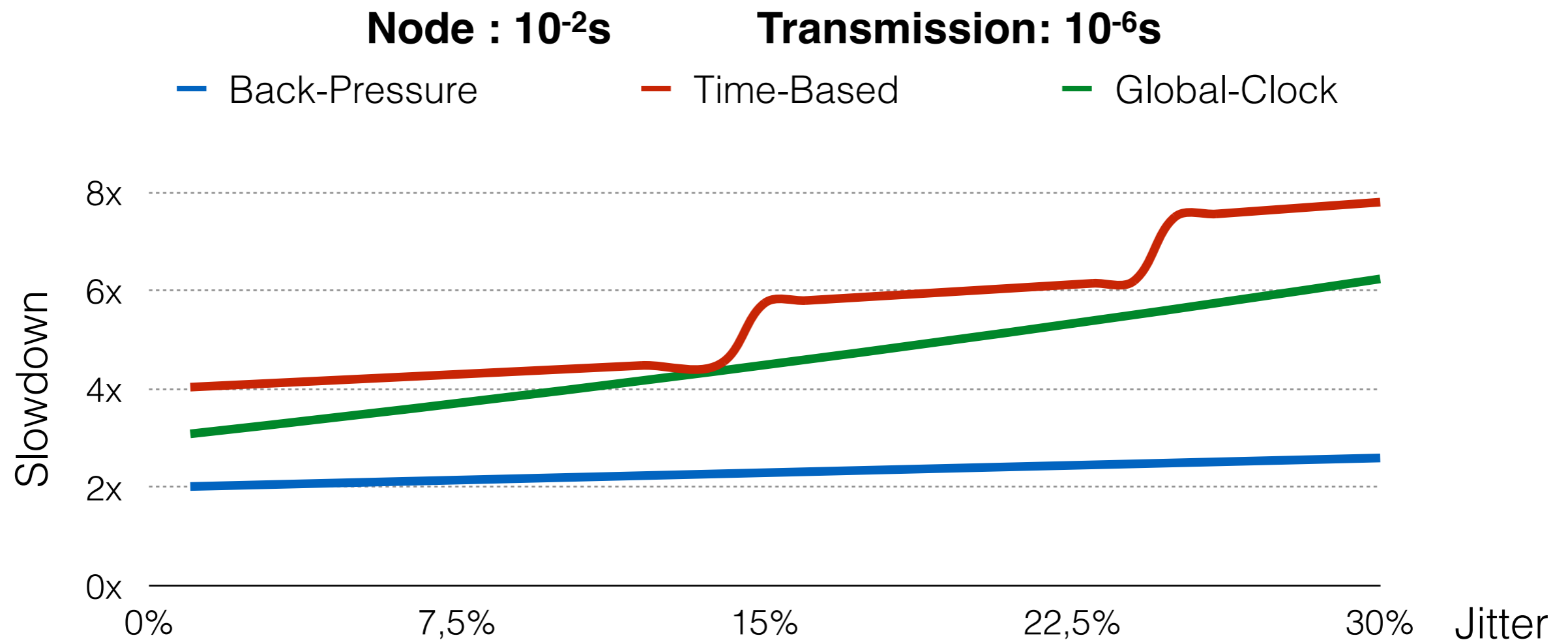
Worst-Case Evaluation

Analytical comparison with synchronous execution*



Worst-Case Evaluation

Analytical comparison with synchronous execution*

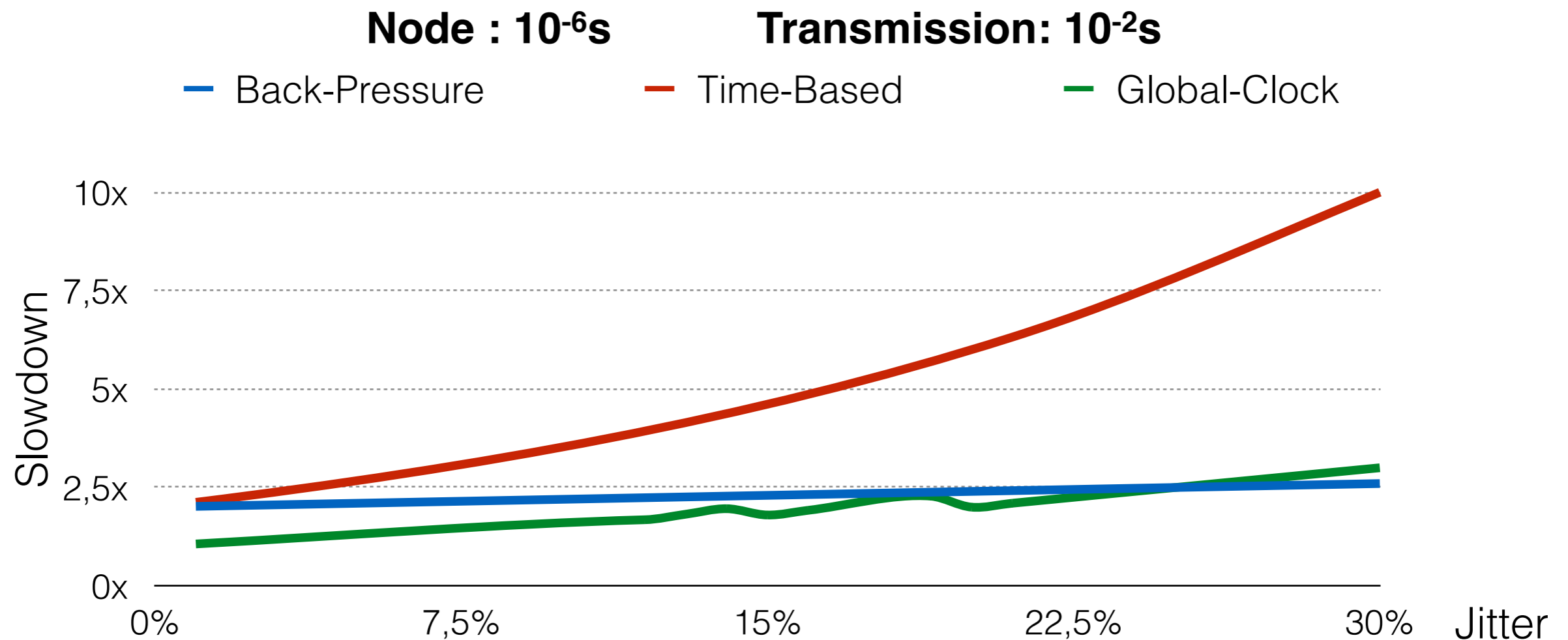


However:

- Global-Clock is as efficient as possible
- LTTA are **simpler** protocols (two control states)
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Contributions

- Clarification of the assumptions on the synchronous application
- A unifying synchronous framework for LTTAs that gives executable code for simulation
- Simplification of the Time-Based protocol
 - Relaxing broadcast communication
 - No more global synchronization
- Theoretical comparison with clock synchronization deployed on the same architecture

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Erratum